



**AP-275**

**APPLICATION  
NOTE**

# **An FFT Algorithm For MCS<sup>®</sup>-96 Products Including Supporting Routines and Examples**

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**AN FFT ALGORITHM FOR  
MCS<sup>®</sup>-96 PRODUCTS  
INCLUDING SUPPORTING  
ROUTINES AND  
EXAMPLES**

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## 1.0 INTRODUCTION

Intel's 8096 is a 16-bit microcontroller with processing power sufficient to perform many tasks which were previously done by microprocessors or special building block computers. A new field of applications is opened by having this much power available on a single chip controller.

The 8096 can be used to increase the performance of existing designs based on 8051s or similar 8-bit controllers. In addition, it can be used for Digital Signal Processing (DSP) applications, as well as matrix manipulations and other processing oriented tasks. One of the tasks that can be performed is the calculation of a Fast Fourier Transform (FFT). The algorithm used is similar to that in many DSP and matrix manipulation applications, so while it is directly applicable to a specific set of applications, it is indirectly applicable to many more.

FFTs are most often used in determining what frequencies are present in an analog signal. By providing a tool to identify specific waveforms by their frequency components, FFTs can be used to compare signals to one another or to set patterns. This type of procedure is used in speech detection and engine knock sensors. FFTs also have uses in vision systems where they identify objects by comparing their outlines, and in radar units to detect the dopler shift created by moving objects.

This application note discusses how FFTs can be calculated using Intel's MCS®-96 microcontrollers. A review of fourier analysis is presented, along with the specific code required for a 64 point real FFT. Throughout this application note, it is assumed that the reader has a working knowledge of the 8096. For those without this background the following two publications will be helpful:

1986 Microcontroller Handbook

Using the 8096, AP-248

These books are listed in the bibliography, along with other good sources of information on the MCS-96 product family and on Fast Fourier Transforms.

## 2.0 PROGRAM OVERVIEW

This application note contains program modules which are combined to create a program which performs an FFT on an analog signal sampled by the on-board ADC (Analog to Digital Converter) of the 8097. The results of the FFT are then provided over the serial

channel to a printer or terminal which displays the results. In the applications listed in the previous section, the data from this FFT program would be used directly by another program instead of being plotted. However, the plotted results are used here to provide an example of what the FFT does. There are four program modules discussed in this application note:

**FFTRUN** - Runs a 64 point FFT on its data buffer. It produces 32 14-bit complex output values and 32 14-bit output magnitudes. A fast square root routine and log conversion routine are included.

**A2DCON** - Fills one of two buffers with analog values at a set sample rate. The sample time can be as fast as 50 microseconds using 8x9xBH components.

**PLOTSP** - Plots the contents of a buffer to a serially connected printer. Routines are provided for console out and hexadecimal to decimal conversion and printing.

**FTMAIN** - The main module which controls the other modules.

Each of the modules will be described separately. In order to better understand how the programs work together, a brief tutorial on FFTs will be presented first, followed by descriptions of the programs in the order listed above.

The final program uses 64 real data points, taken from either a table or analog input 1. Each of the data points is a 16-bit signed number. The processing takes 12.5 milliseconds when internal RAM is used as the data space. If external RAM is used, 14 milliseconds are required. Larger FFTs can be performed by slightly modifying the programs. A 256-point FFT would take approximately 65 milliseconds, and a 1024-point version would require about 300 milliseconds.

In the program presented, the analog sampling time is set for 1 sample every 100 microseconds, providing the 64 samples in 6.4 milliseconds. The sampling time can be reduced to around 60 microseconds per point by changing a variable, and less than 50 microseconds by using the 8x9xBH series of parts, since they have a 22 microsecond A to D conversion time.

The programs are set up to be run in a sequence instead of concurrently. This provides the fastest operation if the sampling speed were reduced to the minimum possible. For the fastest operation above about 80 microseconds a sample, the programs could be run concurrently, but this would require some minor modifications of the program. Figure 1 shows the timing of the program as presented.

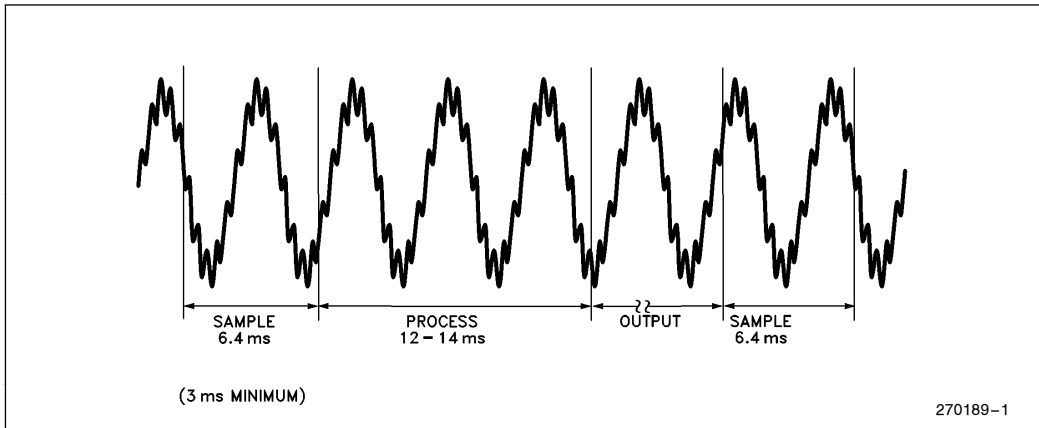


Figure 1. Timing of the FFT Program

These programs have run in the Intel Microcontroller Operation Application Lab and produced the results presented in this application note. Since the programs have not undergone any further testing, we cannot guarantee them to be bug proof. We, therefore, recommend that they be thoroughly tested before being used for other than demonstration purposes.

### 3.0 FOURIER TRANSFORMS

A Fourier Transform is a useful analytical tool that is frequently ignored due to its mathematically oriented derivations. This is unfortunate, since Fourier transforms can be used without fully understanding the mathematics behind them. Of course, if one understands the theory behind these transforms, they become much more powerful.

The majority of this application note deals with how a Fast Fourier Transform (FFT) can be used for spectrum analysis. This procedure takes an input signal and separates it into its frequency components. One can almost treat the FFT as a black box, which has as its output, the frequency components and magnitudes of the input signal, much like a spectrum analyzer.

From a mathematical standpoint, Fourier Transforms change information in the time domain into the frequency domain. The theory behind the Fourier transform stems from Fourier analysis, also called frequency analysis.

There are many books on the topic of Fourier analysis, several of which are listed in the bibliography. In this application note, only the pertinent formulas and uses will be presented, not their derivations.

The main idea in Fourier analysis is that a function can be expressed as a summation of sinusoidal functions of different frequencies, phase angles, and magnitudes. This idea is represented by the Fourier Integral:

$$H(f) = \int_{-\infty}^{\infty} h(t) e^{-j2\pi ft} dt \tag{1}$$

Where:  $H(f)$  is a function of frequency  
 $h(t)$  is a function of time

Since

$$e^{-j\theta} = \cos \theta - j \sin \theta \tag{2}$$

$$H(f) = \int_{-\infty}^{\infty} h(t) (\cos (2\pi ft) - j \sin (2\pi ft)) dt \tag{3}$$

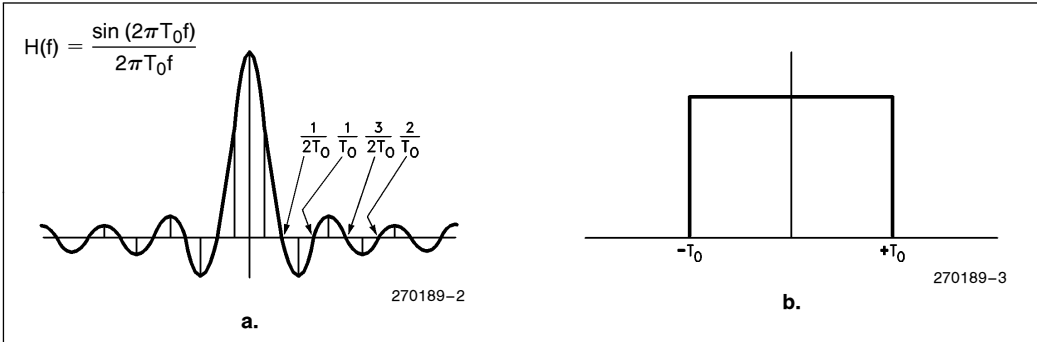
Figure 2 shows a rectangular pulse and its Fourier transform. Note that the results in the frequency domain are continuous rather than discrete. The horizontal axis in Figure 2a is frequency, while that of Figure 2b is time.

In a simplified case, the varying phase angles can be removed, and the integral changed to a summation, known as a Fourier Series. All periodic functions can be described in this way. This series, as shown below, can help provide a more graphical understanding of Fourier analysis.

$$y(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [a_n \cos (2\pi n f_0 t) + b_n \sin (2\pi n f_0 t)] \tag{4}$$

for  $n = 1$  to  $\infty$

Where  $f_0 = \frac{1}{T_0}$ , the fundamental frequency.



**Figure 2. Rectangular Pulse and Its Fourier Transform**

This formula can also be represented in complex form as:

$$\sum_{n=-\infty}^{\infty} \alpha_n e^{j2\pi n f_0 t} \tag{5}$$

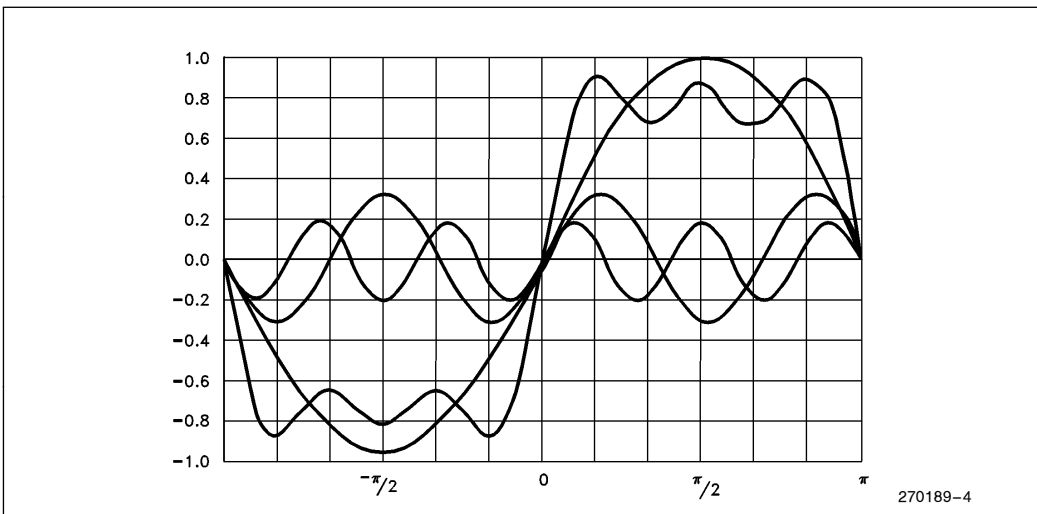
The Fourier series for a square wave is

$$\sum_{k=0}^{\infty} \frac{\sin((2k+1)2\pi f_0 t)}{(2k+1)} \tag{6}$$

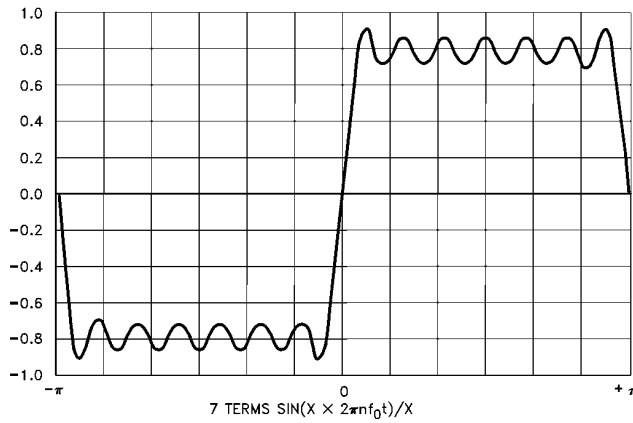
If these sinusoids are summed, a square wave will be formed. Figure 3 shows the graphical summation of the first 3 terms of the series. Since the higher frequencies contribute to the squareness of the waveform at the corners, it is reasonable to compare only the flatness of the top of the waveform. The sharpness or risetime of the waveform can be determined by the highest fre-

quency term being summed. With rise and fall times of 10% of the period, the waveform generated by the first 3 terms is within 20% of ideal. At 7 terms it is within 10%, and at 20 terms it is within 5%. With a 5% risetime, it is within 20% of ideal after 5 terms, 10% after 13 terms and 5% after 32 terms. Figure 4 shows the resultant waveforms after the summation of 7, 15 and 30 terms.

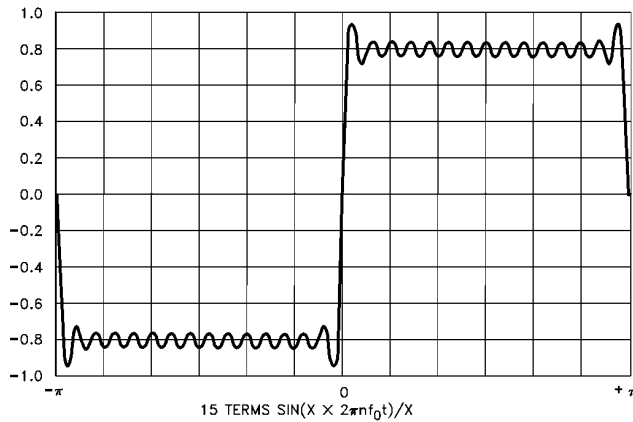
Fourier analysis can be used on equation 4 to find the coefficients  $a_n$  and  $b_n$ . To make this process easier to use with a computer, a discrete form, rather than a continuous one, must be used. The discrete Fourier transform, shown in Equation 7, is a good approximation to the continuous version. The closeness of the approximation depends on several conditions which will be discussed later. The input to this transform is a set of N equally spaced samples of a waveform taken over a period of NT. The period NT is frequently referred to as the "Sampling Window".



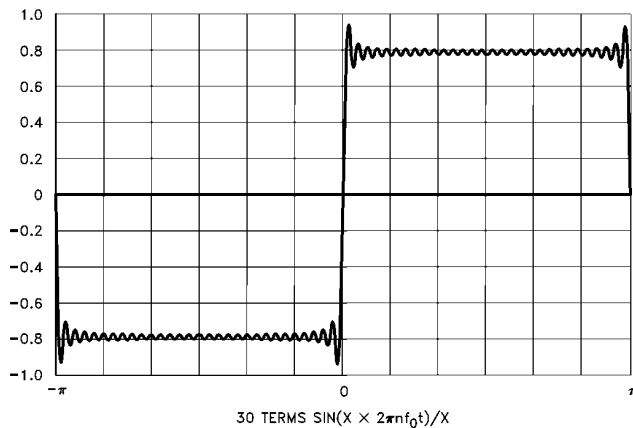
**Figure 3. Graphical Summation of Sinewaves**



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**Figure 4. Square Wave from Sinusoids**



$$H\left(\frac{n}{NT}\right) = \sum_{k=0}^{N-1} h(kT)e^{-j2\pi nk/N}$$

$$n = 0, 1, \dots, N-1 \tag{7}$$

Where: H(f) is a function of frequency  
 h(t) is a function of time  
 T is the time span between samples  
 N is the number of samples in the window  
 n = 0,1,2 ... N-1

This transform is used for many applications, including Fourier Harmonic Analysis. This procedure uses the transform to calculate the coefficients used in Equation 5. In order to do this, the factor T/NT must be added to the transform as follows:

$$H\left(\frac{n}{NT}\right) = \frac{T}{(NT)} \sum_{k=0}^{N-1} h(kT) e^{-j2\pi nk/N}$$

$$n = 0, 1, 2, 3, \dots, N-1 \tag{8}$$

The factor provides compensation for the number of samples taken. Note that the functions H(f) and h(t) are complex variables, so the simplicity of the equation can be misleading. Once the values of h(t) are known, (ie.

the value of the input at the discrete times (t)), the Fourier Transform can be used to find the magnitude and phase shift of the signal at the frequencies (f).

A spectrum analyzer can provide similar information on an analog input signal by using analog filters to separate the frequency components. Regardless of its source, the information on component frequencies of a signal can be used to detect specific frequencies present in a signal or to compare one signal to another. Many lab experiments and product development tests can make use of this type of information. Using these methods, the purity of signals can be measured, specific harmonics can be detected in mechanical equipment, and noise bursts can be classified. All of this information can be obtained while still treating the FFT process as a black box.

Consider the discrete transform of a square wave as shown in Figure 5. Note that the component magnitudes, as shown in the series of Equation 6, are shown in a mirrored form in the transform. This will happen whenever only real data is used as the FFT input, if both real and imaginary data were used the output would not be guaranteed to be symmetrical. For this reason, there is duplicate information in the transform for many applications. Later in this section a method to make the most of this characteristic is discussed.

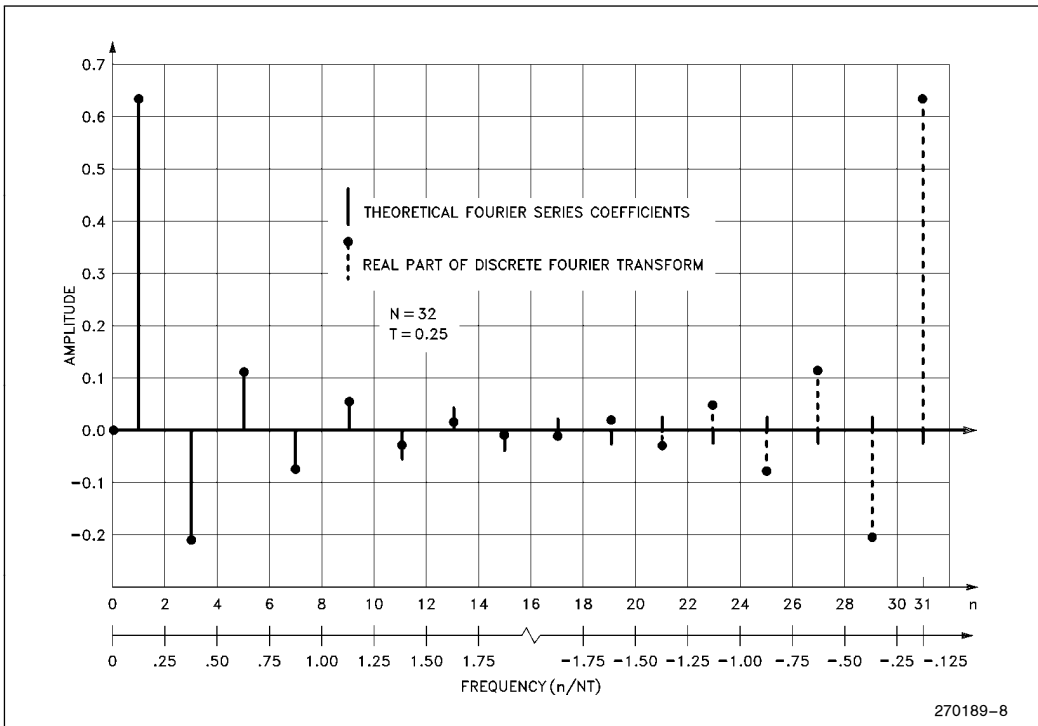


Figure 5. Discrete Transform of a Square Wave



If one looks at Equation 8, it can be seen that the calculation of a discrete Fourier transform requires  $N$  squared complex multiplications. If  $N$  is large, the calculation time can easily become unrealistic for real-time applications. For example, if a complex multiplication takes 40 microseconds, at  $N = 16$ , 10 milliseconds would be used for calculation, while at  $N = 128$ , over half a second would be needed. A Fast Fourier Transform is an algorithm which uses less multiplications, and is therefore faster. To calculate the actual time savings, it is first necessary to understand how a FFT works.

### 4.0 THE FFT ALGORITHM

The FFT algorithm makes use of the periodic nature of waveforms and some matrix algebra tricks to reduce the number of calculations needed for a transform. A more complete discussion of this is in Appendix A, however, the areas that need to be understood to follow the algorithm are presented here. This information need not be read if the reader's intent is to use the program and not to understand the mathematical process of the algorithm

To simplify notation the following substitutions are made in Equation 8.

$$W = e^{-j2\pi/N}$$

$$k = kT$$

$$n = \frac{n}{NT}$$

The resultant equation being

$$x(n) = \sum_{k=0}^{N-1} n(k)W^{nk} \tag{9}$$

Expressed as a matrix operation

$$\begin{bmatrix} X(1) \\ X(2) \\ X(3) \\ \vdots \\ X(N-1) \end{bmatrix} = \begin{bmatrix} W^0 & W^0 & W^0 & \dots & W^0 \\ W^0 & W^1 & W^2 & \dots & W^N \\ W^0 & W^2 & W^4 & \dots & W^{2N} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ W^0 & W^{(N-1)} & W^{2(N-1)} & \dots & W^{(N-1)^2} \end{bmatrix} \begin{bmatrix} X_0(0) \\ X_0(1) \\ X_0(2) \\ \vdots \\ X_0(N-1) \end{bmatrix}$$

A brief review of matrix properties can be found in Appendix A. Because of the periodic nature of  $W$  the following is true:

$$\begin{aligned} W^{nk \text{ MOD } N} &= W^{nk} \tag{10} \\ &= \text{COS}(2\pi nk/N) - j \text{SIN}(2\pi nk/N) \end{aligned}$$

$$W^0 = 1 \text{ therefore, if } nk \text{ MOD } N = 0, W^{nk} = 1$$

This reduces the calculations as several of the  $W$  terms go to 1 and the highest power of  $W$  is  $N$ . All of  $W$  values are complex, so most of the operations will have to be complex operations. We will continue to use only the  $W$ ,  $X(n)$  and  $X_0(k)$  symbols to represent these complex quantities.

The FFT algorithm we will use requires that  $N$  be an integral power of 2. Other FFT algorithms do not have this restriction, but they are more complex to understand and develop. Additionally, for the relatively small values of  $N$  we are using this restriction should not provide much of a problem. We will define EXPONENT as log base 2 of  $N$ . Therefore,

$$N = 2^{\text{EXPONENT}}$$

The magic of the FFT, (as detailed in Appendix A), involves factoring the matrix into EXPONENT matrices, each of which has all zeros except for a 1 and a  $W^{nk}$  term in each row. When these matrices are multiplied together the result is the same as that of the multiplication indicated in Equation 9, except that the rows are interchanged and there are fewer non-trivial multiplications. To reorder the rows, and thus make the information useful, it is necessary to perform a procedure called "Bit Reversal".

This process requires that  $N$  first be converted to a binary number. The least significant bit (lsb) is swapped with the most significant bit (msb). Then the next lsb is swapped with the next msb, and so on until all bits have been swapped once. For  $N = 8$ , 3 bits are used, and the values for  $N$  and their bit reversals are shown below:

Number	Binary	Bit Reversal	Decimal BR
0	000	000	0
1	001	100	4
2	010	010	2
3	011	110	6
4	100	001	1
5	101	101	5
6	110	011	3
7	111	111	7

Recall that the FFT of real data provides a mirrored image output, but the FFT algorithm can accept inputs with both real and imaginary components. Since the inputs for harmonic analysis provided by a single  $A$  to  $D$  are real, the FFT algorithm is doing a lot of calculations with one input term equal to zero. This is obviously not very efficient. More information for a given size transform can be obtained by using a few more tricks.

It is possible to perform the FFT of two real functions at the same time by using the imaginary input values to the FFT for the second real function. There is then a post processing performed on the FFT results which separate the FFTs of the two functions. Using a similar procedure one can perform a transform on 2N real samples using an N complex sample transform.

The procedure involves alternating the real sample values between the real and imaginary inputs to the FFT. If, as in our example, the input to the FFT is a 2 by 32 array containing the complex values for 32 inputs, the 64 real samples would be loaded into it as follows:

N	00 01 02 03 04 05 06 07 ..... 30 31
REAL	00 02 04 06 08 10 12 14 ..... 60 62
IMAGINARY	01 03 05 07 09 11 13 15 ..... 61 63

This procedure is referred to as a pre-weave. In order to derive the desired results, the FFT is run, and then a post-weave operation is performed. The formula for the post-weave is shown below:

$$\begin{aligned}
 X_r(n) &= \left[ \frac{R(n)}{2} + \frac{R(N-n)}{2} \right] + \cos \frac{\pi n}{N} \left[ \frac{I(N)}{2} + \frac{I(N-n)}{2} \right] - \\
 &\quad \sin \frac{\pi n}{N} \left[ \frac{R(n)}{2} - \frac{R(N-n)}{2} \right] \quad n = 0, 1, \dots, N-1 \\
 X_i(n) &= \left[ \frac{I(n)}{2} - \frac{I(N-n)}{2} \right] - \sin \frac{\pi n}{N} \left[ \frac{I(n)}{2} + \frac{I(N-n)}{2} \right] - \\
 &\quad \cos \frac{\pi n}{N} \left[ \frac{R(n)}{2} - \frac{R(N-n)}{2} \right] \quad n = 0, 1, \dots, N-1 \quad (11)
 \end{aligned}$$

Where R(n) is the real FFT output value

I(n) is the imaginary FFT output value

Xr(n) is the real post-weave output

Xi(n) is the imaginary post-weave output

Note that the output is now one-sided instead of mirrored around the center frequency as it is in Figure 5. The magnitude of the signal at each frequency is calculated by taking the square root of the sum of the squares. The magnitude can now be plotted against frequency, where the frequency steps are defined as:

$$\frac{n}{NT} \quad n = 0, 1, 2, 3, \dots, N-1$$

Where N is the number of complex samples (ie. 32 in this case) T is the time between samples

A value of zero on the frequency scale corresponds to the DC component of the waveform. Most signal analysis is done using Decibels (dB), the conversion is dB = 10 LOG (Magnitude squared). Decibels are not used as an absolute measure, instead signals are compared by the difference in decibels. If the ratio between two signals is 1:2 then there will be a 3 dB difference in their power.

### 5.0 USING THE FFT

There are several things to be aware of when using FFTs, but with the proper cautions, the FFT output can be used just like that of a spectrum analyzer. The

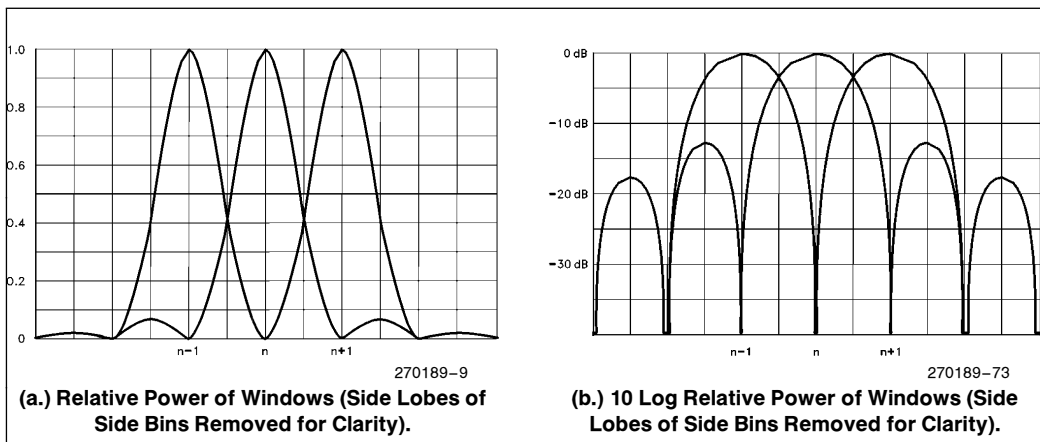


Figure 6. Bin Windows

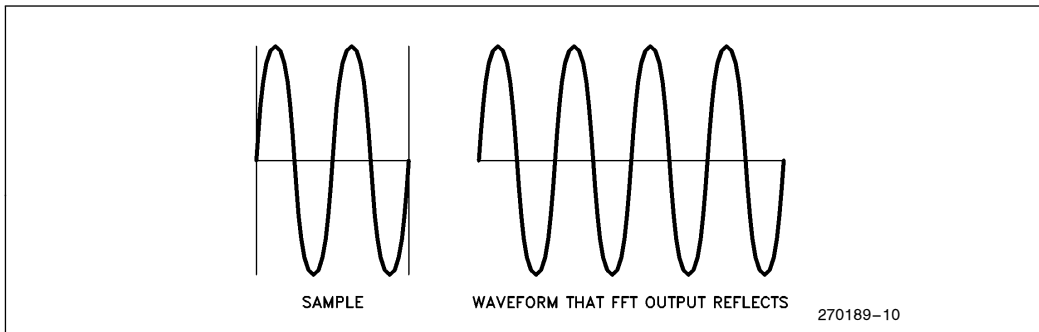
first precaution is that the FFT is a discrete approximation to a continuous Fourier Transform, so the output will seldom fit the theoretical values exactly, but it will be very close.

Since the programs in this application note generate a one-sided transform with  $N=32$ , the frequency granularity is fairly coarse. Each of the frequency components output from the FFT is actually the sum of all energy within a narrow band centered on that frequency. This band of sensitivity is referred to as a "bin". The reported magnitude is the actual magnitude multiplied by the value of the bin window at the actual frequency. Figure 6 shows several bin windows. Note that these windows overlap, so that a frequency midway between the two center frequencies will be reported as energy split between both windows. Be careful not to

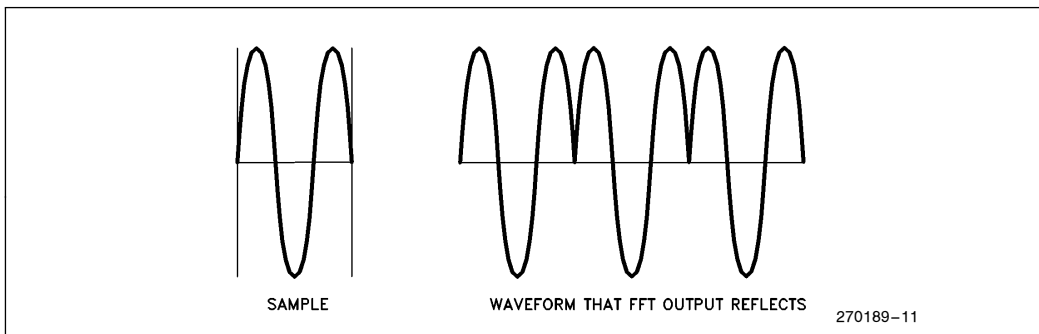
confuse the *sampling window* NT with *bin windows* or with the *windowing function*.

Another area of caution is the relationship of the sampling window to the frequency of the waveform. For the best accuracy, the window should cover an exact multiple of the period of the waveform being analyzed. If it covers less than one period, the results will be invalid. Other variations from ideal will not produce invalid results, just additional noise in the output.

If the sampling window does not cover an exact multiple of all of the frequency components of a waveform, the FFT results will be noisy. The reason for this is the sharp edge that the FFT sees when the edges of the window cut off the input waveform. Figure 7 shows a waveform that is an exact multiple of the window and



**Figure 7. Waveform is a Multiple of the Window**



**Figure 8. Waveform is Not a Multiple of the Window**

the periodic waveform that the FFT output reflects. In Figure 8, the waveform is not a multiple of the window and the waveform that the FFT output reflects has discontinuities. These discontinuities contribute to the noise in an FFT output. This noise is called “spectral leakage”, or simply “leakage”, since it is leakage between one frequency spectrum and another which is caused by digitization of an analog process.

To reduce this leakage, a process called windowing is used. In this procedure the input data is multiplied by specific values before being used in the FFT. The term “windowing” is used because these values act as a window through which the input data passes. If the input window goes smoothly to zero at both endpoints of

the sampling window, there can be no discontinuities. Figure 9 shows a Hanning window and its effect on the input to an FFT. The Hanning window was named after its creator, Julius Von Hann, and is one of the most commonly used windows. More information on windowing and the types of windows can be found in the paper by Harris listed in the bibliography. As expected, the results of the FFT are changed because of the input windowing, but it is in a very predictable way.

Using the Hanning window results in bin windows which are wider and lower in magnitude than normal, as can be seen by comparing Figure 6 with Figure 10. For an input frequency which is equal to the center frequency of a bin window, the attenuation will be 6 dB on the center frequency. Since the bin windows are

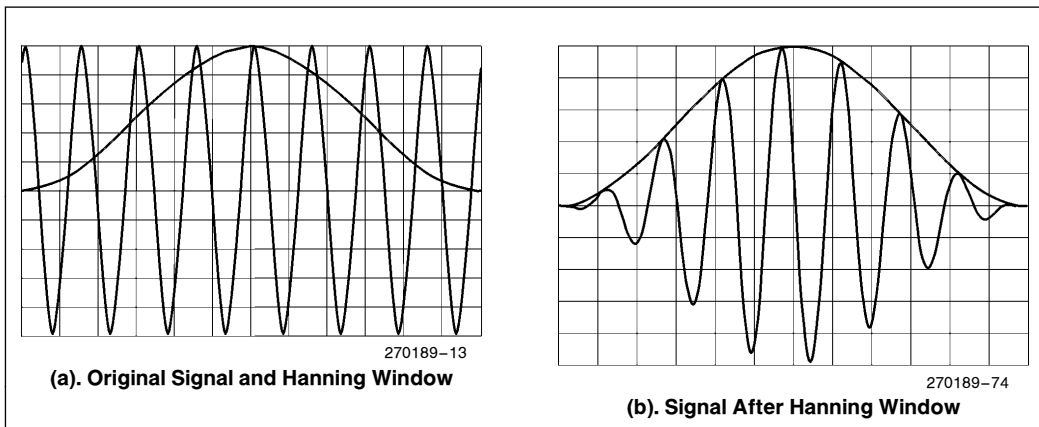


Figure 9. Effect of Hanning Window on FFT Input

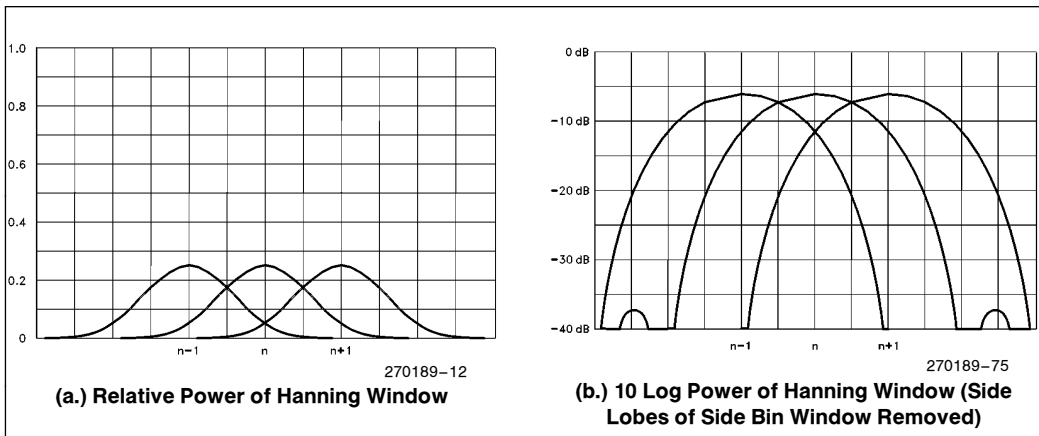


Figure 10. Bin Windows after Using Hanning Input Window

wider than normal, the input frequency will also have energy which falls into the bins on either side of center. These side bins will show a reading of 6 dB below the center window. The disadvantage of this spreading is far less than the advantage of removing leakage from the FFT output.

A set of FFT output plots are included in the Appendix. These plots show the effect of windowing on various signals. There are examples of all of the cases described above. A brief discussion of the plots is also presented.

Applications which can make use of this frequency magnitude information include a wide range of signal processing and detection tasks. Many of these tasks use digital filtering and signature analysis to match signals to a standard. This technique has been applied to anti-knock sensors for automobile engines, object identification for vision systems, cardiac arrhythmia detectors, noise separation and many other applications. The ability to do this on a single-chip computer opens a door to new products which would have not been possible or cost effective previously.

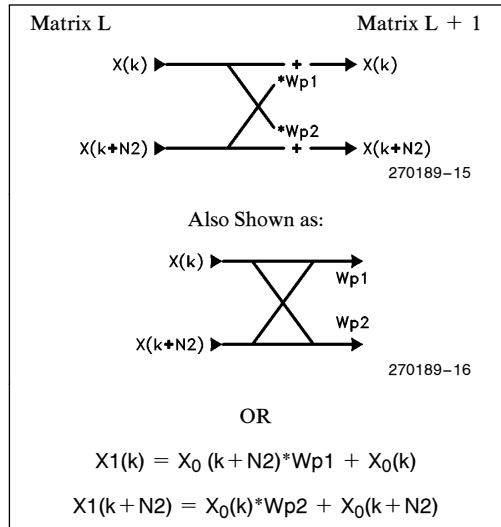
The next four sections of this application note cover the operation of the programs on a line by line basis. Section 6 shows an implementation of the FFT algorithm in BASIC. This code is used as a template to write the ASM96 code in Section 7. Sections 8, 9, and 10 cover the code sections which support the FFT module. After all of the code sections are discussed, an overview of how to use the program is presented in Section 11.

### 6.0 BASIC PROGRAM FOR FFTS

The algorithm for this FFT is shown in the flowchart in Figure 11 and the BASIC program in Listing 1. There are four sections to this program: initialization, pre-weaving, transform calculation, and post-weaving. The flowchart is generalized, however, the BASIC program has been optimized for assembly language conversion with 64 real samples.

On the flowchart, the initialization and pre-weaving sections are incorporated as "Read in Data". The data to be read includes the raw data as well as the size of the array and the scaling factor. The details for pre-weaving have been discussed earlier, and initialization varies from computer to computer. LOOP COUNT keeps track of which of the factored matrices are being multiplied. SHIFT is the shift count which is used to determine the power of W (as defined earlier) which will be used in the loop.

For each loop N calculations are performed in sets of two. Each calculation set is referred to as a butterfly and has the following form:

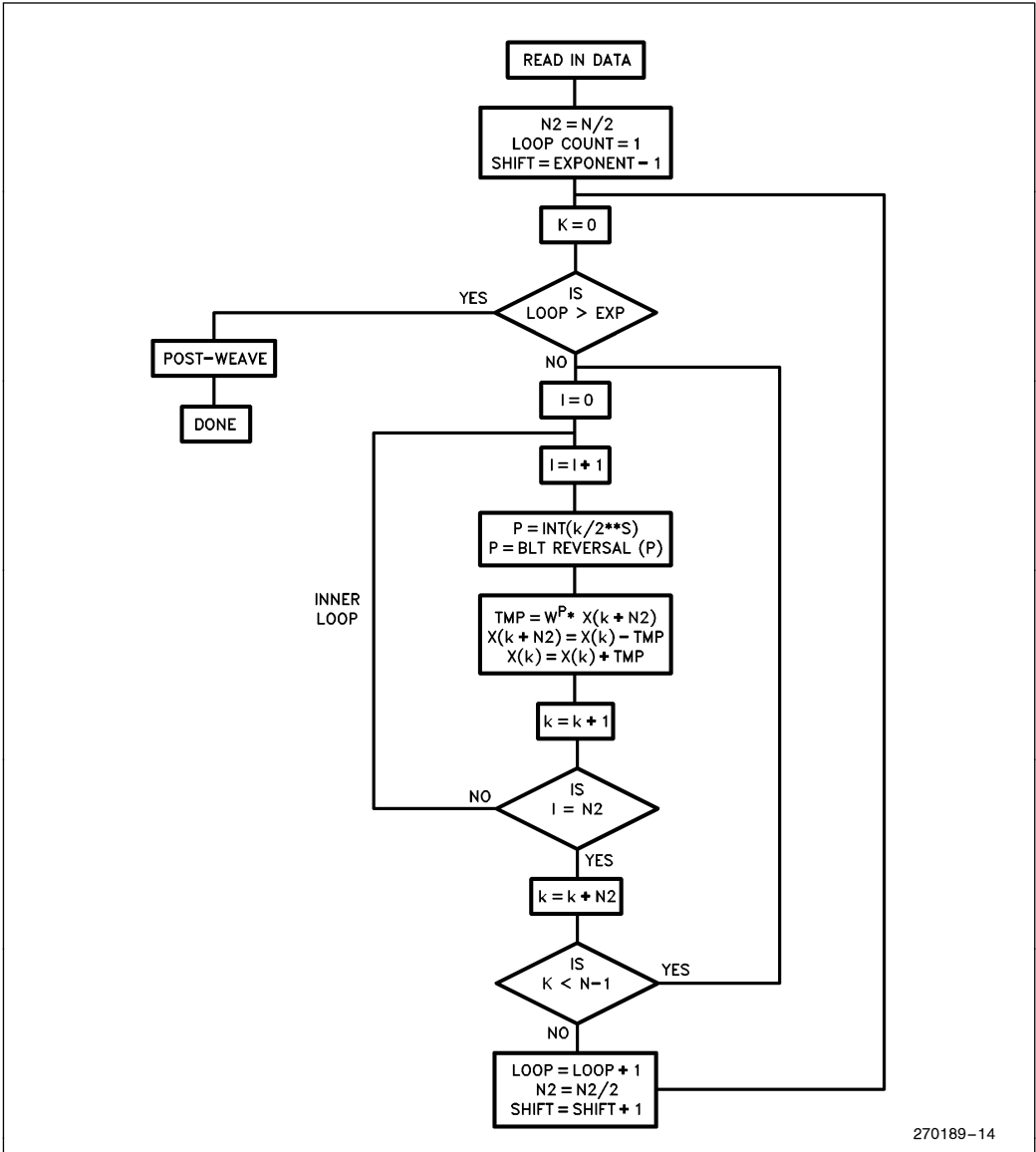


In general, the W factors are not the same. However, for the case of this FFT algorithm, Wp1 will always equal (-Wp2). This is because of the way in which "p" is calculated, and the fact that W(x) is a sinusoidal function.

The inner loop in the flowchart is performed N2 times. For LOOP=1, N2=N/2 and if INCNT=N2 then k=N2 and k+N2=N, so the first loop is done and parameters LOOP, N2, and SHIFT are updated. For the first loop, all N/2 sets of calculations are performed contiguously. As LOOP increases, the number of contiguous calculations are cut in half, until LOOP=EXPONENT.

When LOOP=EXPONENT, N2=1, the butterfly is then performed on adjacent variables. Figure 12 shows the butterfly arrangement for a calculation where N=8, so that EXPONENT=3.

The BASIC program follows this flowchart, but operations have been grouped to make it easier to convert it to assembly language. Also not shown in the flowchart are several divide by 2 operations. There are five in the main section, one per loop. These provide the T/NT factor in equation 8 for N=32 (2<sup>5</sup>=32). There is also an extra divide by two in the post-weave section. It is required to prevent overflows when performing the 16-bit signed arithmetic in the ASM96 program. As a result of these operations, the input scale factor is ±1 = ±32767 and the output scaling is ±1 = ±16384. Note, the maximum input values are ±0.99997.



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Figure 11. Flowchart of Basic Program

```

100 ' THIS IS FFT13, FEBRUARY 4, 1986
105 '
110 ' COPYRIGHT INTEL CORPORATION, 1985
115 ' BY IRA HORDEN, MCO APPLICATIONS
120 '
125 ' THIS PROGRAM PERFORMS A FAST FOURIER TRANSFORM ON 64 REAL DATA POINTS
130 ' USING A 2N-POINTS WITH AN N-POINT TRANSFORM ALGORITHM. THE FIRST
135 ' SECTION OF THE PROGRAM PERFORMS A STANDARD TRANSFORM ON DATA THAT HAS
140 ' BEEN INTERLEAVED BETWEEN THE REAL AND IMAGINARY INPUT VALUES. THE
145 ' RESULTS OF THAT TRANSFORM ARE THEN POST-PROCESSED IN THE SECOND SECTION
150 ' OF THE PROGRAM TO PROVIDE THE 32 OUTPUT BUCKETS. THE OUTPUT VALUES ARE
155 ' MULTIPLIED BY "M" TO MAKE IT EASY TO COMPARE WITH THE ASM-96 PROGRAM
160 '
165 INPUT "NAME OF LIST FILE"; LST$
170 PRINT
175 OPEN LST$ FOR OUTPUT AS #1
180 '
200 ' SET UP VARIABLES FOR BASIC
210 DIM XR(32),XI(32),WR(32),WI(32),BR(32)
220 M=16383 ' M=MULT. FACTOR FOR SCALING
230 N=32 : N1=31 : N2=N/2 ' N=NUMBER OF DATA POINTS
240 LOOP=1 : K=0 : EXPONENT=5 : SHIFT=EXPONENT-1 ' 2**E=N
250 PI=3.141592654# : TPN=2*PI/N : PIN=PI/N
260 '
270 ' READ IN CONSTANTS
280 FOR P=0 TO 31 : PN=P*TPN
290 WR(P)=COS(PN) : WI(P)=-SIN(PN) : READ BR(P)
300 NEXT P
310 '
320 FOR K=0 TO 31 ' READ IN DATA
330 READ XR(K) : READ XI(K)
350 NEXT K
360 '
400 ' INITIALIZATION OF LOOP
410 K=0
420 IF LOOP>EXPONENT THEN 700
430 INCNT=0
440 ' ACTUAL CALCULATIONS BEGIN HERE
445 '
450 INCNT=INCNT+1
460 P=BR(INT(K/(2^SHIFT)))
470 WRP=WR(P) : WIP=WI(P) : KN2=K+N2 ' WRP AND WIP ARE CONSTANTS BASED ON
480 TMPR=(WRP*XR(KN2) - WIP*XI(KN2))/2 ' SINES AND COSINES OF BIT REVERSED
490 TMPI=(WRP*XI(KN2) + WIP*XR(KN2))/2 ' VALUES OF K SHIFTRD RIGHT S TIMES
500 TMPR1=XR(K)/2 : TMPI1=XI(K)/2
510 XR(K+N2) = TMPR1 - TMPR ' TMPR, TMPI ARE THE REAL AND IMAGINARY
520 XI(K+N2) = TMPI1 - TMPI ' RESULTS OF A COMPLEX MULTIPLICATION
530 XR(K) = TMPR1 + TMPR
540 XI(K) = TMPI1 + TMPI
550 '
560 K=K+1
570 IF INCNT<N2 THEN GOTO 450
580 K=K+N2 ' SINCE THE ARRAY IS PROCESSED 2 POINTS AT A TIME,
590 IF K<N1 THEN GOTO 430 ' ONLY N/2 LOOPS NEED TO BE MADE. ON EACH PASS,
600 LOOP=LOOP+1 : N2=N2/2 ' THE VALUE OF N2 CHANGES AND SMALLER CONSECUTIVE
605 SHIFT=SHIFT-1 ' SECTIONS ARE PROCESSED.
610 GOTO 400
620 '
690 '
691 '
692 '
693 '

```

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## Listing 1—BASIC FFT Program



```

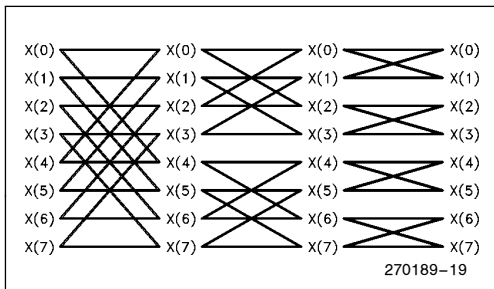
694 '
695 '
696 '
697 '
700           ' POST-PROCESSING AND REORDERING BEGIN HERE
710 '
720 FOR K = 0 TO 31
730 KPIN=K*PIN
740 XRBRK=XR(BR(K)) : XIBRK=XI(BR(K)) ' CONDENSED FOR EASE OF ASM PROGRAMMING
750 XRBRNK=XR(BR(N-K)) : XIBRNB=XI(BR(N-K))
760 TI = (XIBRK+XIBRNB)/2
770 TR = (XRBRK-XRBRNK)/2
780 XRT= (XRBRK+XRBRNK)/4
790 XIT= (XIBRK-XIBRNB)/4
800 OUTR= XRT + TI*COS(KPIN)/2 - TR*SIN(KPIN)/2
810 OUTI= XIT - TI*SIN(KPIN)/2 - TR*COS(KPIN)/2
820 '
830 MAGSQ = OUTR*OUTR+OUTI*OUTI ' THE ASM-96 PROGRAM USES A TABLE LOOK-UP
840 MAG = SQR(MAGSQ) ' ROUTINE TO CALCULATE SQUARE ROOTS
845 IF MAGSQ*M < .5 THEN DECIBEL=0 : GOTO 900
847 DBFACT=M/2/32767*M ' M^2 / 64K
850 DECIBEL=10*LOG(MAGSQ*DBFACT)
860 DECIBEL=DECIBEL * .434294481#
900 GOTO 930
910 PRINT #1, USING "##### "; K,
920 PRINT #1, USING "\ \"; HEX$(M*OUTR), HEX$(M*OUTI), HEX$(M*MAG)
930 ' GOTO 950
942 PRINT #1, USING "## "; K;
943 PRINT #1, USING "##.##### "; OUTR,OUTI,MAG;
945 PRINT #1, USING "###.### "; DECIBEL;
947 PRINT #1, USING "##### "; M*OUTR, M*OUTI, M*MAG
950 NEXT K
960 '
970 IF LST$<>"SCRN:" THEN PRINT #1, CHR$(12)
999 END
1000 END
1010           ' DATA FOR BR(P) - BIT REVERSAL
1020 DATA 0,16,8,24,4,20,12,28,2,18,10,26,6,22,14,30
1030 DATA 1,17,9,25,5,21,13,29,3,19,11,27,7,23,15,31
1040           ' DATA FOR XR,XI
1050 DATA 2,2,2,2,2,2,2,2,2,2,2,2,2,2,2,2
1060 DATA 2,2,2,2,2,2,2,2,2,2,2,2,2,2,2,2
1070 DATA -2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2
1080 DATA -2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2

```

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Listing 1—BASIC FFT Program (Continued)

Lines 165-175 set up the file for printing the data, this can be SCRN:, LPT1:, or any other file.



**Figure 12. Butterflies with N = 8**

Lines 200-310 set up the constants and calculate the WP terms which are stored in the matrices WR(p) and WI(p), for the real and imaginary component respectively.

Lines 320-350 read in the data, alternately placing it into the real and imaginary arrays. The data is scaled by 2 to make the data table simpler.

Lines 410-430 initialize the loop and test for completion.

Lines 450-620 perform the FFT algorithm. Note that all calculations are complex, with the suffixes "R" and "I" indicating real and imaginary components respectively.

The variables on line 470, TMPR1 and TMP11 would normally not be used in a BASIC program as more than one operation can be performed on each line. However, indirect table lookups always use a separate line of assembly code, so separate lines have been used here.

Lines 700-810 perform the post-weave. This is not in the flowchart, but can be found in Equation 11. Once again, table look-ups are separated and additional variables are used for clarity. The variables BR(x) are the bit reversal values of x.

Line 830 calculates the magnitude of the harmonic components.

Lines 900-950 print the results of the calculations, with line 900 determining if the print-out should be in hex or decimal.

Lines 1000-1080 are the data for the bit reversal values and input datapoints. The input waveform is one cycle of a square-wave.

## 7.0 ASM96 PROGRAM FOR FFTS

The BASIC program just presented has been used as an outline for the ASM96 program shown in Listing 2. There are many advantages to using the BASIC program as a model, the main ones being debugging and testing. Since the BASIC program is so similar in program flow to the ASM96 program, it's possible to stop the ASM96 program at almost any point and verify that the results are correct.

```

MCS-96 MACRO ASSEMBLER      FFT_RUN
SERIES-III MCS-96 MACRO ASSEMBLER, V1.0
SOURCE FILE: :F2:FFTRUN.A96
OBJECT FILE: :F2:FFTRUN.OBJ
CONTROLS SPECIFIED IN INVOCATION COMMAND: NOSB
EER LOC OBJECT      LINE  SOURCE STATEMENT
1  $pagelength(50)
2
3  FFT_RUN MODULE STACKSIZE(6)
4
5  ; Intel Corporation, January 24, 1986
6  ; by Ira Horden, MCO Applications
7
8
9  ; This module performs a fast fourier transform (FFT) on 64 real data
10 ; points using a 2N-point algorithm. The algorithm involves using a standard
11 ; FFT procedure for 32 real and 32 imaginary numbers. The real and imaginary
12 ; arrays are filled alternately with real data points, and the output of the
13 ; FFT is run through a post-processor. The result is a one sided array with 32
14 ; output buckets. The post processing includes a table lookup algorithm for
15 ; taking the square root of an unsigned 32-bit number.
16
17 ; All of the calculations in the main FFT program are done using 16-bit
18 ; signed integers. The maximum value of any frequency component is therefore
19 ; +/- 32K. (Note that a square wave of +/-32K has a fundamental component
20 ; greater than +/- 40K). Wherever possible tables are used to increase the
21 ; speed of math operations. The complete transform, including obtaining the
22 ; absolute magnitude of each frequency component, executes in 12
23 ; milliseconds with internal variables, 14 ms with external.
24
25 ; The program requires two 32-word input arrays, with the sample values
26 ; alternated between the two. These start at XREAL and XIMAG. The resultant
27 ; magnitude will be placed in a 32-word array at FFT_OUT. These are all
28 ; externally defined variables. The external constant SCALE_FACTOR is used to
29 ; divide the output when averaging will be used. Since the program averages
30 ; its output, it is necessary to clear the array based at FFT_OUT before
31 ; calling FFT_CALC to start the program.
32
33 ; The program was originally written in BASIC for testing purposes. The
34 ; comments include these BASIC statements to make it easier to follow the
35 ; algorithm.
36
37 $EJECT
    
```

```

MCS-96 MACRO ASSEMBLER      FFT_RUN
ERR LOC OBJECT              SOURCE STATEMENT
38                               ;
39 RSEG                       port1, zero, error
40 EXTRN
41                               ;
42 OSEG at 24H
43 TMPR: ds1                   ; Temporary register, Real
44 TMPI: ds1                   ; Temporary register, Imaginary
45 TMPRL: ds1                  ; Temporary register, Real
46 TMPIL: ds1                  ; Temporary register, Imaginary
47 XTMP: ds1                   ; Temporary data register, Real
48 XTMP: ds1                   ; Temporary data register, Real
49 XHRK: ds1                   ; Temporary register, Imaginary
50 XHRK: ds1                   ; Temporary register, Imaginary
51 XHRK: ds1                   ; Temporary register, Imaginary
52 XHRK: ds1                   ; Temporary register, Imaginary
53 diff equ xrxk              ; Table difference for square root
54 sqrt equ xrxk+2            ; Square root
55 log equ xrxnk              ; 10 Log magnitude*2
56 nxtloc equ xrxk            ; Next location in table
57
58 WIP equ xrxk               ; Multiplication factor, Real
59 WIP equ xrxk+2             ; Multiplication factor, Imaginary
60 PWR equ xrxnk             ; Multiplication factor, Imaginary
61 IN_CNT equ xrxnk-2        ;
62 NDIV2 equ xrxk            ; n divided by 2 (0 < n < N) *2
63
64 KPTR: ds1                  ; K for counter *2 to index words
65 KN2: ds1                   ; KPTR + NDIV2
66 N_SUB_K: ds1              ; N-K *2 to index words
67 RK: ds1                   ; Bit reversed pointer of KPTR
68 RNK: ds1                  ; Bit reversed pointer of N_SUB_K
69 SHFT_CNT: ds1             ;
70 LOOP_CNT: ds1             ;
71 ptr equ kn2               ; Pointer for square root table
72 DSEG
73
74 EXTRN FFT_MODE              ; FFT MODE: mode for FFT input and graphing
75 EXTRN XREAL, XIMAG         ; XREAL, XIMAG: Base addresses for 32 16-bit signed
76                                     ; entries for real and imaginary numbers respectively.
77 EXTRN FFT_OUT              ; FFT_OUT: Starting address for 32 word array
78                                     ; of magnitude information.
79
80 OUTR: dsw                  ; Real component of fft
81 OUTI: dsw                  ; Imaginary component of waveform
82 PUBLIC OUTR,OUTI
83
84 $EJECT
    
```

Listing 2—ASM96 FFT Program (Continued)

```

ERR LOC OBJECT      SOURCE STATEMENT
2280                    CSEG at 2280H
86                    PUBLIC fft_calc      ; Starting point for FFT algorithm
87                    EXTRN scale_factor      ; Shift factor used to prevent overflow when averaging
88                                       ; fft outputs
89                                       ;
90                                       ;
91                                       ;
92                                       ;
93                                       ;
94                                       ;
95                                       ;
96                                       ;
97                                       ;
98                                       ;
99                                       ;
2280                                       ; START FOURIER CALCULATIONS
2280 1100                                       ; 400 ' INITIALIZATION OF LOOP
2282 B10100                    error                    ;*** Indication Only
2285 FC                    port1,#00000001b
2286 B10188                                       ;
2289 B10486                                       ;
228C A1200044                                       ;
2290                                       ;
2290 960400                                       ;
2293 014C                                       ;
2295 990588                                       ;
2298 DA0220A3                                       ;
110                                       ;
111                                       ;
112                                       ;
113                                       ;
114                                       ;
115                                       ;
229E                                       ;
229E 65020042                                       ;
22A2 A04C40                                       ;
22A5 085640                                       ;
22A8 71FE40                                       ;
22AB A341003840                                       ;
22B0 A34144393C                                       ;
22B5 A34186393E                                       ;
22BA 44444C4E                                       ;
127                                       ;

```

Listing 2—ASM96 FFT Program (Continued)

MCS-96 MACRO ASSEMBLER	ERR LOC	OBJECT	FFT_RUN	LINE	SOURCE STATEMENT	02/18/86	PAGE	4
				128	;; Complex multiplication follows			
				129				
				130	;;			
	22BE	FE4F4F00003C24	E	131	gm: mul tmp1,wrp,xreal[kn2]			480
	22C5	FE4F4F00003E28	E	132	mul tmp1,wip,ximag[kn2]			
	22CC	6E2A26		133	sub tmp1,t2,tmp1+2			
				134	;;			
	22CF	FE4F4F00003C2C	E	135	mul tmp1,wrp,ximag[kn2]			490
	22D6	FE4F4F00003E28	E	136	mul tmp1,wip,xreal[kn2]			
	22DD	642E2A		137	add tmp1,t2,tmp1+2			
				138	;;			
				139	;; using the high byte only of a signed multiply			
				140	;; provides an effective divide by two			
				141				
	22E0	DC55		142	BVT ERR1 ; Branch on error in complex multiplications			
				143				
	22E2	A34D00002C	E	144	ld tmp1,xreal[kptr]			500
	22E7	0A012C		145	shra tmp1,#1			
	22EA	A34D000030	E	146	ld tmp11,ximag[kptr]			
	22EF	0A0130		147	shra tmp11,#1			
				148	;;			
				149	;;			
	22F2	482E2C34		150	gr2: sub xrtmp,tmp1,tmp1+2			510
	22F6	C34F000034	E	151	st xrtmp,xreal[kn2]			
				152	;;			
	22FB	482A3038	E	153	gr2: sub xitmp,tmp11,tmp11+2			520
	22FF	C34F000038	E	154	st xitmp,ximag[kn2]			
				155	;;			
				156	;;			
	2304	442E2C34		157	add xrtmp,tmp1,tmp1+2			530
	2308	C34D000034	E	158	st xrtmp,xreal[kptr]			
				159	;;			
	230D	442A3038	E	160	grx: add xitmp,tmp11,tmp11+2			540
	2311	C34D000038	E	161	st xitmp,ximag[kptr]			
				162	;;			
	2316	DC23		163	BVT ERR2 ; Branch on error in complex additions			
				164	\$eject			

Listing 2—ASM96 FFT Program (Continued)







```

MCS-96 MACRO ASSEMBLER      FFT_FUN      PAGE 7
ERR LOC OBJECT                LINE          SOURCE STATEMENT
                                238 ;                Multiply will provide effective divide by 2
                                239 ;                ;;;;
                                240 ;                ;;;; 800 OUTR= (XIT + TI*COSFN(K)/2 - TR* SINFN(K)/2)
                                241 ;                ;;;;
                                242 ;                ;;;;
                                243 ;                ;;;;
                                244 ;                ;;;;
                                245 ;                ;;;;
                                246 ;                ;;;;
                                247 ;                ;;;;
                                248 ;                ;;;; OUTR = Real Output Values
                                249 ;                ;;;;
                                250 ;                ;;;;
                                251 ;                ;;;; 810 OUTI= (XIT - TI*SINFN(K)/2 - TR*COSFN(K)/2)
                                252 ;                ;;;;
                                253 ;                ;;;;
                                254 ;                ;;;;
                                255 ;                ;;;;
                                256 ;                ;;;;
                                257 ;                ;;;;
                                258 ;                ;;;;
                                259 ;                ;;;; OUTI = Imaginary Output values
                                260 ;                ;;;;
                                261 ;                ;;;;
                                262 ;                ;;;;
                                263 ;                ;;;;
                                264 ;                ;;;; 850 MAG =SQR(OUTR*OUTR + OUTI*OUTI)
                                265 ;                ;;;; Get Magnitude of Vector
                                266 ;                ;;;;
                                267 ;                ;;;;
                                268 ;                ;;;;
                                269 ;                ;;;; tmpR = tmpi**2 + tmpR**2
                                270 ;                ;;;;
                                271 ;                ;;;;
                                272 ;                ;;;;
                                273 ;                ;;;; FFT_MODE,2,CALC_SQRT
                                274 ;                ;;;;
                                275 ;                ;;;; $eject

                                23A2 FE4F4D4038242C      mul    tmpR1,tmpR,sinfn[kptr]
                                23A9 FE4F4DC2382B50      mul    tmpI1,tmpI,cosfn[kptr]
                                23B0 643034      add    xrtmp,tmpI1
                                23B3 A43236      addc   xrtmp+2,tmpI1+2
                                23B6 682C34      sub    xrtmp,tmpR1
                                23B9 A82E36      subc   xrtmp+2,tmpR1+2
                                23BC C34D000036      st     xrtmp+2,outr[kptr]
                                R

                                23C1 FE4F4DC238242C      mul    tmpR1,tmpR,cosfn[kptr]
                                23C8 FE4F4D40382B50      mul    tmpI1,tmpI,sinfn[kptr]
                                23CF 685036      sub    xitmp,tmpI1
                                23D2 A6523A      subc   xitmp+2,tmpI1+2
                                23D5 682C36      sub    xitmp,tmpR1
                                23D8 682E3A      subc   xitmp+2,tmpR1+2
                                23DB C34D40003A      st     xitmp+2,outi[kptr]
                                R

                                23E0 A03624      GET_MAG: ld    tmpR,xrtmp+2
                                23E3 A03A28      ld     tmpI,xitmp+2
                                23E6 FB6C2424      mul    tmpR,tmpR
                                23EA FB6C2828      mul    tmpI,tmpI
                                23EE 642824      add    tmpR,tmpI
                                23F1 A42A26      addc   tmpR+2,tmpI+2
                                23F4 32004C      bcc   FFT_MODE,2,CALC_SQRT
                                E
                                275 $eject
    
```

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Listing 2—ASM96 FFT Program (Continued)

```

2377          shift_cnt
2378          tmpr,shift_cnt      ; Normalize and get normalization factor
2379          shift_cnt,#15
2380          LOG_IN_RANGE      ; Jump if SHIFT_CNT <= 15
2381          jle
2382          clr
2383          LOG_STORE
2384          br
2385          LOG_IN_RANGE:
2386          shift_cnt,shift_cnt,shift_cnt      ; Make shift_cnt a pointer
2387          ptr,tmpr+3          ; Most significant byte is table pointer
2388          ptr,ptr,ptr
2389          ptr,# LOG_TABLE-256 ; ptr= Table + offset (offset=tmpr+3)
2390          add                ; Use -256 since tmpr+3 is always >= 128
2391          ld log,[ptr]+
2392          ld nxtloc,[ptr]    ;; Linear Interpolation
2393          sub nxtloc,log      ; nxtloc = next log - log
2394          ldbze diff,tmpr+2  ; diff+1 = nxtloc * tmpr+2 / 256
2395          mulu
2396          shr1 diff,#8       ; log = log + diff/256
2397          add log,diff
2398          shr log,#5        ; 8192/32 * 20LOG(x) = 256 * 20LOG(x)
2399          addc log,log_offset[shft_cnt]      ; add log of normalization factor
2400          ;; Log (M*N) = Log M + Log N
2401          LOG_STORE:
2402          log,#SCALE_FACTOR
2403          shr log,zero      ; Divide to prevent overflow during
2404          add log,FFT_OUT[kptr] ; averaging of outputs
2405          st log,FFT_OUT[kptr]
2406          BR
2407          $reject
2408          BR
2409          AC274E
2410          444E4E4E
2411          65085A4E
2412          A24F40
2413          A24E44
2414          684044
2415          AC263C
2416          6C443C
2417          0C083C
2418          643C40
2419          080540
2420          A7570A3C40
2421          080040
2422          A40040
2423          674D000040
2424          C34D000040
2425          2045

```

Listing 2—ASM96 FFT Program (Continued)



```

ERR LOC OBJECT          FFT_RUN
LINE SOURCE STATEMENT
367 $molist CSEG AT 3800H      ;;;; Use 2k for tables
368
369
370 BREV: ; 2*bit reversal value
371
372 2*0, 2*16, 2*8, 2*24, 2*4, 2*20, 2*12, 2*28
373 2*2, 2*18, 2*10, 2*26, 2*6, 2*22, 2*14, 2*30
374 2*1, 2*17, 2*9, 2*25, 2*5, 2*21, 2*13, 2*29
375 2*3, 2*19, 2*11, 2*27, 2*7, 2*23, 2*15, 2*31
376
377 SINFN:
378 0, 3212, 6393, 9512, 12539, 15446, 18204, 20767
379 23170, 25329, 27245, 28698, 30273, 31356, 32137, 32609
380 32767, 32609, 32137, 31356, 30273, 28698, 27245, 25329
381 23170, 20767, 18204, 15446, 12539, 9512, 6393, 3212
382 0, -3212, -6393, -9512, -12539, -15446, -18204, -20767
383 -23170, -25329, -27245, -28698, -30273, -31356, -32137, -32609
384 -32767, -32609, -32137, -31356, -30273, -28698, -27245, -25329
385 -23170, -20767, -18204, -15446, -12539, -9512, -6393, -3212
386 0
387 COSFN:
388 32767, 32609, 32137, 31356, 30273, 28698, 27245, 25329
389 23170, 20767, 18204, 15446, 12539, 9512, 6393, 3212
390 0, -3212, -6393, -9512, -12539, -15446, -18204, -20767
391 -23170, -25329, -27245, -28698, -30273, -31356, -32137, -32609
392 -32767, -32609, -32137, -31356, -30273, -28698, -27245, -25329
393 23170, -20767, -18204, -15446, -12539, -9512, -6393, -3212
394 -23170, -20767, -18204, -15446, -12539, -9512, -6393, -3212
395 0, 3212, 6393, 9512, 12539, 15446, 18204, 20767
396 23170, 25329, 27245, 28698, 30273, 31356, 32137, 32609
397 32767
398
399 MR: ;;;; MR = COS(K*2PI/N)
400 32767, 32609, 32137, 30273, 27245, 23170, 18204, 12539, 6393
401 0, -6393, -12539, -18204, -23170, -27245, -30273, -32137
402 -32767, -32609, -32137, -30273, -27245, -23170, -18204, -12539, -6393
403 0, 6393, 12539, 18204, 23170, 27245, 30273, 32137
404 32767
405
406 WI: ;;;; WI = -SIN(K*2PI/N)
407 0, -6393, -12539, -18204, -23170, -27245, -30273, -32137
408 -32767, -32137, -30273, -27245, -23170, -18204, -12539, -6393
409 0, 6393, 12539, 18204, 23170, 27245, 30273, 32137
410 32767, 32137, 30273, 27245, 23170, 18204, 12539, 6393
411 0
412 $eject
    
```

Listing 2—ASM96 FFT Program (Continued)

```

MCS-96 MACRO ASSEMBLER          FFT_RUN          PAGE 11
ERR LOC OBJECT                    SOURCE STATEMENT
39C8                                ; 65535/(square root of 2**SHFT_CNT) ; 0<=SHFT_CNT<32
39C8 FFF04B50080825A              TAB_SQR:      1      2      4      8      16     32     64     128
39D8 0010500800008A905            DCW          65535, 46340, 32768, 23170, 16384, 11585, 8192, 5793
420                                ;:          256     512     1024    2048    4096    8192    16384   32768
421 DCW          4096, 2896, 2048, 1448, 1024, 724, 512, 362
422                                ;:          65536, 131072, 262144, 524288, ...
424 DCW          256, 181, 128, 91, 64, 45, 32, 23
425 DCW          16, 11, 8, 6, 4, 3, 2, 1
426
427 SQ_TABLE:      ; square root of n * 2**24 N=128, 129, 130 ... 255
429 DCW          46341, 46522, 46702, 46881, 47059, 47237, 47415, 47591
430 DCW          47767, 47942, 48117, 48291, 48465, 48637, 48809, 48981
431 DCW          49152, 49322, 49492, 49661, 49830, 49998, 50166, 50332
432 DCW          50499, 50665, 50830, 50995, 51159, 51323, 51486, 51649
433 DCW          51811, 51972, 52134, 52294, 52454, 52614, 52773, 52932
434 DCW          53090, 53248, 53405, 53562, 53719, 53874, 54030, 54185
435 DCW          54340, 54494, 54647, 54801, 54954, 55106, 55258, 55410
436 DCW          55661, 55712, 55862, 56012, 56162, 56311, 56459, 56608
437 DCW          56756, 56903, 57051, 57196, 57344, 57490, 57636, 57781
438 DCW          57926, 58071, 58215, 58359, 58503, 58646, 58789, 58931
439 DCW          59073, 59215, 59357, 59495, 59639, 59779, 59919, 60059
440 DCW          60199, 60338, 60477, 60615, 60754, 60891, 61029, 61166
441 DCW          61303, 61440, 61576, 61712, 61848, 61984, 62119, 62254
442 DCW          62388, 62523, 62657, 62790, 62924, 63057, 63190, 63323
443 DCW          63455, 63587, 63719, 63850, 63982, 64113, 64243, 64374
444 DCW          64504, 64634, 64763, 64893, 65022, 65151, 65280, 65408
445 DCW
446
447 $eject

```

Listing 2—ASM96 FFT Program (Continued)



The BASIC program is used as comments in the ASM96 program. Some of the variables in the ASM96 program have slightly different names than their counter-parts in the BASIC program. This was to make the comments fit into the ASM96 code. Highlights in this section of code are a table driven square root routine and log conversion routine which can easily be adapted for use by any program.

Both the square root routine and the log conversion routine use the 32-bit value in the variable TMPR. The square root routine calculates the square root of that value in the variable SQRT+2, a 16-bit variable. In this program, the square root value is averaged and stored in a table.

The log conversion routine divides the value in TMPR by 65536 ( $2^{16}$ ) and uses table lookup to provide the common log. The result is a 16-bit number with the value  $512 * 10 \text{ Log}(\text{TMPR}/65536)$  stored in the variable LOG. This calculation is used to present the results of the FFT in decibels instead of magnitude. With an input of 63095, the output is  $512 * 48 \text{ dB}$ . The graph program, (Section 10), prints the output value of the plot as INPUT/512 dB.

The following descriptions of the ASM code point out some of the highlights and not-so-obvious coding:

Lines 1-104 initialize the code and declare variables. The input and output arrays of the program are declared external. Note that many of the registers are

overlayable, use caution when implementing this routine with others with overlayable registers.

Lines 116-124 calculate the power of W to be used. Note that KPTR is always incremented by 2. The multiple right shift followed by the AND mask creates an even address and the indirect look to the BR (Bit Reversal) table quickly calculates the power PWR.

Lines 130-138 perform the complex multiplications. Since WIP and WRP range from  $-32767$  to  $+32767$ , the multiplication is easy to handle. The automatic divide by two which occurs when using the upper word only of the 32-bit result is a feature in this case.

Lines 144-163 use right shifts for a fast divide, then add or subtract the desired variables and store them in the array. Note that the upper word of TMPR and TMPI is used, and the same array is used for both the input and output of the operations.

Lines 165-189 update the loop variables and then check for errors on the complex multiplications and additions. If there are no overflows at this time the data will run smoothly through the rest of the program.

Lines 200-212 load variables with values based on the bit reversed values of pointers.

Lines 214-236 perform additions and subtractions to prepare for the next set of formulas. Note that XITMP and XRTMP are 32-bit values.

Lines 240-260 perform multiplies and summations resulting in 32-bit variables. This saves a bit or two of accuracy. The upper words are then stored as the results.

Lines 263-272 generate the squared magnitude of the harmonic component as a 32-bit value.

Lines 278-310 calculate  $10 \text{ Log} (\text{TMPR}/65536)$ . The 32-bit register TMPR is divided by 65536 so that the output range would be reasonable.

First, the number is normalized. (It is shifted left until a 1 is in the most significant bit, the number of shifts required is placed in SHFT\_CNT.) If it had to be shifted more than 15 times the output is set to zero.

Next, the most significant BYTE is used as a reference for the look-up table, providing a 16-bit result. The next most significant BYTE is then used to perform linear interpolation between the referenced table value and the one above it. The interpolated value is added to the directly referenced one.

The 16-bit result of this table look-up and interpolation is then added to the Log of the normalization factor, which is also stored in a table. This table look-up approach works fast and only uses 290 bytes of table space.

Lines 321-357 calculate the square root of the 32-bit register TMPR using a table look-up approach.

First, the number is normalized. Next, the most significant BYTE is used as a reference for the look-up table, providing a 16-bit result. The next most significant BYTE is then used to perform linear interpolation between the referenced table value and the one above it. The interpolated value is added to the directly referenced one.

The 16-bit result of this table look-up and interpolation is then divided by the square root of the normalization factor, which is also stored in a table. This table look-up approach works fast and only uses 320 bytes of table space. The results are valid to near 14-bits, more than enough for the FFT algorithm.

Lines 352-360 average the magnitude value, if multiple passes are being performed, and then store the value in the array. The loop-counters are incremented and the process repeats itself.

This concludes the FFT routine. In order to use it, it must be called from a main program. The details for calling this routine are covered in the next section.

## 8.0 BACKGROUND CONTROL PROGRAM

The main routine is shown in Listing 3. It begins with declarations that can be used in almost any program. Note that these are similar, but not identical, to other 8096 include files that have been published. Comments on controlling the Analog to Digital converter routine follow the declarations.



MCS-96 MACRO ASSEMBLER FFT\_MAIN\_APNOTE  
 SERIES-III MCS-96 MACRO ASSEMBLER, V1.0  
 SOURCE FILE: :F2:FTMAIN.A96  
 OBJECT FILE: :F2:FTMAIN.OBJ  
 CONTROLS SPECIFIED IN INVOCATION COMMAND: NO\$B

```

ERR LOC OBJECT
LINE SOURCE STATEMENT
1 $pagelength(50)
2
3 FFT_MAIN_APNOTE MODULE MAIN, STACKSIZE(6)
4
5 ; Intel Corporation, January 24, 1986
6 ; by Ira Horden, MCO Applications
7
8
9 ; This program performs an FFT on real data and plots it on a printer.
10 ; It uses the program modules A2DOON, PLOTSP, and FFTRUN. The adjustable
11 ; parameters of each of the programs are set by this main module.
12
13
14 $INCLUDE (:F0:DEMO96.INC) ; Include SFR definitions
15 ;$no$list ; Turn listing off for include file
16
17 ;*****
18 ; Copyright 1985, Intel Corporation
19 ; October 28, 1985
20 ; by Ira Horden, MCO Applications
21
22 ; DEMO96.INC - DEFINITION OF SYMBOLIC NAMES FOR THE I/O REGISTERS OF THE 8096
23 ;*****
24
25
26
27 EQU 00h:WORD ; R/W Zero Register
28 EQU 02h:BYTE ; W A to D command register
29 AD RESULT_LO ; R Low byte of result and channel
30 AD RESULT_HI ; R High byte of result
31 HSI_MODE ; W Controls HSI transition detector
32 HSO_TIME ; W HSI time tag
33 HSI_TIME ; R HSO time tag
34 HSO_COMMAND ; W HSO command tag
35 HSI_STATUS ; R HSI status register (reads fifo)
36 SBUF ; R/W Serial port buffer
37 INT_MASK ; R/W Interrupt mask register
38 INT_PENDING ; R/W Interrupt pending register
39 SPOON ; R/W Serial port control register
40 SPSTAT ; R Serial port status register
41 WATCHDOG ; W Watchdog timer
0000
0002
0003
0004
0006
0007
0008
0009
0011
0011
000A
    
```

Listing 3—Main Routine

ERR LOC OBJECT

```

LINE SOURCE STATEMENT
000A EQU OAH:WORD
000C EQU OCH:WORD
000E EQU OEH:BYTE
000F EQU OFH:BYTE
0010 EQU OFH:BYTE
0015 EQU IOH:BYTE
0016 EQU IOH:BYTE
0018 EQU IOH:BYTE
0019 EQU IOH:BYTE
0020 EQU IOH:BYTE
0021 EQU IOH:BYTE
0022 EQU IOH:BYTE
0023 EQU IOH:BYTE
0024 EQU IOH:BYTE
0025 EQU IOH:BYTE
0026 EQU IOH:BYTE
0027 EQU IOH:BYTE
0028 EQU IOH:BYTE
0029 EQU IOH:BYTE
0030 EQU IOH:BYTE
0031 EQU IOH:BYTE
0032 EQU IOH:BYTE
0033 EQU IOH:BYTE
0034 EQU IOH:BYTE
0035 EQU IOH:BYTE
0036 EQU IOH:BYTE
0037 EQU IOH:BYTE
0038 EQU IOH:BYTE
0039 EQU IOH:BYTE
0040 EQU IOH:BYTE
0041 EQU IOH:BYTE
0042 EQU IOH:BYTE
0043 EQU IOH:BYTE
0044 EQU IOH:BYTE
0045 EQU IOH:BYTE
0046 EQU IOH:BYTE
0047 EQU IOH:BYTE
0048 EQU IOH:BYTE
0049 EQU IOH:BYTE
0050 EQU IOH:BYTE
0051 EQU IOH:BYTE
0052 EQU IOH:BYTE
0053 EQU IOH:BYTE
0054 EQU IOH:WORD
0055 EQU ODH
0056 EQU OAH
0057 EQU OAH
0058 EQU OAH
0059 EQU OAH
0060 EQU OAH
0061 EQU OAH
0062 EQU OAH
0063 EQU OAH
0064 EQU OAH
0065 EQU OAH
0066 EQU OAH
0067 EQU OAH
0068 EQU OAH
0069 EQU OAH
0070 EQU OAH
0071 EQU OAH
0072 EQU OAH
0073 EQU OAH
0074 EQU OAH
0075 EQU OAH
0076 EQU OAH
0077 EQU OAH
0078 EQU OAH
0079 EQU OAH
0080 EQU OAH
0081 EQU OAH
0082 EQU OAH
0083 EQU OAH
0084 EQU OAH
0085 EQU OAH
0086 EQU OAH
0087 EQU OAH
0088 EQU OAH

```

```

; R Timer1 register
; R Timer2 register
; R I/O port 0
; W Band rate register
; R/W I/O port 1
; R/W I/O port 2
; W I/O control register 0
; R I/O status register 0
; W I/O control register 1
; R I/O status register 1
; W PWM control register
; R/W System stack pointer

PUBLIC ZERO,AD_COMMAND,AD_RESULT_LO,AD_RESULT_HI,HSI_MODE,HSO_TIME,HSI_TIME
PUBLIC HSO_COMMAND
PUBLIC HSI_STATUS,SEUF,INT_MASK,INT_PENDING,WATCHDOG,TIMER1,TIMER2
PUBLIC BAOD_REG, PORT0, PORT1, PORT2,SPSTAT,SPOON,IOCU,IOCI,IOSO,IOSI
PUBLIC PWM_CONTROL,SP,CR,LF
RSEG at ICH
AX: DSW 1
DX: DSW 1
BX: DSW 1
CX: DSW 1
AL EQU AX :BYTE
AH EQU (AX+1) :BYTE
BL EQU BX :BYTE
public ax, bx, cx, dx, ah, al, bl
$list ; Turn listing back on
; End of include file
; A2D UTILITY COMMANDS/RESPONSES FOR "CONTROL_A2D"
81
82 busy equ 7
83 con_b0 equ 00010000b; convert to BUFFO
84 dump_b0_p_s equ 00101000b; download BUFFO as PAIRED SIGNED data
85
86
87 AVE_NUM equ 1 ; Number of times to average the waveform
88 AVR_NUM < 256

```

; Temp registers used in conformance  
; with PIM-96(tm) conventions.

Listing 3—Main Routine (Continued)

```

MCS-96 MACRO ASSEMBLER      FFT_MAIN_APNOTE
ERR LOC OBJECT                LINE SOURCE STATEMENT
0000                          89 SCALE_FACTOR equ 0 ; Number of rights shifts performed on
                               90 ; output of FFT. Used to prevent overflow
                               91 ; on summation
0100                          93 PLOT_RES equ 256 ; Number of input units per plot unit
0080                          95 PLOT_RES_2 equ PLOT_RES/2
9100                          96 PLOT_MAX equ PLOT_RES*145 ; 145 chrs/row
                               97 PUBLIC scale_factor, plot_res, plot_res_2, plot_max
                               98
0024                          100 OSEG at 24H ; common oseg area
0024                          101 tmpreal: ds1 1
0028                          103 tmpimag: ds1 1
002C                          104 wndptr: ds1 1
002E                          106 varptr: ds1 1
0000                          107
0000                          108 RSEG
0000                          109 fft_mode: dsb 1
0001                          110 error: dsb 1
0002                          111 svf_cnt: dsb 1
                               112 PUBLIC error, fft_mode
                               113
                               114 EXTRN sample_period, control_a2d
                               115
                               116
0080                          117 DSEG at 80h
0080                          118 XREAL: ; For FFT routine
0080                          119 DEST_BUFF_BASE: DSW 64 ; For A2D routine
                               120 XIMAG equ XREAL+64 ; For FFT routine
                               121
                               122 PUBLIC DEST_BUFF_BASE, XREAL, XIMAG
                               123
0200                          124 DSEG AT 200H
0200                          126
0200                          127 PLOT_IN: DSW 32 ; For FFT routine
0240                          128 FFT_OUT: DSW 64 ; For A2D routine
02C0                          129 BUFFO_BASE: DSW 64 ; For A2D routine
                               130 BUFFI_BASE: DSW 64 ; For A2D routine
                               131
                               132 PUBLIC BUFFO_BASE, BUFFI_BASE, FFT_OUT, PLOT_IN
                               133 $eject

```

270189-47

```

ERR LOC OBJECT      SOURCE STATEMENT
2080                    CSEG AT 2080H
134                    EXTRN    INIT_OUTPUT, DRAW_GRAPH, CON_OUT      ; For Plot Routine
135                    EXTRN    FFT_CALC                                    ; For FFT routine
136                    EXTRN    A2D_BUFF_UTIL                               ; For A2D routine
137                    EXTRN    A2D_BUFF_UTIL
138                    EXTRN    A2D_BUFF_UTIL
139                    EXTRN    A2D_BUFF_UTIL
140                    EXTRN    A2D_BUFF_UTIL
141                    EXTRN    A2D_BUFF_UTIL
142                    EXTRN    A2D_BUFF_UTIL
143                    EXTRN    A2D_BUFF_UTIL
144                    EXTRN    A2D_BUFF_UTIL
145                    EXTRN    A2D_BUFF_UTIL
146                    EXTRN    A2D_BUFF_UTIL
147                    EXTRN    A2D_BUFF_UTIL
148                    EXTRN    A2D_BUFF_UTIL
149                    EXTRN    A2D_BUFF_UTIL
150                    EXTRN    A2D_BUFF_UTIL
151                    EXTRN    A2D_BUFF_UTIL
152                    EXTRN    A2D_BUFF_UTIL
153                    EXTRN    A2D_BUFF_UTIL
154                    EXTRN    A2D_BUFF_UTIL
155                    EXTRN    A2D_BUFF_UTIL
156                    EXTRN    A2D_BUFF_UTIL
157                    EXTRN    A2D_BUFF_UTIL
158                    EXTRN    A2D_BUFF_UTIL
159                    EXTRN    A2D_BUFF_UTIL
160                    EXTRN    A2D_BUFF_UTIL
161                    EXTRN    A2D_BUFF_UTIL
162                    EXTRN    A2D_BUFF_UTIL
163                    EXTRN    A2D_BUFF_UTIL
164                    EXTRN    A2D_BUFF_UTIL
165                    EXTRN    A2D_BUFF_UTIL
166                    EXTRN    A2D_BUFF_UTIL
167                    EXTRN    A2D_BUFF_UTIL
168                    EXTRN    A2D_BUFF_UTIL
169                    EXTRN    A2D_BUFF_UTIL
170                    EXTRN    A2D_BUFF_UTIL
171                    EXTRN    A2D_BUFF_UTIL
172                    EXTRN    A2D_BUFF_UTIL
173                    EXTRN    A2D_BUFF_UTIL
174                    EXTRN    A2D_BUFF_UTIL
175                    EXTRN    A2D_BUFF_UTIL
176                    EXTRN    A2D_BUFF_UTIL
177                    EXTRN    A2D_BUFF_UTIL
178                    EXTRN    A2D_BUFF_UTIL
179                    EXTRN    A2D_BUFF_UTIL

```

Listing 3—Main Routine (Continued)

```

ERR LOC OBJECT          LINE SOURCE STATEMENT
-----
20C7          180          ;
                181 LOAD_DATA:          ;;;; LOAD DATA INTO RAM
                182          ;**** FOR INDICATION ONLY
                183          port1,#00
                184
                185 SET_A2D:
                186          control_a2d,#con_b0      ; Set converter for buffer0
                187          orb                      ; Convert channel 1
                188          ld                      ; 100 us sample period
                189          sample_period,#50
                190          CALL
                191          a2d_buff_util          ; Start the conversion process
                192          jbs                      ; wait for all conversions to be done
                193          control_a2d,busy,$
                194          Down_load:
                195          idb                      ; download b0 paired/signed
                196          CALL
                197          a2d_buff_util
                198          RET
                199
                200          TABLE_LOAD:
                201          bx                      ; Load tabled data for testing
                202          clr
                203          id
                204          cx,[ax]+
                205          dx,[ax]+
                206          cx,xreal[bx]
                207          st
                208          dx,ximag[bx]
                209          bx,#2
                210          cmp
                211          bx,#64
                212          blt
                213          LOAD
                214          RET
                215          ; SQUARE WAVE
                216          DATA0:
                217          DCW
                218          32767, 32767, 32767, 32767, 32767, 32767, 32767, 32767
                219          DCW
                220          32767, 32767, 32767, 32767, 32767, 32767, 32767, 32767
                221          DCW
                222          32767, 32767, 32767, 32767, 32767, 32767, 32767, 32767
                $eject

```

Listing 3—Main Routine (Continued)

```

ERR LOC OBJECT      LINE      SOURCE STATEMENT
-----
2182      223      ;
2182      224      DO_WINDOW:      ;;; PERFORM HANNING WINDOW
2182      225           clr      wndptr      ; Windowing provides an effective
2186      226           clr      varptr      ; divide by 2 because of the multiply
2186      227      WINDOW:      ;
2186      228           ld      ax,hanning[wndptr]
2190      229           mul      tmpreal,ax,xreal[varptr]
2197      230           mul      tmpimag,bs,ximag[varptr]
2198      231           shll      tmpreal,#1
21A1      232           shll      tmpimag,#1
21A4      233           st      tmpreal+2,xreal[varptr]
21A9      234           st      tmpimag+2,ximag[varptr]
21AB      235           add      wndptr,#4
21B2      236           add      varptr,#2
21B6      237           cmp      varptr,#54
21BA      238           jne      window
21BC      239           RET
21BE      240      ;
21BE      241      HANNING:      ; Windowing function
21CE      242           dcw      0,      79,      315,      705,      1247,      1935,      2761,      3719
21DE      243           dcw      4799,      6990,      7281,      8660,      10114,      11628,      13187,      14778
21EE      244           dcw      16384,      17989,      19580,      21139,      22653,      24107,      25486,      26777
21FE      245           dcw      27968,      29048,      30006,      30832,      31520,      32062,      32452,      32688
220E      246           dcw      32767,      32688,      32452,      32062,      31520,      30832,      30006,      29048
221E      247           dcw      27968,      26777,      25486,      24107,      22653,      21139,      19580,      17989
222E      248           dcw      16384,      14778,      13187,      11628,      10114,      8660,      7281,      5990
223E      249           dcw      4799,      3719,      2761,      1935,      1247,      705,      315,      79
223E      250           dcw      0
223E      251           dcw      $jeq
223E      252           dcw      0
223E      253           dcw      0
223E      254           dcw      0
223E      255           dcw      0
223E      256           dcw      0
223E      257           dcw      0
223E      258           dcw      0
223E      259           dcw      0
223E      260           dcw      0
223E      261           dcw      0
223E      262           dcw      0
223E      263           dcw      0
223E      264           dcw      0
223E      265           dcw      0
223E      266           dcw      0
223E      267           dcw      0
223E      268           dcw      0
223E      269           dcw      0
223E      270           dcw      0
223E      271           dcw      0
223E      272           dcw      0
223E      273           dcw      0
223E      274           dcw      0
223E      275           dcw      0
223E      276           dcw      0
223E      277           dcw      0
223E      278           dcw      0
223E      279           dcw      0
223E      280           dcw      0
223E      281           dcw      0
223E      282           dcw      0
223E      283           dcw      0
223E      284           dcw      0
223E      285           dcw      0
223E      286           dcw      0
223E      287           dcw      0
223E      288           dcw      0
223E      289           dcw      0
223E      290           dcw      0
223E      291           dcw      0
223E      292           dcw      0
223E      293           dcw      0
223E      294           dcw      0
223E      295           dcw      0
223E      296           dcw      0
223E      297           dcw      0
223E      298           dcw      0
223E      299           dcw      0
223E      300           dcw      0
223E      301           dcw      0
223E      302           dcw      0
223E      303           dcw      0
223E      304           dcw      0
223E      305           dcw      0
223E      306           dcw      0
223E      307           dcw      0
223E      308           dcw      0
223E      309           dcw      0
223E      310           dcw      0
223E      311           dcw      0
223E      312           dcw      0
223E      313           dcw      0
223E      314           dcw      0
223E      315           dcw      0
223E      316           dcw      0
223E      317           dcw      0
223E      318           dcw      0
223E      319           dcw      0
223E      320           dcw      0
223E      321           dcw      0
223E      322           dcw      0
223E      323           dcw      0
223E      324           dcw      0
223E      325           dcw      0
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255                                DATA1:          ; SINE 7.0 X
256                                0, 20787, 32137, 28898, 12539, -9512, -27245, -32609
257                                -23170, -3212, 18204, 31356, 30273, 15446, -6393, -25329
258                                -32767, -25329, -6392, 15446, 30273, 31356, 18204, -3212
259                                -23170, -32609, -27245, -9512, 12539, 28898, 32137, 20787
260                                0, -20787, -32137, -28898, -12539, 9512, 27245, 32609
261                                23170, 3212, -18204, -31356, -30273, -15446, 6393, 25329
262                                32767, 25329, 6392, -15446, -30273, -31356, -18204, 3212
263                                23170, 32609, 27245, 9512, -12539, -28898, -32137, -20787
264                                ; SINE 7.5 X
265                                DATA2:
266                                0, 22005, 32609, 26319, 6393, -16845, -31356, -29621
267                                -12539, 11039, 28898, 31785, 18204, -4808, -25329, -32728
268                                -23170, -1608, 20787, 32412, 27245, 7962, -15446, -30852
269                                -30273, -14010, 9512, 28105, 32137, 19519, -3212, -24279
270                                -32767, -24279, -3212, 19519, 32137, 28105, 9512, -14010
271                                -30273, -30852, -15446, 7962, 27245, 32412, 20787, -1608
272                                -23170, -32728, -25329, -4808, 18205, 31785, 28898, 11039
273                                -12539, -29621, -31356, -16845, 6393, 26319, 32609, 22005
274                                ; .707*SINE 7.5X
275                                DATA3:
276                                0, 15558, 23055, 18607, 4520, -11910, -22169, -20942
277                                -8865, 7804, 20431, 22472, 12870, -3399, -17908, -23138
278                                -16381, -1137, 14697, 22916, 19262, 5629, -10921, -21812
279                                -21403, -9905, 6725, 19870, 22721, 13800, -2271, -17165
280                                -23166, -17165, -2271, 13800, 22721, 19870, 6725, -9905
281                                -21403, -21812, -10920, 5629, 19262, 22916, 14696, -1137
282                                -16381, -23138, -17908, -3399, 12871, 22472, 20431, 7804
283                                -8865, -20942, -22169, -11910, 4520, 18607, 23055, 15557
284                                ; .707*SINE(11x) /16
285                                DATA4:
286                                0, 1277, 1204, -142, -1338, -1119, 282, 1386
287                                1024, -420, -1420, -919, 554, 1441, 804, -683
288                                1448, -683, 804, 1441, 554, -919, -1420, -420
289                                1024, 1386, 282, -1119, -1338, -142, 1204, 1277
290                                -0, -1277, -1204, 142, 1338, 1119, -282, -1386
291                                -1024, 420, 1420, 919, -554, -1441, -804, 683
292                                1448, 683, -804, -1441, -554, 919, 1420, 420
293                                -1024, -1386, -282, 1119, 1338, 142, -1204, -1277
294                                ; -.707*(SINE 7.5X + 1/16 SINE 11X)
295                                DATA5:
296                                0, 1277, 1204, -142, -1338, -1119, 282, 1386
297                                1024, -420, -1420, -919, 554, 1441, 804, -683
298                                1448, -683, 804, 1441, 554, -919, -1420, -420
299                                1024, 1386, 282, -1119, -1338, -142, 1204, 1277
300                                -0, -1277, -1204, 142, 1338, 1119, -282, -1386
301                                -1024, 420, 1420, 919, -554, -1441, -804, 683
302                                1448, 683, -804, -1441, -554, 919, 1420, 420
303                                -1024, -1386, -282, 1119, 1338, 142, -1204, -1277
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MCS-96 MACRO ASSEMBLER   FFT_MAIN_APNOTE
ERR LOC OBJECT            LINE   SOURCE STATEMENT
3F00 0000C241C35E2148     302   DCW
3F10 5EE1D81C43A3164     303   DCW
3F20 59BAE5F8D0C245F     304   DCW
3F30 595095DE5F1B3F49     305   DCW
3F40 5245F0B769F27636     306   DCW
3F50 65A870AC64DA9419     307   DCW
3F60 4BC54868E8618D9     308   DCW
3F70 5FD5C6A4DA6D9D5     309   DCW
3F80                                     310   DCW
                                     311
                                     312   END
                                     313
ASSEMBLY COMPLETED, NO ERROR(S) FOUND.
    
```

SOURCE STATEMENT

```

0, 16894, 24259, 18465, 3182, -13029, -21886, -19657
-7842, 7394, 19011, 21553, 13425, -1968, -17103, -23821
-17829, -1819, 15601, 24386, 19816, 4710, -12341, -22232
-20379, -8519, 7007, 18761, 21583, 13658, -1067, -15888
-23168, -18442, -3476, 13942, 24059, 20990, 6442, -11290
-22427, -21382, -8600, 6848, 18708, 21475, 13892, 4694
-14933, -22466, -18712, -4840, 12317, 23391, 21861, 8225
-9899, -22328, -22451, -10791, 5857, 18749, 21861, 14281
    
```



SERIES-III MCS-96 RELOCATOR AND LINKER, V2.0  
 Copyright 1983 Intel Corporation

INPUT FILES: :F2:FTMAIN.OBJ, :F2:FFTRUN.OBJ, :F2:PLOTSP.OBJ, :F2:A2DCON.OBJ  
 OUTPUT FILE: :F2:FFTOUT  
 CONTROLS SPECIFIED IN INVOCATION COMMAND:  
 IX

INPUT MODULES INCLUDED:  
 :F2:FTMAIN.OBJ(FFT\_MAIN\_APNOTE) 02/18/86  
 :F2:FFTRUN.OBJ(FFT\_RUN) 02/18/86  
 :F2:PLOTSP.OBJ(PLOT\_SERIAL) 02/18/86  
 :F2:A2DCON.OBJ(A2D\_BUFFERING\_UTILITY) 02/18/86

SEGMENT MAP FOR :F2:FFTOUT(FFT\_MAIN\_APNOTE):

	TYPE	BASE	LENGTH	ALIGNMENT	MODULE NAME
**RESERVED*		0000H	001AH		
	REG	001AH	0001H	BYTE	PLOT_SERIAL
*** GAP ***		001BH	0001H		
	REG	001CH	0008H	ABSOLUTE	FFT_MAIN_APNOTE
	OVRLY	0024H	0035H	ABSOLUTE	FFT_RUN
**OVERLAP**	OVRLY	0024H	0010H	ABSOLUTE	PLOT_SERIAL
**OVERLAP**	OVRLY	0024H	000CH	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		0059H	0001H		
	OVRLY	005AH	0006H	WORD	A2D_BUFFERING_UTILITY
	REG	0060H	000CH	WORD	A2D_BUFFERING_UTILITY
	REG	006CH	0003H	BYTE	FFT_MAIN_APNOTE
*** GAP ***		006FH	0011H		
	DATA	0080H	0080H	ABSOLUTE	FFT_MAIN_APNOTE
	STACK	0100H	001EH	WORD	
	DATA	011EH	0080H	WORD	FFT_RUN
*** GAP ***		019EH	0062H		
	DATA	0200H	0140H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		0340H	1CC2H		
	CODE	2002H	0002H	ABSOLUTE	A2D_BUFFERING_UTILITY
*** GAP ***		2004H	007CH		
	CODE	2080H	01C0H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		2240H	0040H		
	CODE	2280H	0215H	ABSOLUTE	FFT_RUN
*** GAP ***		2495H	006BH		
	CODE	2500H	0168H	ABSOLUTE	PLOT_SERIAL
	CODE	2668H	00ECH	BYTE	A2D_BUFFERING_UTILITY
*** GAP ***		2754H	10ACH		
	CODE	3800H	042AH	ABSOLUTE	FFT_RUN
*** GAP ***		3C2AH	00D6H		
	CODE	3D00H	0280H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		3F80H	C080H		

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## Listing 3—Main Routine (Continued)

Several constants are then setup for other routines. The purpose of centrally locating these constants was the ease of modifying the operation of the routines. Note that `AVR_NUM` and `SCALE_FACTOR` must be changed at the same time. `SCALE_FACTOR` is the shift count used to divide each FFT output value before it is added to the output array. `AVR_NUM` must be less than  $2^{**}SCALE\_FACTOR$  or an overflow could occur. Next, the public variables are declared for the arrays and a few other parameters.

The program then begins by setting the stack pointer and waiting for the SBE-96 to finish talking to the terminal. If this is not done, there may be serial port interrupts occurring for the first twenty five milliseconds of program operation.

Initialization of the plotter is next, followed by setting the `FFT_MODE` byte. This byte controls the graphing, loading and magnitude calculation of the FFT data. Since `FFT_MODE` is declared `PUBLIC` in this module, and `EXTERNAL` in the `PLOT` module and `FFTRUN` module, the extra bits available in this byte can be used for future enhancements.

The next step is to clear the FFT output array. Since the FFT program can be set to average its results by dividing the output before adding it to the magnitude array, the array must be cleared before beginning the program.

Data is then loaded into into the FFT input array by the code at `LOAD_DATA`, or the code at `TABLE_LOAD`, depending on the value of `FFT_MODE` bit 0. The tabled data located at `DATA0` is a square wave of magnitude 1. This waveform provides a reasonable test of the FFT algorithm, as many harmonics are generated. The results are also easy to check as the pattern contains half zeros, imaginary values which are always the same, and real values which decrease. Figure 13 shows the output in fractions, hexadecimal and decimal. The hexadecimal and decimal values are based on an output of 16384 being equal to 1.00.

Note that the magnitude is

$$SQR (REAL^2 + IMAG^2)$$

and the dB value is

$$10 \text{ LOG } ( (REAL^2 + IMAG^2)/65536 )$$

The divide by 65536 is used for the dB scale to provide a reasonable range for calculations. If this was not done, a 32-bit LOG function would have been needed.

After the data is loaded, the data is optionally windowed, based on `FFT_MODE` bit 1, and the FFT program is called. Once the loop has been performed `AVR_CNT` times, the graph is drawn by the plot routine.

Appended to the main routine is the `FFTOUT.M96` Listing. This is provided by the relocater and linker, `RL96`. With this listing and the main program, it is possible to determine which sections of code are at which addresses.

Using the modular programming methods employed here, it is reasonably easy to debug code. By emulating the program in a relatively high level language, each routine can be checked for functionality against a known standard. The closer the high level implementation matches the `ASM96` version, the more possible checkpoints there are between the two routines.

Once all of the program routines (modules) can be shown to work individually, the main program should work unless there is unwanted interaction between the modules. These interactions can be checked by verifying the inputs and outputs of each module. The assembly language locations to perform the program breaks can be retrieved by absolutely locating the main module. The other modules can be dynamically located by `RL96`.

The more interactive program modules are, the more difficult the program becomes to debug. This is especially true when multiple interrupts are occurring, and several of the interrupt routines are themselves interruptable. In these cases, it may be necessary to use debugging equipment with trace capability, like the `VLSiCE-96`. If this type of equipment is not available, then using I/O ports to indicate the entering and leaving of each routine may be useful. In this way it will be possible to watch the action of the program on an oscilloscope or logic analyzer. There are several places within this code that I/O port toggling has been used as an aid to debugging the program. These lines of code are marked "FOR INDICATION ONLY."

K	Fractional			dB	Decimal			Hexadecimal		
	REAL	IMAG	MAG <sup>2</sup>		REAL	IMAG	MAG <sup>2</sup>	REAL	IMAG	MAG <sup>2</sup>
0	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
1	0.0625	-1.2722	1.2738	38.225	1024	-20843	20868	400	AE95	5184
2	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
3	0.0625	-0.4213	0.4260	28.710	1024	-6903	6978	400	E509	1B42
4	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
5	0.0625	-0.2495	0.2572	24.329	1024	-4088	4214	400	F008	1076
6	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
7	0.0625	-0.1747	0.1855	21.491	1024	-2862	3039	400	F4D2	BDF
8	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
9	0.0625	-0.1321	0.1462	19.421	1024	-2165	2395	400	F78B	95B
10	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
11	0.0625	-0.1043	0.1216	17.820	1024	-1708	1992	400	F954	7C8
12	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
13	0.0625	-0.0843	0.1049	16.540	1024	-1381	1719	400	FA9B	6B7
14	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
15	0.0625	-0.0690	0.0931	15.499	1024	-1130	1525	400	FB96	5F5
16	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
17	0.0625	-0.0566	0.0844	14.645	1024	-928	1382	400	FC60	566
18	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
19	0.0625	-0.0464	0.0778	13.944	1024	-759	1275	400	FD09	4FB
20	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
21	0.0625	-0.0375	0.0729	13.374	1024	-614	1194	400	FD9A	4AA
22	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
23	0.0625	-0.0296	0.0691	12.918	1024	-484	1133	400	FE1C	46D
24	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
25	0.0625	-0.0224	0.0664	12.564	1024	-366	1088	400	FE92	440
26	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
27	0.0625	-0.0157	0.0644	12.305	1024	-256	1056	400	FF00	420
28	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
29	0.0625	-0.0093	0.0632	12.135	1024	-152	1035	400	FF68	40B
30	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
31	0.0625	-0.0031	0.0626	12.051	1024	-50	1025	400	FFCE	401

Figure 13. FFT Output for a Square Wave Input

## 9.0 ANALOG TO DIGITAL CONVERTER MODULE

The module presented in Listing 4 is a general purpose one which converts analog values under interrupt control and stores them in one of two buffers. These buffers

can then be downloaded to another buffer, such as the input buffer to the FFT program. During downloading, this module can convert the data into signed or unsigned formats, and fill a linear or a paired array. A paired array is like the one used in the FFT transform program. It requires N data points placed alternately in two arrays, one starting at zero and the other at N/2.

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SOURCE FILE: F2:A2DCON.A96

OBJECT FILE: F2:A2DCON.OBJ

CONTROL'S SPECIFIED IN INVOCATION COMMAND: NOSB

```

ERR LOC OBJECT          LINE  SOURCE STATEMENT
1  $pageLength(50)
2
3  A2D_Buffering_UTILITY  module stacksize(12)
4  ;
5  ; Intel Corporation, July 16, 1985
6  ; by Dave Ryan, Intel Applications Engineer
7
8  ; This utility fills a memory buffer with A/D conversion results. The
9  ; conversions are done under interrupt control, and are initiated when
10 ; A2D_BUFF_Util is called. The results of the conversions are placed
11 ; in one of two buffers, called BUFF0 and BUFF1.
12 ;
13 ; This utility provides options for the selection of the buffer lengths, data
14 ; format, sample period, conversion channel and time base. The utility also
15 ; has a download routine that will load either buffer into a register file
16 ; buffer. Output formats can also be chosen for the downloaded buffer. The
17 ; data can be formatted as signed or unsigned linear or paried arrays.
18
19 ; RUN-TIME OPTIONS
20
21 ; Rather than use the STACK to pass controls, this utility gets its directions
22 ; from 2 control words in memory. The utility expects that its control words
23 ; are valid at the time A2D_BUFF_Util is called and remain valid throughout
24 ; A/D interrupt executions and downloads. The control words are:
25
26 ; Sample_Period   ; WORD ; The time between samples in timer counts
27 ;                ;      ; where the timer used has been specified
28
29
30 ; Control_A2D     ; BYTE ; Control information for the utility:
31 ;                ;     ; BIT#
32 ;                ; 0-2 ; Channel Number
33 ;                ; 3   ; Signed Result/Unsigned Result#
34 ;                ; 4   ; Convert/Download#
35 ;                ; 5   ; BUFF1/BUFF0# for conversions
36 ;                ; 6   ; BUFF0/BUFF1# for downloads
37 ;                ; 7   ; Linear/Paired#
38 ;                ;     ; Converter BUSY/IDLE#
39
40
41 $EJECT

```

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```

ERR LOC OBJECT          SOURCE STATEMENT
-----
42      ;
43      ; The following is a table of equates that can be used to simplify the
44      ; bitiddling requirements. If you are not running conversions concurrently
45      ; with downloads, always LDR Control_A2D with the following command then
46      ; ORB Control_A2D with the channel number you wish to convert if you are
47      ; starting a conversion.
48      ;
49      ; Once the utility is called, care must be taken when Control_A2D is
50      ; modified. You can cause downloads to occur while conversions are running,
51      ; but you cannot start conversions during a download. To do this, ORB to the
52      ; control byte with the appropriate bits set. Do NOT change the BUFF bit or
53      ; the BUSY bit. Just set the download bit and set the data format bits to the
54      ; correct values.
55      ;
56      ; The BUFF bit has opposite definitions for conversions and downloads. This
57      ; allows conversions to be done into BUFF0 while downloads come from BUFF1, and
58      ; vice versa.
59      ;
60      ; A2D UTILITY COMMANDS
61      ;-----
62      con_b0 equ 00010000b;convert to BUFF0
63      con_b1 equ 00110000b; " " BUFF1
64      ;
65      dump_b0_i_u equ 01100000b; download BUFF0 as LINEAR UNSIGNED data
66      dump_b1_i_u equ 01000000b; " " " " " "
67      dump_b0_p_u equ 00100000b; " " BUFF0 " PAIRED " "
68      dump_b1_p_u equ 00000000b; " " BUFF1 " " " "
69      dump_b0_i_s equ 01101000b; download BUFF0 as LINEAR SIGNED data
70      dump_b1_i_s equ 01001000b; " " " " " "
71      dump_b0_p_s equ 00101000b; " " BUFF0 " PAIRED " "
72      dump_b1_p_s equ 00001000b; " " " " " "
73      ;-----
74      $eject

```

Listing 4—A to D Converter Routine (Continued)

```

75 ; SOURCE STATEMENT
76 ;
77 ; ASSEMBLY-TIME OPTIONS
78 ; The base addresses and length of each conversion buffer and the destination
79 ; buffer are DECLARED EXTERNAL in this utility. Other options such as selection
80 ; of the timer used as a timebase, the length of the buffer, and the effective
81 ; number of bits in the reported result are set at assembly time through use
82 ; of EQUATES in this module.
83 ;
84 ; The following parameters need to be provided at assembly or link time.
85 ; The buffer bases are declared EXTERNAL by this utility, while the buffer
86 ; length shift count and HSO commands are EQUATED.
87 ;
88 ; BUFF0_BASE ; The starting address of BUFF0
89 ; BUFF1_BASE ; The starting address of BUFF1
90 ; DEST_BUFF_BASE ; The starting address of the download
91 ; ; target buffer.
92 ;
93 ; BUFF_LENGTH ; The number of SAMPLES that each
94 ; ; buffer must hold. must be >1 and <256
95 ;
96 ; Shift_count ; The number of times that the conversion result is
97 ; ; to be shifted right from its natural left justified
98 ; ; position. Setting a shift count greater than 6 will
99 ; ; result in lost bits to the right. Rounding is NOT
100 ; ; done.
101 ;
102 ; CLOCK ; Specify as either TIMER1 or T2CLK. This is the
103 ; ; timebase used for conversions.
104 ;
105 ; Samples are stored as words in the buffers. The program stores
106 ; conversions linearly in BUFF0 and BUFF1, and linearly or paired in the
107 ; destination buffer as selected. If the download is to be paired, the first
108 ; sample is placed in location DEST_BUFF_BASE, the second sample is placed in
109 ; location (DEST_BUFF_BASE + BUFF_LENGTH), the third in (DEST_BUFF_BASE + 2),
110 ; the fourth in (DEST_BUFF_BASE + 2 + BUFF_LENGTH), etc.
111 ;
112 ;$ject
    
```

Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER    A2D\_BUFFERING\_UTILITY    02/18/86    PAGE    4

ERR LOC OBJECT    SOURCE STATEMENT

```

113 ;
114 ; NOTES ON EXECUTION
115 ;
116 ; When a utility call directs the initiation of a set of A2D conversions, the
117 ; first conversion is begun at approximately one sample time plus 50 state
118 ; times from when the utility was called. This assumes that no interrupts are
119 ; present.
120 ;
121 ; The conversion busy bit is set approximately 50 state times after a call
122 ; to the utility, if the convert bit was set in the A2D_Control byte. The
123 ; busy bit is cleared after all conversion results have been stored in the
124 ; result buffer designated (BUFF0 or BUFF1).
125 ;
126 ; Take great care in modifying the A2D_Control byte to do a download while
127 ; conversions are taking place. You can never download a buffer that is
128 ; being converted into. The results would be invalid.
129 $eject
    
```

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Listing 4—A to D Converter Routine (Continued)

```

MCS-96 MACRO ASSEMBLER      A2D_BUFFERING_UTILITY      02/18/86      PAGE      5
ERR LOC OBJECT
0000
130 LINE SOURCE STATEMENT
131 RSEG
132
133 EXTRN BUFFL_BASE, BUFFL_BASE, DEST_BUFF_BASE
134 EXTRN ad_command, ad_result_lo, ad_result_hi
135 EXTRN hso_command, hso_time, sp
136
137 BUFF_LENGTH EQU 64
138 Shift_Count EQU 1
139 CLOCK EQU TIMER1
140
141 ; set up hso commands for correct timer *****
142
143 TIMER1 equ 0AH
144 T2CLK equ 0CH
145
146 MASK equ (10h*CLOCK)AND(40h)
147
148 Start_A2D equ (00001111b)OR(MASK)
149 ;start a2d based on timer 1, no interrupt
150
151 HSO_0_Low equ (00000000b)OR(MASK)
152 ; make hso.0 low based on timer1 no interrupt
153
154 HSO_0_High equ (00100000b)OR(MASK)
155 ; make hso.0 hi based on timer1 no interrupt
156
157
158 ; set up storage *****
159
160 adudtemp0: DSW 1; temp register for download calls
161
162 aductemp0: DSW 1; temp registers for conversion calls
163 aductemp1: DSW 1
164 top_of_buffer: DSW 1
165 sample_count: DSB 1
166
167 Control_A2D: DSB 1; the byte that controls the utility execution
168 DForm equ 3 ; Signed/Unsigned#
169 Con_Dwn equ 4 ; Convert/Download#
170 B0_B1 equ 5 ; Buffl/Buff0# for conversions
171 ; Buff0/Buff1# for downloads
172 Lin_Far equ 6 ; Linear/Paired#
173 Busy equ 10000000B ; Bit 8
174 $eject

```

270189-58

Listing 4—A to D Converter Routine (Continued)



```

ERR LOC OBJECT          LINE  SOURCE STATEMENT
000A                   175
                           176 Sample_Period: DSW 1; the word that specifies the number of clock ticks
                           177 ; that elapse between each sample
                           178
                           179 PUBLIC Control_A2D, Sample_Period
                           180
                           181
                           182 OSEG
                           183
                           184 src_ptr: DSW 1; some overlayable temp registers
                           185 temp set src_ptr:WORD
                           186 dest_ptr: DSW 1
                           187 loop_count: DSW 1
                           188
                           189
                           190 CSEG at 2002h
                           191
                           192 PUBLIC A2D_DONE_Vector
                           193
                           194 DCW A2D_DONE_Vector
                           195
                           196
                           197 CSEG
                           198
                           199 PUBLIC A2D_BUFF_Ut11
                           200
                           201 Load_HSO_Command MACRO var ; Macro to load HSO
                           202
                           203 IDB hao_command,#var
                           204 LD hao_time,aductemp0
                           205 ENDM
                           206 $reject

```

Listing 4—A to D Converter Routine (Continued)

```

ERR LOC OBJECT          LINE SOURCE STATEMENT
0000                207 A2D_BUFF_Util:
0000 3C0962            208 Control_A2D, Con_Dwn, Convert ; Select convert or download
0003                209 Download:
0003 A1000000          210 JBS Control_A2D, B0_B1, Set_Data_Format
0007 350904            211 LD src_ptr,#BUFF1_BASE
000A                212 JBC Control_A2D, B0_B1, Set_Data_Format
000A                213 Download_BUFF0:
000A A1000000          214 LD src_ptr,#BUFF0_BASE
000E                215 Set_Data_Format:
000E A1000002          216 LD dest_ptr,#RST_BUFF_BASE ; Choose linear or paired
0012 B14004            217 LDB loop_count,#BUFF_LENGTH
0015 3E091D            218 JBS Control_A2D, Lin_Par, Linear_data_loop
0018 180104            219 PAIRED: SHRB loop_count,#1 ; The paired data routine uses 1/2
001B A20000            220 LD adudtemp0,[src_ptr]+ ; as many loops as the unpaired
001E C20200            221 ST adudtemp0,[dest_ptr] ; Move even word
0021 65400002          222 ADD dest_ptr,#BUFF_LENGTH ; Length = # of words = 1/2 # of bytes
0025 A20000            223 LD adudtemp0,[src_ptr]+ ; Move odd word
0028 C20200            224 ST adudtemp0,[dest_ptr]+
002B 69400002          225 SUB dest_ptr,#BUFF_LENGTH
002F E004E9            226 DJNZ loop_count, Paired_data_loop ; Loop until done
0032 280D              227 CALL Convert_Data
0034 F0                228 RET
0035                229 Linear_Data_loop:
0035 A20000            230 LD adudtemp0,[src_ptr]+ ; Move data linearly
0038 C20200            231 ST adudtemp0,[dest_ptr]+
003B E004F7            232 DJNZ loop_count, Linear_Data_loop ; Loop until done
003E 2801              233 CALL Convert_Data
0040 F0                234 RET
0040 F0                235 $eject
    
```

Listing 4—A to D Converter Routine (Continued)

```

ERR LOC OBJECT          LINE SOURCE STATEMENT
0041                                251 Convert_Data:
                                252 ; Convert the data in the destination buffer
0041 A1400004           R 253 LD Loop_Count,#BUFF_LENGTH
0045 A1000000           E 254 LD src_ptr,#DEST_BUFF_BASE
0049 A20000             R 255 LD adudtemp0,[src_ptr]
004C 710000             R 256 LD adudtemp0,#11000000b
004F 330909             R 257 ANDB Control_A2D,DForm,Unsigned_Result
0052                                260 Signed_Result:
0052 69E07F00           R 261 SUB adudtemp0,#7fe0H
0056 040100             R 262 SHRA adudtemp0,#Shift_Count
0059 2003               R 263 BR Replace_Sample
005B                                265 Unsigned_Result:
005B 080100             R 266 SHR adudtemp0,#Shift_Count
005E                                268 Replace_Sample:
005E C20000             R 269 ST adudtemp0,[src_ptr]+
0061 E004E5             R 270 DJNZ Loop_Count,Again ; Loop until done
0064 FU                R 271 RET
0065                                274 Convert:
0065                                275 ;; Prepare to Start Conversions
0065                                276 PUSHF
0065 F2                R 277 ORB Control_A2D,#Busy ; set converter busy bit
0066 918009            R 278 LD sample_count,#BUFF_LENGTH - 1
0069 B13F08            R 281 LD top_of_buffer,#BUFFO_BASE
006C A1000006          E 282 LD aductemp1,#(BUFFO_BASE + 2*BUFF_LENGTH)
0070 A1800004          E 284 LD Control_A2D,B0_B1,Start_Conversions
0074 350908            R 285 LD top_of_buffer,#BUFF1_BASE
0077 A1000006          E 287 LD aductemp1,#(BUFF1_BASE + 2*BUFF_LENGTH)
007B A1800004          E 288 $reject
0089                                289

```

Listing 4—A to D Converter Routine (Continued)

```

MCS-96 MACRO ASSEMBLER      A2D_BUFFERING_UTILITY      02/18/86      PAGE      9
ERR LOC OBJECT                LINE  SOURCE STATEMENT
007F                                290  Start_Conversions:
007F 51070900      E      291  ANDB  ad_command,Control_A2D,#00000111b ;load channel number
0083 440A0A02      R      292  ADD   aductemp0,CLOCK,Sample_Period ;start first conversion
;one sample time from
;now
293
294
295
296
297
298
299  Load_HSO_Command Start_A2D      ; Start A2D at Time=aductemp0
300
301  POP   temp                        ; get a copy of the psw
302
303  Load_HSO_Command HSO_0_high      ; set hso.0 high at conversion
; start time for external S/H
304
305  OR    temp,#202h                  ; enable a2d interrupts
306
307
308
309  ADD   aductemp0,Sample_Period      ; start second conversion one
; sample time from the first
310
311  Load_HSO_Command Start_A2D      ; put psw back on stack
312
313  PUSH  temp                        ; lower hso.0 for external S/H
314
315  Load_HSO_Command HSO_0_low
316
317  POPF
318  RET
319
320
321
322
323
324
325
326
327
328
329
330
331  $reject

```

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Listing 4—A to D Converter Routine (Continued)

```

ERR LOC OBJECT          A2D_BUFFERING_UTILITY          SOURCE STATEMENT
00AC          CSSEG
332
333
334          A2D_DONE_Vector:          ; A/D INTERRUPT ROUTINE
00AC F2          PUSHF
335
336
00AD C60600          STB          ad_result_lo,[top_of_buffer]+
0080 C60600          STB          ad_result_hi,[top_of_buffer]+
0083 51070900          ANDB         ad_command,Control_A2D,#00000111b          ;load channel number
00B7 E00809          R          DJNZ         sample_count, Sample_Again
00BA 1708          R          INCB          top_of_buffer,aductempl          ; Check top of buffer
343
344          CMP          top_of_buffer,aductempl
008C 860406          R          BE          Top_of_buffers
00BF DF26          R          POPF
00C1 F3          R          RET
00C2 F0          R
347
348
00C3          Sample_Again:
00C3 640A02          R          ADD          aductemp0,Sample_Period
00C6 860406          R          CMP          top_of_buffer,aductempl          ; Set next sample time
351
352          Load_HSO_Command Start_A2D          ; Check top of buffer
353
357          JBC          sample_count,0,Make_HSO_High          ; for later jump
358
359          Make_HSO_low:
00D2          nop
00D2 FD          R          Load_HSO_Command HSO_0_Low          ; wait 8 states after HSO load
361
362          BE          Top_of_buffers          ; Load for change of HSO to trigger S/H
00D9 DF0C          R
00DB F3          R          POPF
00DC F0          R          RET
368
369
00DD          Make_HSO_high:
370
371          Load_HSO_Command HSO_0_High          ; Load for change of HSO to trigger S/H
372
376          BE          Top_of_buffers
00E3 DF02          R
00E5 F3          R          POPF
00E6 F0          R          RET
377
378
00E7          Top_of_buffers:
00E7 717F09          R          ANDB         Control_A2D,#NOT(busy)          ; Clear converter BUSY bit
00EA F3          R          POPF
00EB F0          R          RET
383
384
00EC          END
385

```

ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

Listing 4—A to D Converter Routine (Continued)

The listing contains a fairly complete description of what the program does. The block by block operations are shown below:

Lines 1-198 describe the program, declare the variables and set up equates. Several of these variables are declared as overlayable, so the user needs to be careful if using this module for other than the FFT program.

Lines 205-210 declare a macro which is used to load the HSO unit. This will be used repeatedly through the code.

Lines 212-253 determine whether a conversion or download has been requested. If a download has been requested, the data is downloaded to the destination array as either paired or linear data. Paired data has been described earlier.

Lines 255-278 contain a subroutine which converts the destination array to either signed or unsigned numbers. The numbers are also shifted right to provide the desired full-scale value as requested by `SHIFT__COUNT`.

Lines 279-334 initialize the conversion routine. `HSO_0` is toggled with the start of each routine so that an external sample and hold can be used. The instructions in lines 308, 316, and 326 have been interweaved with the `Load__HSO__Commands` to provide the required 8 state delays between HSO loadings. If this was not done, NOPs would have been needed. It is easier to understand the code if these lines are thought of as being gathered at line 326.

Lines 337-353 are the actual A/D interrupt routine. The A/D results are placed BYTE by BYTE on the buffer, the A/D is reloaded, and then the number of samples taken is compared to the number needed. Note that the A/D command register needs to be reloaded even if the channel does not change. `INCB` on line 348 is used to insure that the `DJNZ` falls through on the next pass (if `sample__count` is not reset).

Lines 355-396 complete the routine. The HSO is set up to trigger the next conversion and provide the `HSO_0` toggle for an external sample and hold. Once again, the time between consecutive loads of the HSO is 8 states minimum. Note that this section of code has been optimized for speed by reducing branches to an absolute minimum and duplicating code where needed.

This concludes the description of the A to D buffer module. In the FFT program, this module is run, then the FFT transform module, then the plot module. This allows variables to be overlaid, saving RAM space. The time cost for this is not bad, considering the printer is the limiting factor in these conversions. If more RAM

was provided, and the FFT was run with its data in external RAM, this module could be run simultaneously with the other modules.

## 10.0 DATA PLOTTING MODULE

The plot module is relatively straight-forward, and is shown in Listing 5. After the declarations, which include overlayable registers, an initialization routine is listed. This separately called routine sets up the serial port on the 8096 to talk to the printer. In this case, the port has to be set for 300 baud.

A console out routine follows. This routine can also be called by any program, but it is used only by the plot routine in this example. The write to port 1 is used to trace the program flow. The character to be output is passed to this routine on the stack. This conforms to PLM-96 requirements.

Since all stack operations on the 8096 are 16-bits wide, a multiple character feature has been added to the console out routine. If the high byte it receives is non-zero, the ASCII character in that byte is printed after the character in the low byte. If the high byte has a value between 128 and 255, the character in the low byte is repeated the number of times indicated by the least significant 7 bits of the high byte.

The print decimal number routine is next. It is called with two words on the stack. The first word is the unsigned value to be printed. The second byte contains information on the number of places to be printed and zero and blank suppression. This routine is not overflow-proof. The user must declare a sufficient number of places to be printed for all possible numbers.

The `DRAW__GRAPH` routine provides the plot. It first sends a series of carriage return, line feeds (CRLFs) to clear the printer and provides a margin on the paper. Each row is started with the row number, 2 spaces, and a "+". Asterisks are then plotted until

Number of asterisks > FFT Value / `PLOT__RES`

Recall that `PLOT__RES` is a variable set by the main program. When the number of asterisks hits the desired value, the value of the line is printed. If the Decibel mode is selected, the line value is divided by 512 and printed in integer + decimal part form, followed by "dB". If the number of asterisks reaches `PLOT__MAX`, no value is printed. The next line is then started. A line with only a "!" is printed before the next plot line to provide a more aesthetic display on the printer. If a CRT was used, this extra line would probably not be wanted.

MCS-96 MACRO ASSEMBLER PLOT\_SERIAL  
 SERIES-III MCS-96 MACRO ASSEMBLER, V1.0  
 SOURCE FILE: :F2:PLOTSP.A96  
 OBJECT FILE: :F2:PLOTSP.OBJ  
 CONTROLS SPECIFIED IN INVOCATION COMMAND: NOSB

```

ERR LOC OBJECT LINE SOURCE STATEMENT
1 1 $pageLength(50)
2 2
3 3 PLOT_SERIAL MODULE STACKSIZE (6)
4 4
5 5 ; Intel Corporation, December 12, 1985
6 6 ; by Ira Horden, MCO Applications
7 7
8 8 ; This program produces a plot on serially connected printer. The
9 9 ; magnitude of each of the 32 input values is plotted horizontally, with one
10 10 ; '!' followed by a linefeed between each plot line. Each plot line starts
11 11 ; with a "!" and the entire plot begins with 3 line feeds and ends with a form
12 12 ; feed. The values to be plotted are 32 unsigned words based at the externally
13 13 ; defined pointer PLOT_IN.
14 14
15 15 ; The routine INIT_OUTPUT must be run to set up the serial port when the
16 16 ; system is turned on. CON_OUT can be used by a program to output to the
17 17 ; serial port. DRAW_GRAPH is the routine that automatically plots the data.
18 18
19 19 ; Sizing of the graph can be done using PLOT_RES, which determines how many
20 20 ; units are needed for each dot, and PLOT_MAX, which is the maximum value the
21 21 ; program will be passed. Note that (PLOT_MAX/PLOT_RES) defines the maximum
22 22 ; number of columns the routine will print.
23 23 ;
24 24 RSEG
25 25
26 26 EXTRN ioc1, baud_reg, spcon, spstat, sbuf, port1
27 27 EXTRN zero, ax, bx, cx, dx, FFT_MODE
28 28 spump: dsb 1
29 29
30 30 OSEG at 24H
31 31 value: ds1 1
32 32 divisor: ds1 1
33 33 xptr: dsw 1
34 34 yptr: dsw 1
35 35 xval: dsw 1
36 36 log_val: dsw 1
37 37
38 38 DSEG
39 39 EXTRN PLOT_IN
40 40
41 41 $eject
    
```

Listing 5—The Plot Module

```

MCS-86 MACRO ASSEMBLER      PLOT_SERIAL
ERR LOC OBJECT                LINE   SOURCE STATEMENT
2500                          42
43      CSEG at 2500H          43      ;;;;          PROGRAM MODULE BEGINS
44      PUBLIC INIT_OUTPUT, CON_OUT, DRAW_GRAPH
45      EXTRN PLOT_RES, PLOT_RES_2, PLOT_MAX
46      INIT_OUTPUT:          46      ; INITIALIZE SERIAL PORT
47      ;
48      ;
49      ;
50      ;
51      ;
52      ;
53      ;
54      ;
55      ;
56      ;
57      ;
58      ;
59      ;
60      ;
61      ;
62      ;
63      ;
64      ;
65      ;

```

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Listing 5—The Plot Module (Continued)



MCS-96 ERR LOC	MACRO OBJECT	ASSEMBLER	PLOT_SERIAL	LINE	SOURCE STATEMENT
				66	
				67	
				68	
				69	
				70	
				71	
				72	
				73	
				74	
				75	
				76	
				77	
				78	CON_OUT:
2510	CC00			79	pop ax ; cx contains the calling address
2512	CC00			80	pop dx ; If bit 7 is set print one character
2514	3F011C			81	jbs dx+1,7,onechr ; if highbyte=0 print one character
2517	960001			82	cmpb dx+1,zero
251A	DF17			83	je onechr
251C	900000			84	orb sptmp,spstat ; wait for TI
251F	3500FA			86	jbc sptmp,5,twochr ; clear TI--tmp
2522	71DF00			87	andb sptmp,#11011111b ; remove possible false TI
2525	900000			88	orb zero,spstat
2528	B00000			89	lcb sbuf,dx
2529	B00100			90	lcb dx,dx+1 ; Load second character
252E	1101			92	clrb dx+1 ; clear count byte
2530	717F00			93	andb dx,#07FH ; mask MSB
2533	1701			94	onechr: dx+1
2535	717F01			95	andb dx+1,#7FH ; wait for TI
2538	900000			97	orb sptmp,spstat ; wait for TI
253B	3500FA			98	jbc sptmp,5,wait1 ; clear TI--tmp
253E	71DF00			99	andb sptmp,#11011111b ; remove possible false TI
2541	900000			100	orb zero,spstat
2544	B00000			101	lcb sbuf,dx
2547	E001EE			102	dx+1,wait1
254A	E300			103	BR [ax] ; Effectively a RET
				105	
				106	\$eject

-----  
 CONSOLE OUT ROUTINE  
 -----

Call with a word parameter on stack. The low byte has the character to be sent. If the high byte has a value between 81H and 8FEH, the character is repeated 1 to 126 times respectively. One repeat means that the character will be printed 2 times. If the high byte contains a value between 1 and 7FH, the character represented by that value will be printed after the character in the low byte. If the high byte contains a value of zero only the low byte will be printed.

```

107 LINE
108
109
110
111
112
113
114
115
116
117
118
119
120
121
122
123
124
125
126
127
128
129
130
131
132
133
134
135
136
137
138
139
140
141
142
143
144
145
146
147
148
149
150
151
152
153
254C
254C
254E
2550
2553
2556
255A
255A
255C
255F
2562
2565
2567
256A
256A
256C
256E
2570
2574
2576
2579
257D
2581
2583
2585
2588
258A
258E
2591
2593
2593
2596
2596

; Send decimal number to CON_OUT
; bx is mode byte, bx+1 is divisor pointer
; dx, bx+1
; divisor, divtab[dx]
; value
; value+2
; value, divisor
; bx,0,chr_ok
; value,zero
; non_0
; Value is zero
; jump if value is non zero
; Print space instead of 0
; If in rightmost position print 0
; Do not print space if bit is set
; 0F0H+30H = 20H = space
; chr_ok
; Set flag so 0's will be printed
; 30h + n = 0 to 9 ascii
; send least sig seven bits, clear upper word
; value
; con_out
; value,value+2
; load value with remainder
; clr
; divisor+2
; divu
; divisor,#10
; divisor,zero
; div_loop
; [cx]
; Number of places for result
; 0, 1, 10, 100, 1000, 10000 ; divisor table - 10**n

```

Listing 5—The Plot Module (Continued)

```

ERR LOC OBJECT SOURCE STATEMENT
LINE
154
155
156
157
158          ; Graph drawing routine
159          DRAW_GRAPH:  #0dh
160          call  con_out
161          push  #820AH
162          call  con_out
163          push  #00
164          call  con_out
165
166          clr  xptr
167          clr  xval
168
169          NMT_ROW:
170          push #0A0DH
171          call con_out
172          push #00H
173          call con_out
174
175          push # (0A00H or 0010b)
176          call PRINT_NUM
177
178          push #2020H
179          call con_out
180          push #2BH
181          call con_out
182
183          ld  yptr, #PLOT_RES_2
184          ; PLOT_RES_2 = PLOT_RES/2
185          ; PLOT_RES is defined 7 lines down
186          ; Next Column
187          yptr, PLOT_IN[xptr]
188          PRT_NUM
189          PRT_MK:
190          push #2AH
191          call con_out
192          INC_CNT:
193          add  yptr, #PLOT_RES
194          ; PLOT_RES = number of inputs per output point
195          cmp  yptr, #PLOT_MAX
196          ; PLOT_max = maximum line length
197          jnh nxt_col
198          br  NMTLN
199          $eject

```

Listing 5—The Plot Module (Continued)

ERR	LOC	MACRO	ASSEMBLER	PLOT_SERIAL	LINE	SOURCE STATEMENT
					198	
	258C				199	
	258C	8900002E		E	200	PFT_NUM: Yptr,#PLOT_RES_2 ; If value is less than minimum needed
	25F0	DF49			201	be NNTLN ; for a plot, do not print value
	25F2	C92020			202	push #2020H ; print 2 spaces then value
	25F5	2F19			204	call con_out
	25F7	3B0008		E	205	JBS PFT_MODE,3,db_mode
	25FA	C82D0000		E	207	norm_mode: ;
	25FF	C9000A			208	push PLOT_IN[xptr] ; suppress all zeros
	2601	2F49			209	push #(0A00H or 0000B)
	2603	2036			210	call PRINT_NUM
	2605	A32D00002E		E	211	BR NNTLN
	260A	08012E		E	212	db_mode: ;
	260D	AC2F00			213	ld yptr,plot_in[xptr] ; PLOT_IN = 512*10LOG(x)
	2610	C800		E	214	shr yptr,#1 ; yptr=286 * 10LOG(x)
	2612	C9020A			215	ldbze ax,yptr+1 ; ax= 10LOG(x) = yptr/256
	2615	2F35			217	push ax ; Print AX
	2617	C92E00			218	call PRINT_NUM ; suppress all but rightmost zero
	261A	2EF4			220	push #2EH ; Decimal point
	261C	E02E01		E	221	call con_out
	261F	1100		E	222	ldb ax+1,yptr ; high byte of ax = fractional portion of 10LOG(x)
	2621	6D860300		E	224	cirb ax ;
	2625	370102		E	225	mulu ax,#3E6H ; ax,#3E6H
	2628	0700		E	227	inc dx ; if ax=FF00H then ax+2 now = 998 decimal
	262A	C800		E	229	dx ; round value up
	262C	C90106			230	dx ; dx=ax+2
	262F	2F1B			231	call Print_num ; #(800H or 0001B)
	2631	C92000			232	push #20H ; space
	2634	2EDA			233	call con_out
	2636	C96442			234	push #4264H ; "dB"
	2639	2ED5			235	call con_out
	263A				237	
	263B				238	
	263C				239	\$eject

Listing 5—The Plot Module (Continued)

```

ERR LOC OBJECT          LINE SOURCE STATEMENT
240
241
242          #0A0DH      ; Setup for next line
243          CON OUT    ; CRLF
244          #00H       ; nul
245          CON OUT    ; 7 spaces
246          #8620H    ; 7 spaces
247          CON OUT    ; !
248          #21H      ; !
249          con_out   ;
250
251          xval       ; Start printing next row
252          xptr,#2    ;
253          add        ;
254          cmp        ;
255          blt_row    ;
256          Done:     ;
257          CON OUT   ; CRLF ; Form feed for next graph
258          #0C00H    ;
259          con_out   ; null,FF
260          RET
261
262          END
ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

```

Listing 5—The Plot Module (Continued)

At the end of the plot, a form feed is given to set the printer up for the next graph. Our printer would frequently miss the character after a CRLF. To solve this problem, a null (ASCII 0) is sent after every CRLF to make sure the printer is ready for the next line. This has been found to be a problem with many devices running at close to their maximum capacity, and the nulls work well to solve it.

With the plot completed, the program begins to run again by taking another set of A to D samples.

## 11.0 USING THE FFT PROGRAM

The program can be used with either real or tabled data. If real data is used, the signal is applied to analog channel 1. The program as written performs A/D samples at 100 microsecond intervals, collecting the 64 samples in 6.4 milliseconds. This sets the sampling window frequency at 156 Hz. If tabled data is used, 64 words of data should be placed in the location pointed to by DATA0 in the TABLE\_LOAD routine of the Main Module.

Program control is specified by FFT\_MODE which is loaded in the main module. Also within the main module are settings which control the A to D buffer routine and the Plot routine. The intention was to have only one module to change and recompile to vary parameters in the entire program.

The program modules are set up to run one-at-a-time so that the code would be easy to understand. Additionally, the Plot routine takes so long relative to the other sections, that it doesn't pay to try to overlap code sections. If this code were to be converted to run a process instead of print a graph, it might be worthwhile to run the FFT and the A/D routines at the same time.

If the goal of a modified program is to have the highest frequency sampling possible, it might be desirable to streamline the A/D section and run it without interruption. When the A to D routine was complete the FFT routine could be started. The reasoning behind this is that at the fastest A/D speeds the processor will be almost completely tied up processing the A/D information and storing it away. Using an interrupt based A/D routine would slow things down.

A set of programs which will perform a FFT has been presented in this application note. These programs are available from the INSITE users library as program CA-26. More importantly, dozens of programing examples have been made available, making it easier to get started with the 8096. Examples of how to use the hardware on the 8096 have already appeared in AP-248, "Using The 8096". These two applications notes form a good base for the understanding of MCS-96 microcontroller based design.

## 12.0 APPENDIX A - MATRICES

Matrices are a convenient way to express groups of equations. Consider the complex discrete Fourier Transform in equation 9, with  $N = 4$ .

$$Y_n = \sum_{k=0}^3 X(k) W^{nk} \quad n = 0, 1, 2, 3$$

This can be expanded to

$$\begin{aligned} Y(0) &= X(0) W^0 + X(1) W^0 + X(2) W^0 + X(3) W^0 \\ Y(1) &= X(0) W^0 + X(1) W^1 + X(2) W^2 + X(3) W^3 \\ Y(2) &= X(0) W^0 + X(1) W^2 + X(2) W^4 + X(3) W^6 \\ Y(3) &= X(0) W^0 + X(1) W^3 + X(2) W^6 + X(3) W^9 \end{aligned}$$

In matrix notation, this is shown as

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} W^0 & W^0 & W^0 & W^0 \\ W^0 & W^1 & W^2 & W^3 \\ W^0 & W^2 & W^4 & W^6 \\ W^0 & W^3 & W^6 & W^9 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

The first step to simplifying this is to reduce the center matrix. Recalling that

$$W^N = W^N \text{ MOD } N \quad \text{and} \quad W^0 = 1$$

The matrix can be reduced to have less non-trivial multiplications.

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & W^1 & W^2 & W^3 \\ 1 & W^2 & W^0 & W^2 \\ 1 & W^3 & W^2 & W^1 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

The square matrix can be factored into

$$\begin{bmatrix} Y(0) \\ Y(2) \\ Y(1) \\ Y(3) \end{bmatrix} = \begin{bmatrix} 1 & W^0 & 0 & 0 \\ 1 & W^2 & 0 & 0 \\ 0 & 0 & 1 & W^1 \\ 0 & 0 & 1 & W^3 \end{bmatrix} \begin{bmatrix} 1 & 0 & W^0 & 0 \\ 0 & 1 & 0 & W^0 \\ 1 & 0 & W^2 & 0 \\ 0 & 1 & 0 & W^2 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

For this equation to work, the  $Y(1)$  and  $Y(2)$  terms need to be swapped, as shown above. This procedure is a Bit Reversal, as described in the text.

Multiplying the two rightmost matrices results in

$$\begin{aligned} &X(0) + X(2) W^0 \\ &X(1) + X(3) W^0 \quad \text{requiring 4 complex multiplications} \\ &X(0) + X(2) W^3 \quad \text{\& 4 complex additions} \\ &X(1) + X(3) W^2 \end{aligned}$$

Noting that  $W^0 = -W^2$ , 2 of the complex multiplications can be eliminated, with the following results

$$\begin{aligned} &X(0) + X(2) W^0 \\ &X(1) + X(3) W^0 \quad \text{requiring 2 complex multiplications} \\ &X(0) - X(2) W^0 \quad \text{and 4 complex additions} \\ &X(1) - X(3) W^0 \end{aligned}$$

Since  $W^1 = -W^3$ , a similar result occurs when this vector is multiplied by the remaining square matrix. The resulting equations are:

$$\begin{aligned} Y(0) &= (X(0) + X(2) W^0) + W^0 (X(0) + X(3) W^0) \\ Y(2) &= (X(0) + X(2) W^0) - W^0 (X(1) + X(3) W^0) \\ Y(1) &= (X(0) - X(2) W^0) + W^1 (X(1) - X(3) W^0) \\ Y(3) &= (X(0) - X(2) W^0) - W^1 (X(1) - X(3) W^0) \end{aligned}$$

The number of complex multiplications required is 4, as compared with 16 for the unfactored matrix.

In general, the FFT requires

$$\frac{N * \text{EXPONENT}}{2} \text{ complex multiplications}$$

and

$$N * \text{EXPONENT} \text{ complex additions}$$

where

$$\text{EXPONENT} = \text{Log}_2 N$$

A standard Fourier Transform requires

$$N^2 \text{ complex multiplications}$$

and

$$N(N-1) \text{ complex additions}$$





## 13.0 APPENDIX B - PLOTS

The following plots are examples of output from the FFT program. These plots were generated using tabulated data, but very similar plots have also been made using the analog input module. Typically, a plot made using the analog input module will not show quite as much power at each frequency and will show a positive value for the DC component. This is because it is difficult to get exactly a full-scale analog input with no DC offset.

Plot 1 is a Magnitude plot of a square wave of period  $NT$ .

Plot 2 is the same data plotted in dB. Note how the dB plot enhances the difference in the small signal values at the high frequencies.

Plot 3 shows the windowed version of this data. Note that the widening of the bins due to windowing shows energy in the even harmonics that is not actually present. For data of this type a different window other than Hanning would normally be used. Many window types are available, the selection of which can be determined by the type of data to be plotted.<sup>3</sup>

Plot 4 shows a sine wave of period  $NT/7$  or frequency  $7/NT$ .

Plot 5 shows the same input with windowing. Note the signal shown in bins 6 and 8.

Plot 6 shows a sine wave of period  $NT/7.5$ . Note the noise caused by the discontinuity as discussed earlier.

Plot 7 uses windowing on the data used for plot 6. Note the cleaner appearance.

Plot 8 shows a sine wave input of magnitude 0.707 and period  $NT/7.5$ .

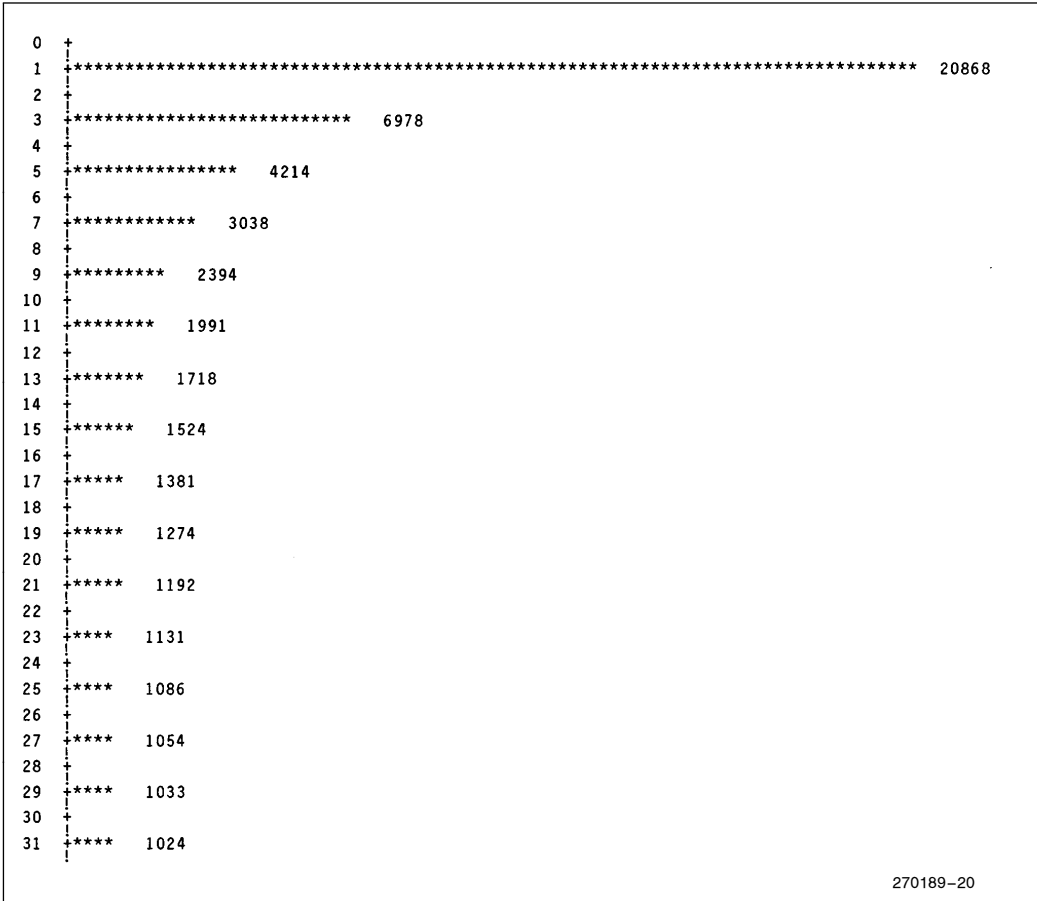
Plot 9 shows same input with windowing.

Plot 10 shows a sine wave of magnitude  $0.707/16$  and period  $NT/11$ .

Plot 11 shows the same input with windowing. Note that there is no power shown in bins 10 and 12. This is because at 6 dB down from 3 dB they are nearly equal to zero.

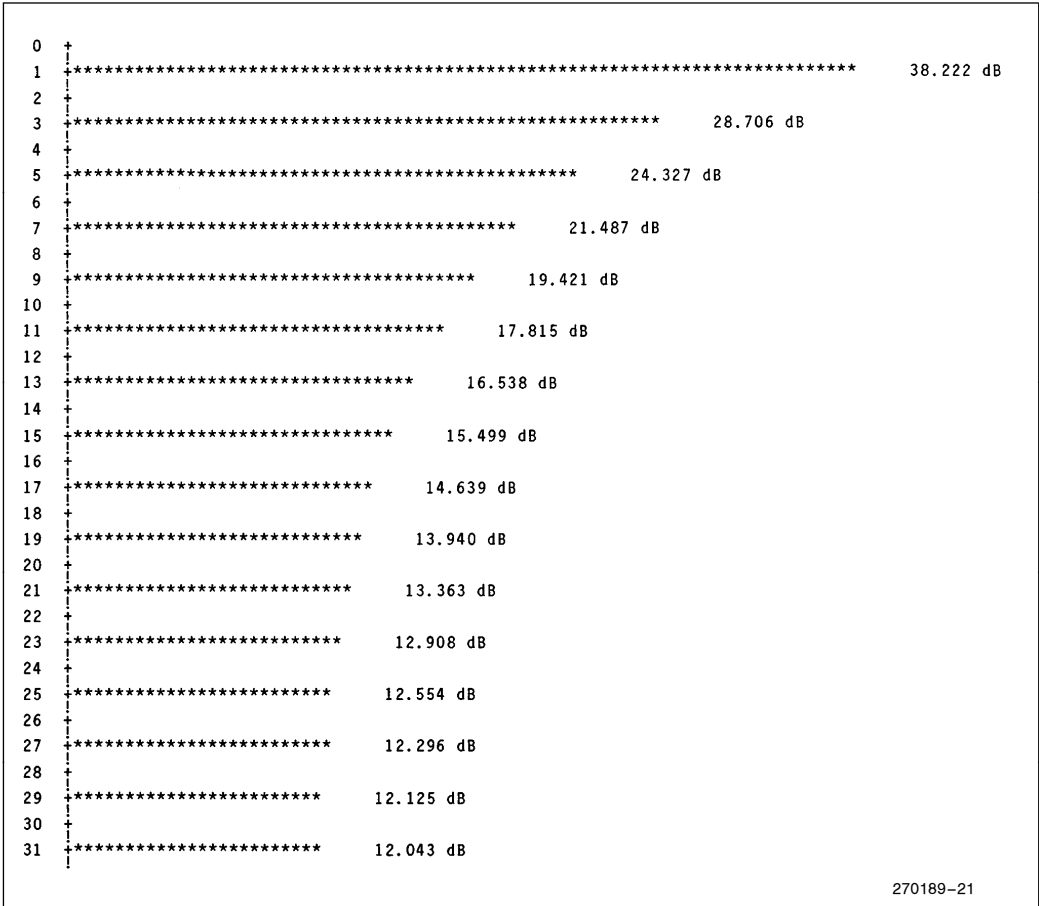
Plot 12 uses the sum of the signals for plots 8 and 10 as inputs. Note that the component at period  $NT/11$  is almost hidden.

Plot 13 uses the same signal as plot 12 but applies windowing. Now the period component at  $NT/11$  can easily be seen. The Hanning window works well in this case to separate the signal from the leakage. If the signals were closer together the Hanning window may not have worked and another window may have been needed.

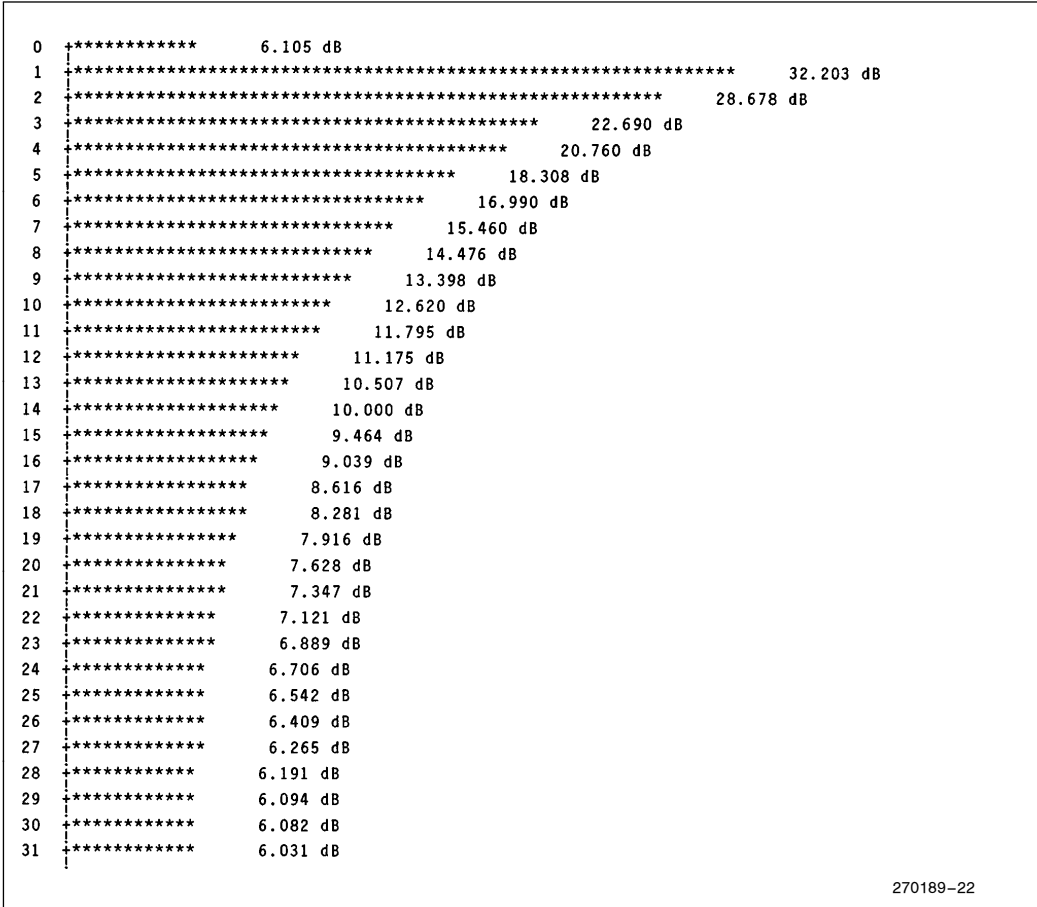


270189-20

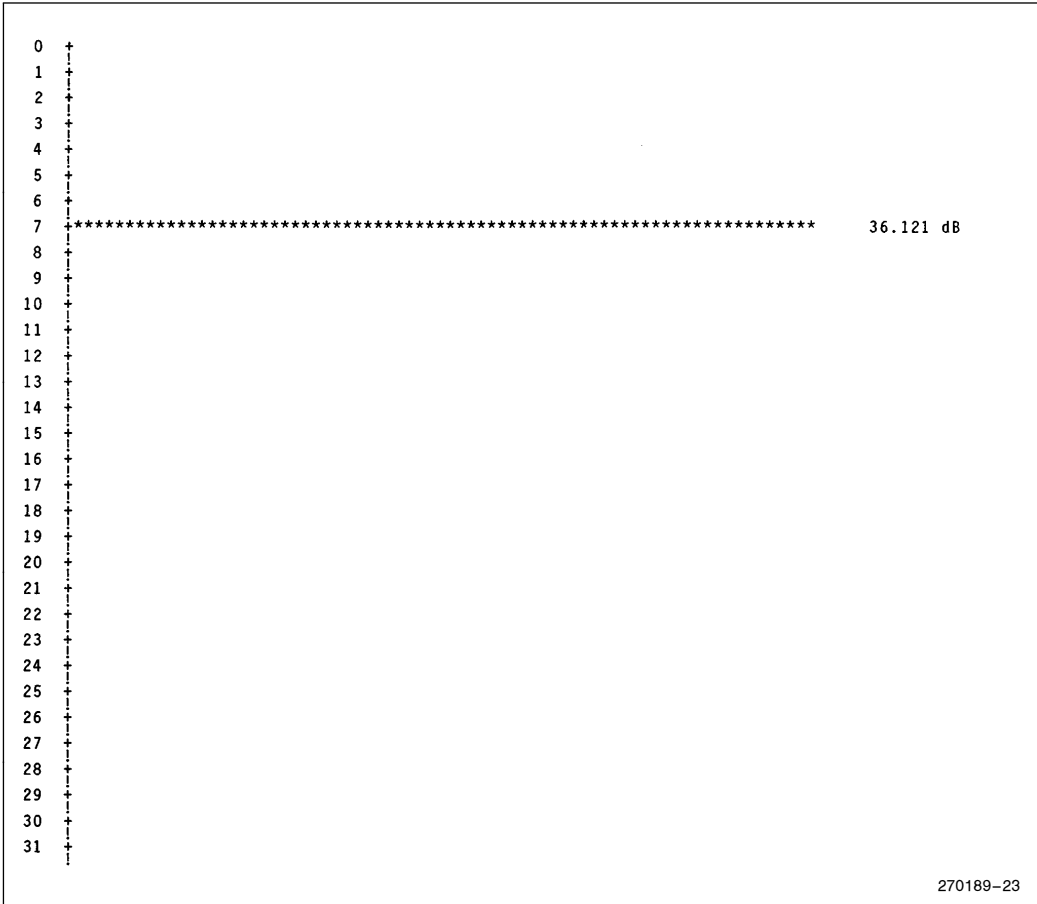
Plot 1—Magnitude Plot of Squarewave



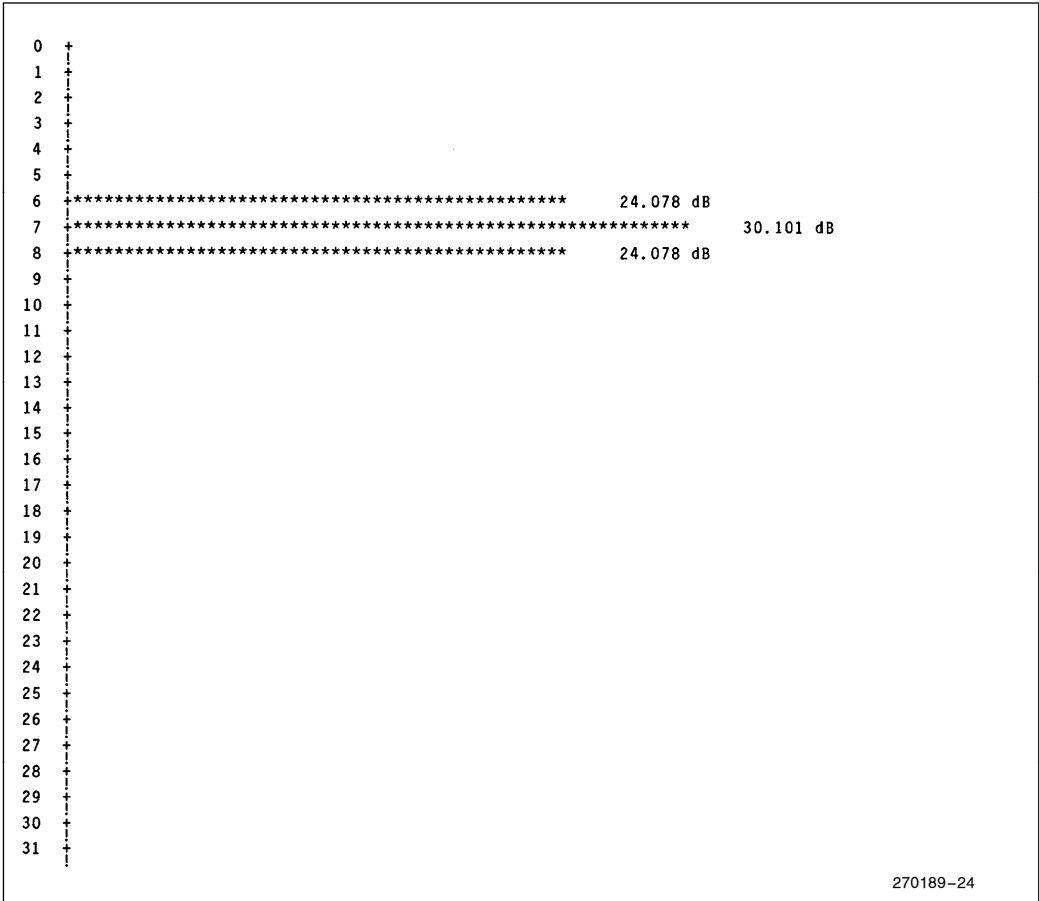
Plot 2—Decibel Plot of Squarewave



Plot 3—Plot of Squarewave with Window



Plot 4—Sin (7.0X) without Window



Plot 5—Sin (7.0X) with Window

270189-24

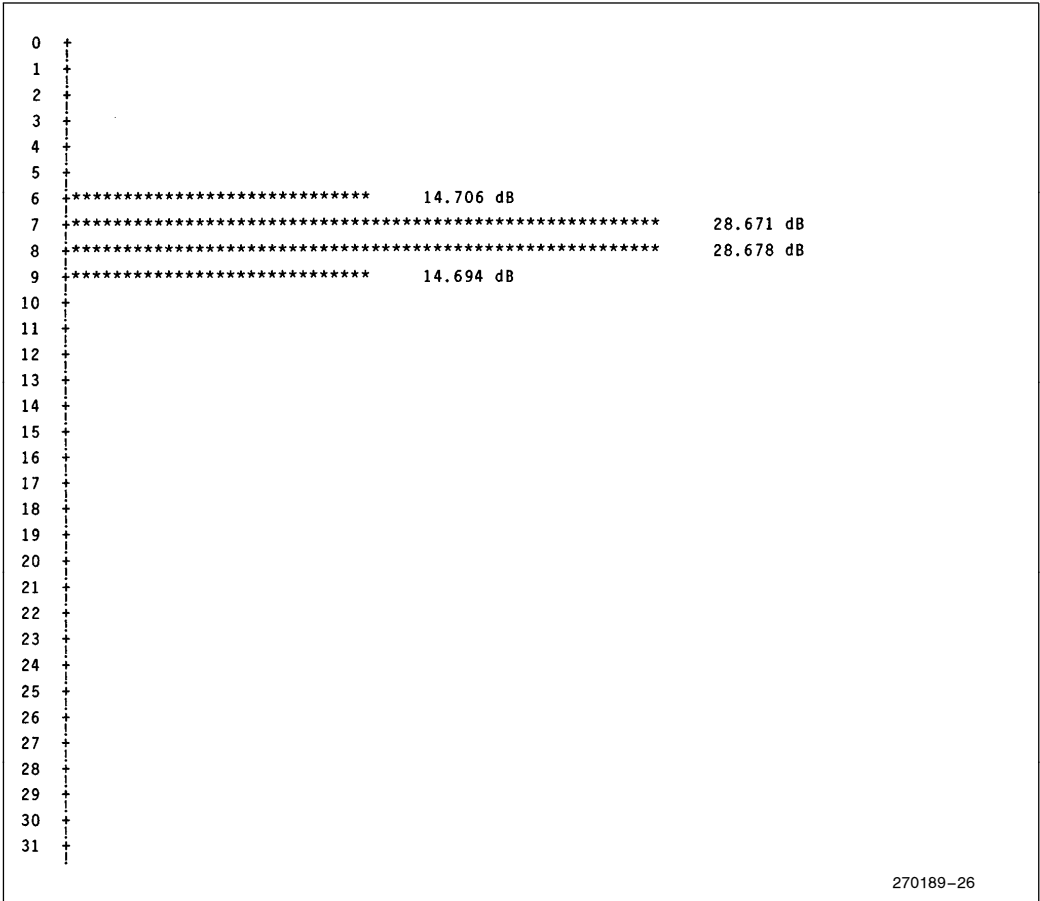
```

0 +***** 14.265 dB
1 +***** 14.444 dB
2 +***** 14.943 dB
3 +***** 15.865 dB
4 +***** 17.308 dB
5 +***** 19.569 dB
6 +***** 23.421 dB
7 +***** 32.441 dB
8 +***** 31.971 dB
9 +***** 22.012 dB
10 +***** 17.199 dB
11 +***** 13.943 dB
12 +***** 11.472 dB
13 +***** 9.483 dB
14 +***** 7.819 dB
15 +***** 6.402 dB
16 +***** 5.164 dB
17 +***** 4.090 dB
18 +***** 3.152 dB
19 +***** 2.308 dB
20 +*** 1.546 dB
21 +** 0.901 dB
22 +* 0.300 dB
23 +
24 +
25 +
26 +
27 +
28 +
29 +
30 +
31 +

```

270189-25

Plot 6—Sin (7.5X) without Window



270189-26

Plot 7—Sin (7.5X) with Window



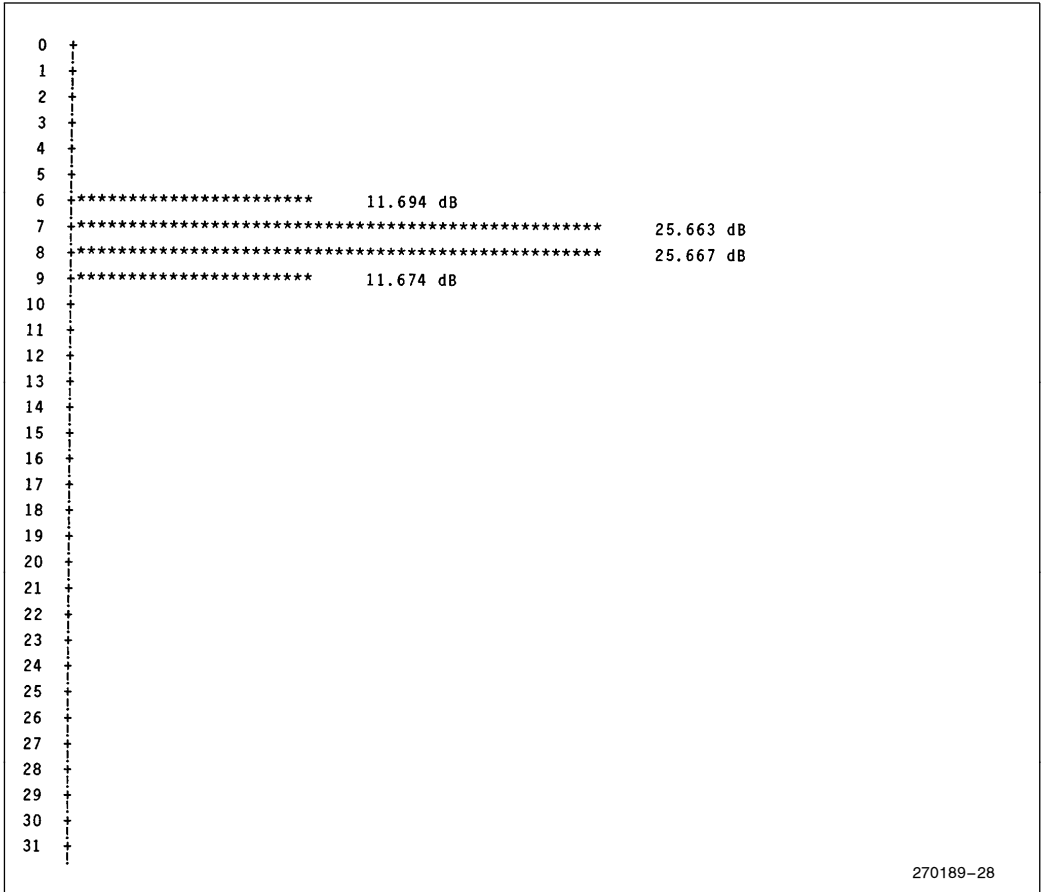
```

0 +***** 11.242 dB
1 -***** 11.417 dB
2 +***** 11.936 dB
3 +***** 12.846 dB
4 +***** 14.296 dB
5 +***** 16.561 dB
6 +***** 20.409 dB
7 +***** 29.425 dB
8 +***** 28.959 dB
9 +***** 18.994 dB
10 +***** 14.187 dB
11 +***** 10.936 dB
12 +***** 8.472 dB
13 +***** 6.468 dB
14 +***** 4.819 dB
15 +***** 3.382 dB
16 +**** 2.152 dB
17 +** 1.082 dB
18 +
19 +
20 +
21 +
22 +
23 +
24 +
25 +
26 +
27 +
28 +
29 +
30 +
31 +

```

270189-27

Plot 8—0.707 \* Sin (7.5X) without Window



Plot 9—0.707 \* Sin (7.5X) with Window

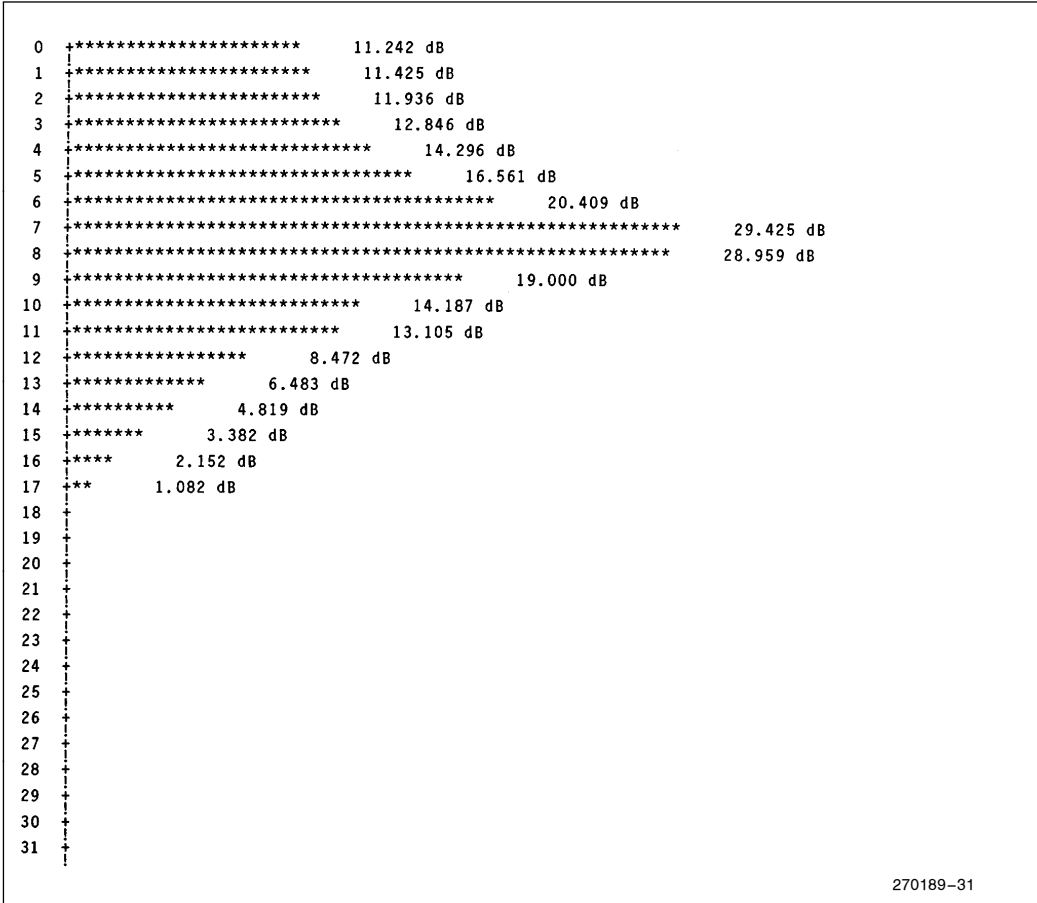
270189-28



Plot 10— $0.707/16 * \sin(11X)$  without Window

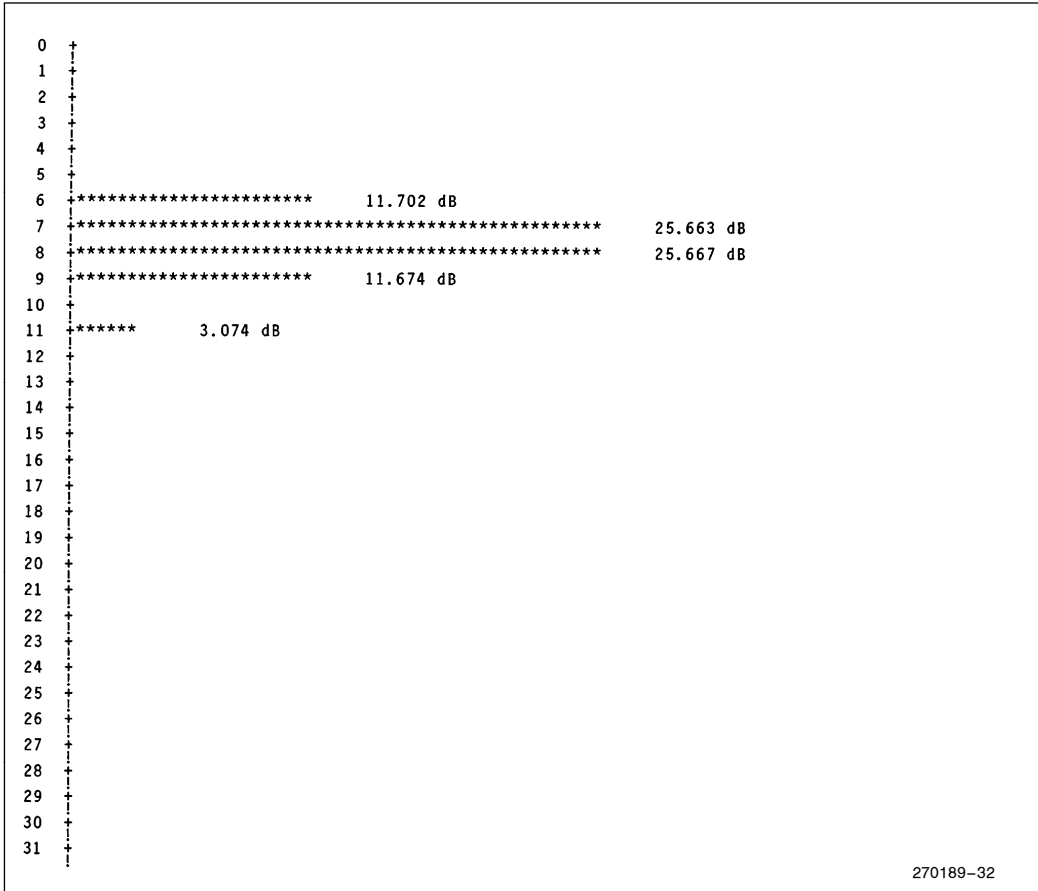


Plot 11— $0.707/16 * \sin(11X)$  with Window



Plot 12—0.707 (Sin (7.5X) + 1/16 Sin (11X)) without Window

270189-31



Plot 13— $0.707 (\sin (7.5X)) + \frac{1}{16} \sin (11X)$  with Window

270189-32

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