

# **SBC5204 USER'S MANUAL REVISION 1.1**



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## **CHAPTER 1**

### **INTRODUCTION TO THE SBC5204 BOARD**

#### **1.1 INTRODUCTION**

The SBC5204 is a versatile single board computer based on MCF5204 ColdFire Processor. It may be used as a powerful microprocessor based controller in a variety of applications. With the addition of a terminal, it serves as a complete microcomputer for development/evaluation, training and educational use. The user must only connect an RS-232 compatible terminal (or a personal computer with terminal emulation software) and a power supply to have a fully functional system.

Provisions have been made to connect this board to additional user supplied boards, via the Microprocessor Expansion Bus connectors, to expand memory and I/O capabilities. Additional boards may require bus buffers to permit additional bus loading.

Furthermore, provisions have been made in the PC-board to permit configuration of the board in a way which best suits an application. Options available are: 1M of SRAM, Timer, I/O, ISA bus interface, and up to 1M bytes of Flash or 2M bytes of EPROM. In addition, all of the I/O functions of the MCF5204 are available for the user.

#### **1.2 GENERAL HARDWARE DESCRIPTION**

The SBC5204 board provides the RAM, Flash ROM, optional Ethernet interface (ISA bus), RS232, and all the built-in I/O functions of the MCF5204 for learning and evaluating the attributes of the MCF5204. The MCF5204 is a member of the ColdFire family of processors. It is a 32-bit processor with 32 bits of addressing and 32 lines of data. The processor has eight 32-bit data registers, 8 32-bit address registers, a 32-bit program counter, and a 16-bit status register.

The MCF5204 has a System Integration Module referred to as SIM. The module incorporate many of the functions needed for system design. These include programmable chip-select logic, System Protection logic, General purpose I/O, and Interrupt controller logic. The chip-select logic can select up to six memory banks or peripherals. The chip-select logic also allows programmable number of wait-state to allow the use of slower memory (refer to MCF5204 User's Manual by Motorola for detail information about the SIM.) The SBC5204 dBUG monitor only uses five of the chip selects to access the Flash ROM's, one bank of SRAM's, MC68HC901, and ISA bus interface. All other functions of the SIM are available to the user.

A hardware watchdog timer (Bus Monitor) circuit is included in the SIM which monitors the bus activities. If a bus cycle is not terminated within a programmable time, the watchdog timer will assert an internal transfer error signal to terminate the bus cycle. A block diagram of the board is shown in Figure 1.1.

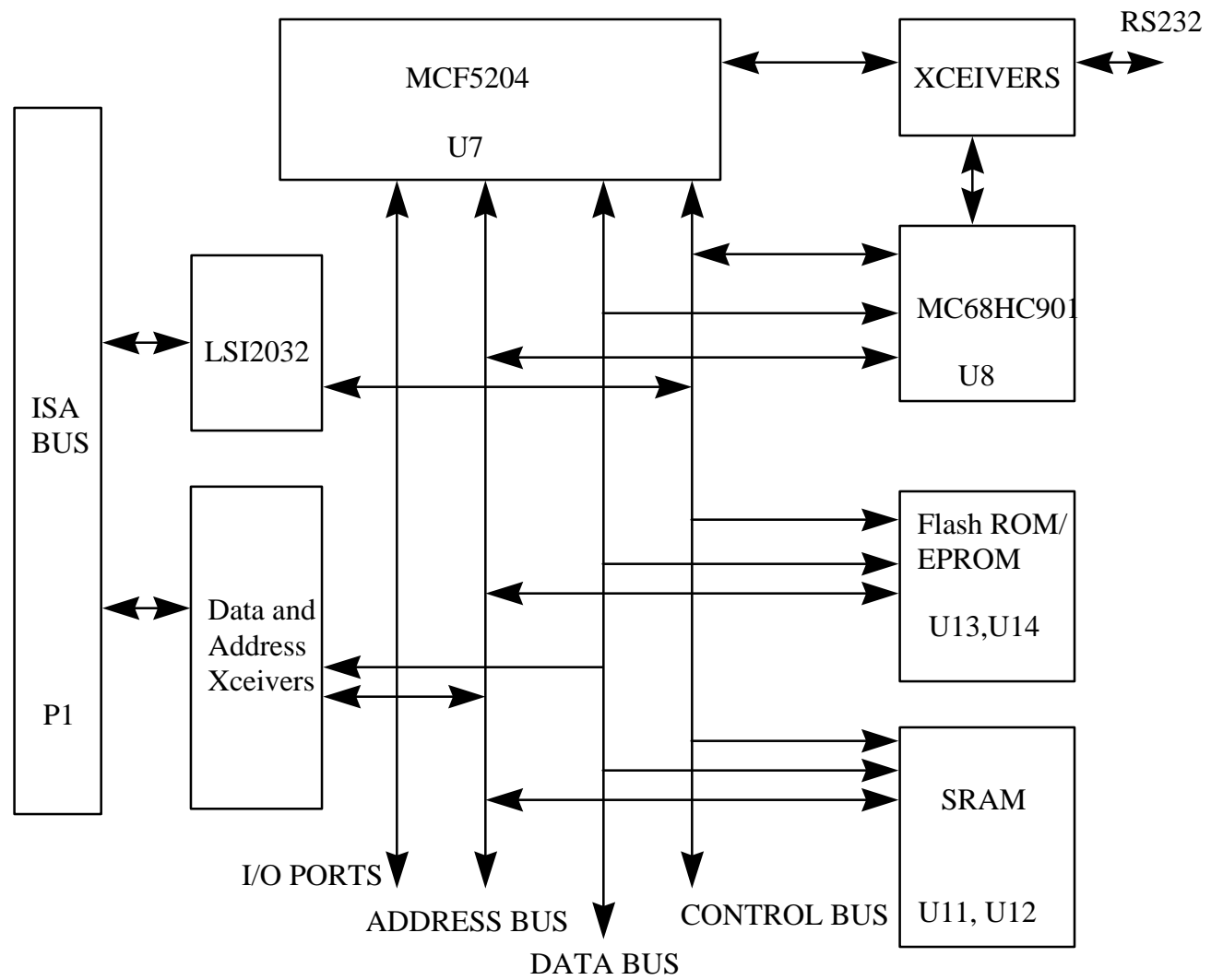


Figure 1.1



### **1.3 SYSTEM MEMORY**

There are two 32-pin sockets on the board for EPROM's or Flash ROM's (U13, U14), U13 is the most significant byte and the U14 is the least significant byte. The EPROM sockets can be set up via jumpers (JP2, JP3, and JP4) to accept 27C256, 27C512, 27C010, 27C020, 27C040, and 27C080 EPROM's. or 29F010, and 29F040. The SBC5204 comes with two 29F010 Flash ROM's which are programmed with a debugger/monitor firmware. The dBUG driver only supports 29F010 Flash ROM.

There are two 32-pin sockets for SRAM's which can accept 128Kx8 and 512Kx8 SRAM's. JP2 is used to make the selection.

### **1.4 SERIAL COMMUNICATION CHANNELS**

The MCF5204 has one built-in Serial Communication Channel with baud rate generator. This signals of this channel are passed through external Driver/Receivers to make the channel compatible with RS-232. This channel is not used by the debugger and is available to user. The SBC5204, however, has one MC68HC901 which has four timers and a serial communication port. One timer channel is used as baud rate generator for the serial channel. The RXD and TXD lines are passed through external Driver/Receiver to make this channel compatible with RS-232C level (Note: only 2 main signals are available, RXD and TXD signals). This channel is the "TERMINAL" channel used by the debugger for communication with external terminal/PC.

### **1.5 PARALLEL I/O PORTS**

Some of the multifunction pins of the MCF5204 can be used as Port A general purpose I/O pins. These pins are available to user except A20/PA0 which may be used for EPROM selection when using 8M EPROM's.

### **1.6 PROGRAMMABLE TIMER/COUNTER**

The MCF5204 has two built in general purpose timer/counters. These timers are not used by the debugger and are available to the user. The signals for the timer share the pins with Port A and are available on the connector J9. There are also three timers in MC68HC901 which are available to user.

### **1.7 ISA BUS CONNECTOR**

The SBC5204 has one ISA bus connector to allow the use of off-the-shelf ISA I/O cards. The main reason for this connector is to install an Ethernet card to support down-load via network.

### **1.8 SYSTEM CONFIGURATION**

The SBC5204 board requires only the following items for minimum system configuration (Fig. 1.2):

- a. The SBC5204 board (provided).
- b. Power supply ( +5 Vdc regulated or 7.5V to 12V DC), about 0.5 Amp.
- c. RS-232C compatible terminal or a PC with terminal emulation software.

- d. Communication cable (provided).

Refer to next sections for initial setup.

## **1.9 INSTALLATION AND SETUP**

The following sections describe all the steps needed to prepare the board for operation. Please read the following sections carefully before using the board. When you are preparing the board for the first time, do not use the optional features (Ethernet, ISA BUS). The minimum configuration does not require any modifications. After the board is functional in its minimal configuration, you may use other features by following the instructions provided in the following sections.

### **1.9.1 Unpacking**

Unpack the computer board from its shipping box. Save the box for storing or reshipping. Refer to the following list and verify that all the items are present. You should have received:

- a. SBC5204 Single Board Computer.
- b. SBC5204 User's Manual, this documentation.
- c. One communication cable.

### **WARNING**

AVOID TOUCHING THE MOS DEVICES. STATIC DISCHARGE  
CAN AND WILL DAMAGE THESE DEVICES.

Once you verified that all the items are present, remove the board from its protective jacket. Check the board for any visible damage. Ensure that there are no broken, damaged, or missing parts. If you have not received all the items listed above or they are damaged, please contact Arnewsh Inc. immediately in order to correct the problem.

### **1.9.2 Preparing the Board for Use**

The board as shipped is ready to be connected to a terminal and the power supply without any need for modification. However, follow the steps below to insure proper operation from the first time you apply the power. Figure 1.3 shows the placement of the jumpers and the connectors which you need to refer to in the following sections. The steps to be taken are:

- a. Connecting the power supply.
- b. Connecting the terminal.

### **1.9.3 Providing Power to the Board**

The board accepts two means of power supply connections. Connector J3 is a 2.1mm power jack and J4 lever actuated connector. The board accepts either +5V regulated supply **or** +7.5V to 12V DC (regulated or unregulated), less than one Amp via either connectors. Jumper JP1 selects between +5 and +7.5-12V

options. **Make sure the jumper JP1 is in proper location for your option.** Connect power supply as marked on the board and shown below (do not turn the power supply on yet):

<u>Contact NO.</u>	<u>Voltage</u>
1	+5 Vdc or +7.5-12V
2	Ground

**Jumper JP1.**

<b>Jumper Pin</b>	<b>Function</b>
1 and 2	+5V regulated
2 and 3	+7.5-12V DC, regulated or unregulated (default)

#### **1.9.4 Selecting Terminal Baud Rate**

The serial channel of MC68HC901 which is used for serial communication channel has a built in software programmable baud rate generator (timer). It can be programmed to a number of baud rates. After the power-up or a manual RESET, the dBUG firmware configures the channel for 19200 baud. After the dBUG is running, you may issue the SET command to choose any baud rate supported by the dBUG. Refer to Chapter 2 for the discussion of this command.

#### **1.9.5 The Terminal Character Format**

The character format of the communication channel is fixed at the power-up or RESET. The character format is 8 bits per character, no parity, and one stop bit. You need to insure that your terminal or PC is set to this format.

#### **1.9.6 Connecting the Terminal**

The board is now ready to be connected to a terminal. Use the communication cable provided to connect the terminal to the SBC5204. The cable has a 9-pin female D-sub connector at one end and a 9-pin male D-sub connector at the other end. Attach the 9-pin male connector to J1 connector on the board. Attach the 9-pin female connector to a 9-pin-to-25-pin adapter, if necessary, to make it compatible with the connector on the back of the terminal.

#### **1.9.7 Using a Personal Computer as a Terminal**

You may use your personal computer as a terminal provided you also have a terminal emulation software such as PROCOMM, KERMIT, QMODEM, or similar packages. Use the communication cable provided to connect the PC to the SBC5204. The cable has a 9-pin female D-sub connector at one end and a 9-pin male D-sub connector at the other end. Connect the 9-pin male connector to J1 connector on SBC5204. Connect the 9-pin female connector to one of the available serial communication channels normally referred to as COM1 (COM2, etc.) on the IBM PC's or compatible. Depending on the kind of serial connector on the back of your PC, the connector on your PC may be a male 25-pin or 9-pin. You may need to obtain a 9-pin-to-25-pin adapter to make the connection. If you need to build an adapter, refer to Figure 1.4 which shows the pin assignment for the 9-pin connector on the board.

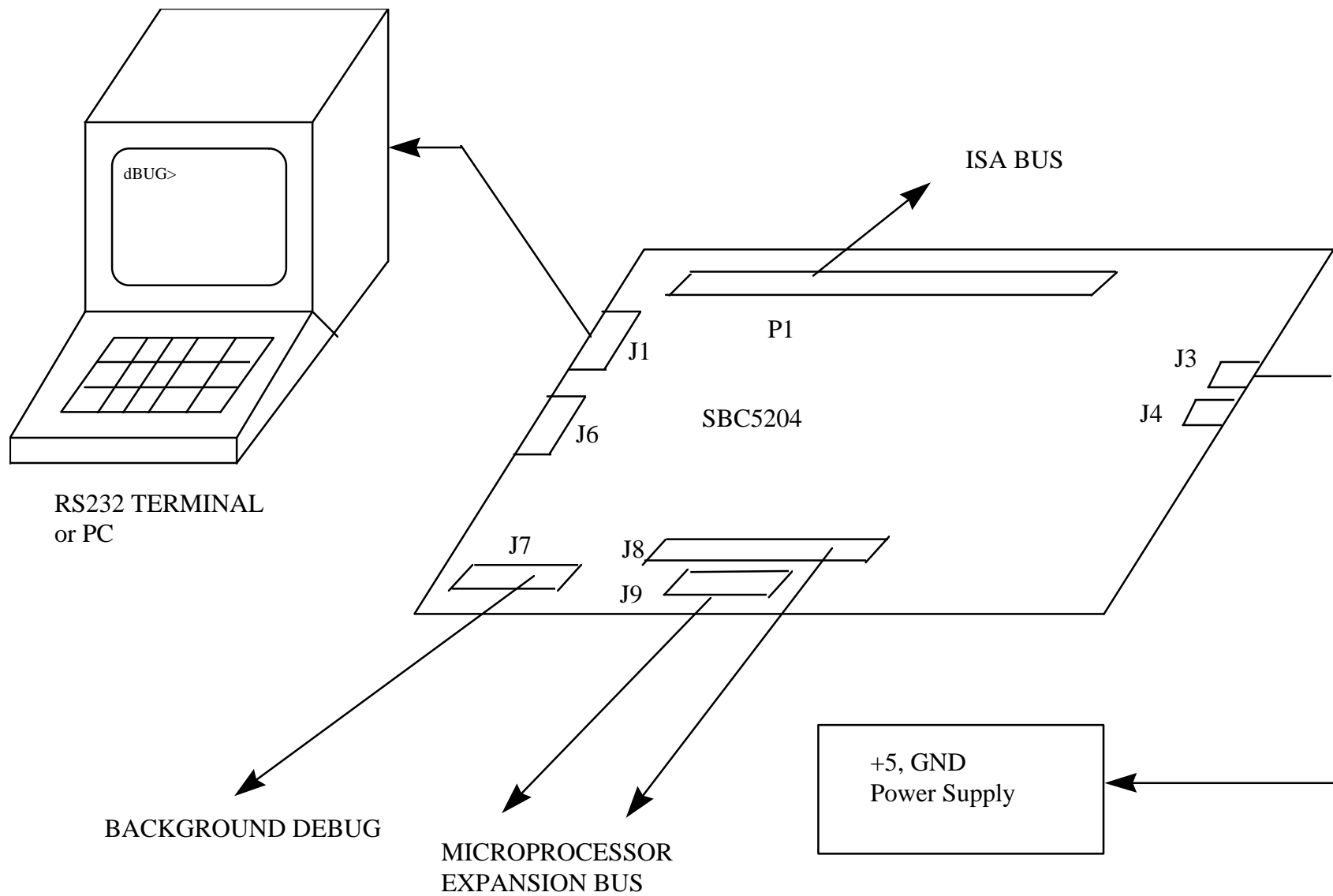
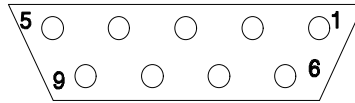


Figure 1.2. System Configuration

Once the connection to the PC is made, you are ready to power-up the PC and run the terminal emulation software. When you are in the terminal mode, you need to select the baud rate and the character format for the channel. Most terminal emulation software packages provide a command known as "Alt-p" (press the p key while pressing the Alt key) to choose the baud rate and character format. Make sure you select 8 bits, no parity, one stop bit (see Section 1.9.5). Then, select the baud rate as 19200. Now you are ready to apply power to the board.



1. Data Carrier Detect, Output (shorted to pins 6 and 8).
2. Receive Data, Output from board (receive refers to terminal side).
3. Transmit Data, Input to board (transmit refers to terminal side).
4. Data Terminal Ready, input (not used).
5. Signal Ground.
6. Data Set Ready, Output (shorted to pins 1 and 8).
7. Request to Send, input.
8. Clear to send, output (shorted to pins 1 and 6).
9. Not connected.

**Figure 1.4. Pin assignment for the J1 (Terminal) connector.**



Figure 1.3. Jumper and connector placement.

## 1.10 SYSTEM POWER-UP AND INITIAL OPERATION

Now that you have connected all the cables, you may apply power to the board. After power is applied, the dBUG initializes the board then displays the power-up message on the terminal which includes the amount of the memory present.

*Hard Reset*

*Installed SRAM: 256K*

*Copyright 1995-1996 Motorola, Inc. All Rights Reserved.  
ColdFire MCF5204 EVS Debugger V2.1 (Aug xx 1996 xx:xx:xx:)  
Enter 'help' for help.*

*dBUG>*

The board is now ready for operation under the control of the debugger as described in Chapters 2. If you do not get the above response, perform the following checks:

1. Make sure that the power supply is properly set and connected to the board.
2. Check that the terminal and board are set for the same character format and baud.
3. Press the red RESET (red switch) button to insure that the board has been initialized properly.

If you still are not receiving the proper response, your board may have been damaged in shipping. Contact Arnewsh for further instructions.

## 1.11 SBC5204 JUMPER SETUP

The jumpers on the board are discussed in Chapter 3. However, a brief discussion of the jumper settings are as follows:

1. Jumper JP1. This jumper selects the power supply selection.

Jumper Pin	Function
1 and 2	+5V regulated.
2 and 3	+7.5-12V DC regulated or unregulated (default)

2. Jumper JP2. This jumper selects the SRAM size and EPROM Size.

Jumper Pin	Function
2 to 4	Selects 128Kx8 SRAM (default)
1 to 3	Selects 128Kx8 Flash Memory (default)

3. Jumper JP3. This jumper selects between Flash and EPROM.

Jumper Pin	Function
3 to 5 and 4 to 6	Select Flash (default)

4. Jumper JP4. This jumper selects the size of EPROM or Flash.

Jumper Pin	Function
7 to 9 and 8 to 10	Selects 128Kx8 EPROM/Flash

## 1.12 USING THE BDM

The MCF5204 has a built in debug mechanism referred to as BDM. The SBC5204 has the necessary connector, J7, to facilitate this connection.

In order to use the BDM, simply connect the 26-pin IDC header at the end of the BDM cable provided by the BDM development tool (third party tool) to the J7 connector. No special setting is needed. Refer to the BDM User's Manual for additional instructions.



## CHAPTER 2

### USING THE MONITOR/DEBUG FIRMWARE

The SBC5204 Computer Board has a resident firmware package that provides a self-contained programming and operating environment. The firmware, named dBUG, provides the user with monitor/debug, disassembly, program download, and I/O control functions. This Chapter is a how-to-use description of the dBUG package, including the user interface and command structure.

#### 2.1 WHAT IS dBUG?

dBUG is a resident firmware package for the ColdFire family Computer Boards. The firmware (stored in two 128Kx8 Flash ROM devices) provides a self-contained programming and operating environment. dBUG interacts with the user through pre-defined commands that are entered via the terminal.

The user interface to dBUG is the command line. A number of features have been implemented to achieve an easy and intuitive command line interface.

dBUG assumes that an 80x24 character dumb-terminal is utilized to connect to the debugger. For serial communications, dBUG requires eight data bits, no parity, and one stop bit, 8N1. The baud rate is 19200 but can be changed after the power-up.

The command line prompt is "dBUG> ". Any dBUG command may be entered from this prompt. dBUG does not allow command lines to exceed 80 characters. Wherever possible, dBUG displays data in 80 columns or less. dBUG echoes each character as it is typed, eliminating the need for any "local echo" on the terminal side.

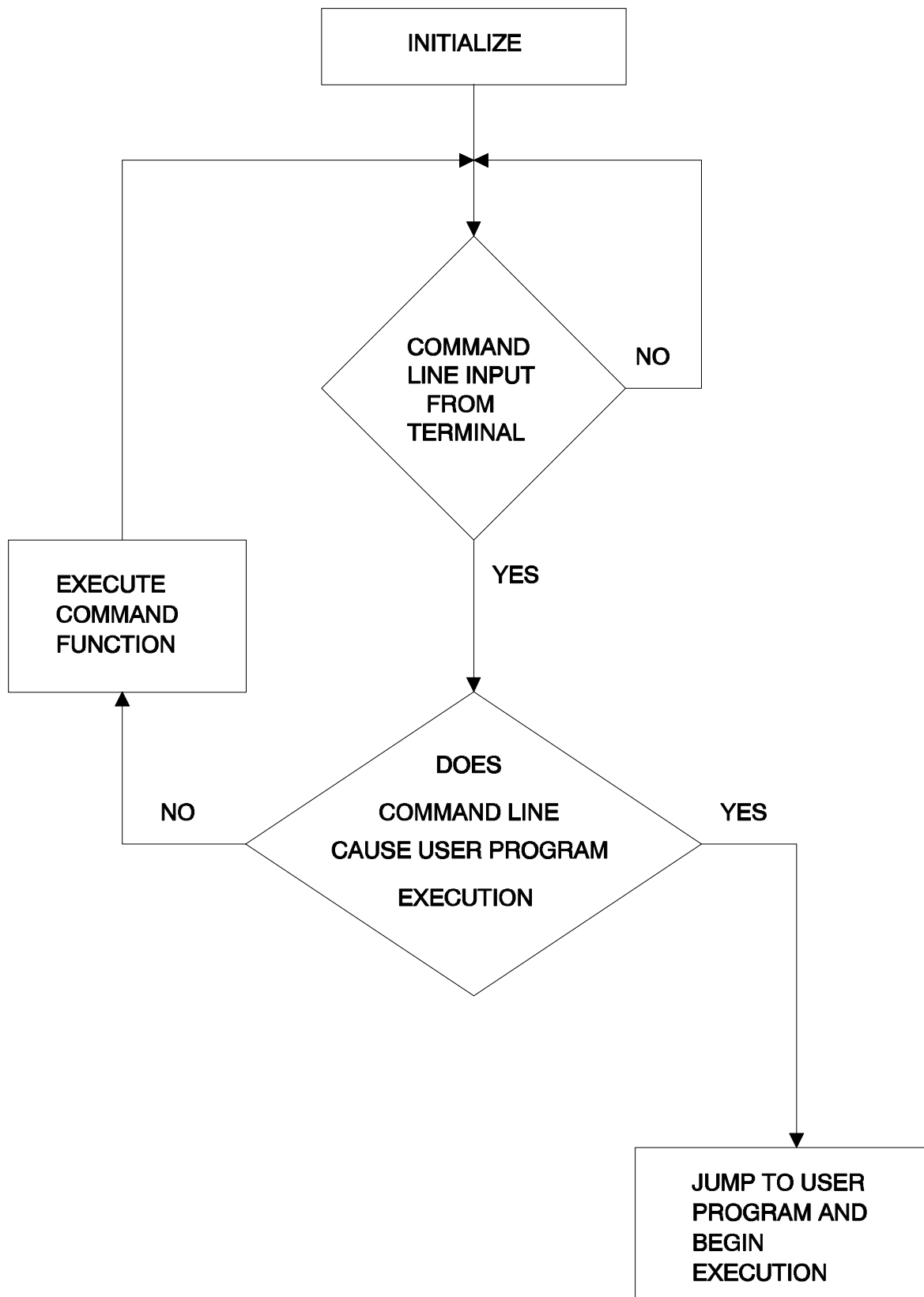
In general, dBUG is not case sensitive. Commands may be entered either in upper or lower case, depending upon the user's equipment and preference. Only symbol names require that the exact case be used.

Most commands can be recognized by using an abbreviated name. For instance, entering "h" is the same as entering "help". Thus, it is not necessary to type the entire command name.

The commands DI, GO, MD, STEP and TRACE are used repeatedly when debugging. dBUG recognizes this and allows for repeated execution of these commands with minimal typing. After a command is entered, simply press <RETURN> or <ENTER> to invoke the command again. The command is executed as if no command line parameters were provided.

An additional function called the "TRAP 15 handler" allows the user program to utilize various routines within dBUG. The TRAP 15 handler is discussed at the end of this chapter.

The operational mode of dBUG is demonstrated in Figure 2-1. After the system initialization, the board waits for a command line input from the user terminal. When a proper command is entered, the operation continues in one of the two basic modes. If the command causes execution of the user program, the dBUG firmware may or may not be re-entered, depending on the discretion of the user. For the alternate case, the command will be executed under control of the dBUG firmware, and after command completion, the system returns to command entry mode.



**Figure 2-1. Flow Diagram of dBUG Operational Mode.**

During command execution, additional user input may be required depending on the command function.

For commands that accept an optional <width> to modify the memory access size, the valid values are:

- .B      8-bit (byte) access
- .W      16-bit (word) access
- .L      32-bit (long) access

When no <width> option is provided, the default width is .W, 16-bit.

The core ColdFire register set is maintained by dBUG. These are listed below:

- A0-A7
- D0-D7
- PC
- SR

All control registers on ColdFire are not readable by the supervisor programming model, and thus not accessible via dBUG. User code may change these registers, but caution must be exercised as changes may render dBUG useless.

A reference to “SP” actually refers to “A7”.

## **2.2 OPERATIONAL PROCEDURE**

System power-up and initial operation are described in detail in Chapter 1. This information is repeated here for convenience and to prevent possible damage.

### **2.2.1 System Power-up**

- a. Be sure the power supply is connected properly prior to power-up.
- b. Make sure the terminal is connected to TERMINAL (J1) connector.
- c. Turn power on to the board.

### **2.2.2 System Initialization**

The act of powering up the board will initialize the system. The processor is reset and dBUG is invoked.

dBUG performs the following configurations of internal resources during the initialization. The instruction cache is invalidated and disabled. The Vector Base Register, VBR, points to the Flash. However, a copy of the exception table is made at address \$00000000 in SRAM. To take over an exception vector, the user places the address of the exception handler in the appropriate vector in the vector table located at 0x00000000, and then points the VBR to 0x00000000.

The Software Watchdog Timer is disabled, Bus Monitor enabled, and internal timers are placed in a stop condition. Interrupt controller registers initialized with unique interrupt level/priority pairs. The Port A general purpose I/O pins are configured for dedicated peripheral functions, i.e. the UART.

After initialization, the terminal will display:

**Hard Reset**

**Installed SRAM: 256K**

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**ColdFire MCF5204 EVS Debugger V2.1 (Aug xx 1996 xx:xx:xx:)**

**Enter 'help' for help.**

**dBUG>**

If you did not get this response check the setup. Refer to Section 1.10. Note, the date

'Aug xx 1996 xx:xx:xx' may vary in different revisions.

Other means can be used to re-initialize the SBC5204 Computer Board firmware. These means are discussed in the following paragraphs.

**2.2.2.1 RESET Button.** RESET is the red button located in the middle side of the board. Depressing this button causes all processes to terminate, resets the MCF5204 processor and board logic's and restarts the dBUG firmware. Pressing the RESET button would be the appropriate action if all else fails.

**2.2.2.2 ABORT Button.** ABORT is the black button located next to RESET button in the middle side of the board. The abort function causes an interrupt of the present processing (a level 7 interrupt on MCF5204) and gives control to the dBUG firmware. This action differs from RESET in that no processor register or memory contents are changed, the processor and peripherals are not reset, and dBUG is not restarted. Also, in response to depressing the ABORT button, the contents of the MCF5204 core internal registers are displayed.

The abort function is most appropriate when software is being debugged. The user can interrupt the processor without destroying the present state of the system.

**2.2.2.3 Software Reset Command.** dBUG does have a command that causes the dBUG to restart as if a hardware reset was invoked. The command is "RESET".

**2.2.2.4 USER Program.** The user can return control of the system to the firmware by recalling dBUG via his/her program. Instructions can be inserted into the user program to call dBUG via the TRAP 15 handler.

## **2.2.3 System Operation**

After system initialization, the terminal will display:

**Hard Reset**

**Installed SRAM: 256K**

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**ColdFire MCF5204 EVS Debugger V2.1 (Aug xx 1996 xx:xx:xx:)**

**Enter 'help' for help.**

**dBUG>**

and waits for a command.

The user can call any of the commands supported by the firmware. A standard input routine controls the system while the user types a line of input. Command processing begins only after the line has been entered and followed by a carriage-return.

### **NOTES**

1. The user memory is located at addresses \$00010000-\$xxxxxxx, \$xxxxxxx is the maximum RAM address of the memory installed in the board. When first learning the system, the user should limit his/her activities to this area of the memory map. Address range \$00000000-\$0000FFFF is used by dBUG.
2. If a command causes the system to access an unused address (i.e., no memory or peripheral devices are mapped at that address), a bus trap error will occur. This results in the terminal printing out a trap error message and the contents of all the MCF5204 core registers. Control is returned to the dBUG monitor.

## **2.3 TERMINAL CONTROL CHARACTERS**

The command line editor remembers the last five commands, in a history buffer, which were issued. They can be recalled and then executed using control keys.

Several keys are used as a command line edit and control functions. It is best to be familiar with these functions before exercising the system. These functions include:

- a. RETURN (carriage- return) - will enter the command line and causes processing to begin.
- b. Delete (Backspace) key or CTRL-H - will delete the last character entered on the terminal.
- c. CTRL-D - Go down in the command history buffer, you may modify then press enter key.
- d. CTRL-U - Go up in the command history buffer, you may modify then press enter key.
- e. CTRL-R - Recall and execute the last command entered, does not need the enter key to be pressed.

For characters requiring the control key (CTRL) , the CTRL should be pushed and held down and then the other key (H) should be pressed.

## **2.4 dBUG COMMAND SET**

Table 2-1 lists the dBUG commands. Each of the individual commands is described in the following pages.

**TABLE 2-1. dBUG Commands.**

COMMAND MNEMONIC	DESCRIPTION	SYNTAX	PAGE
BF	BLOCK FILL	BF<WIDTH> BEGIN END DATA	2-7
BM	BLOCK MOVE	BM BEGIN END DEST	2-8
BS	BLOCK SEARCH	BS <WIDTH> BEGIN END DATA	2-9
BR	BREAKPOINT	BR ADDR <-R> <-C COUNT> <-T TRIGGER>	2-10
DATA	DATA CONVERT	DATA VALUE	2-11
DI	DISASSEMBLE	DI <ADDR>	2-12
DL	DOWNLOAD SERIAL	DL <OFFSET>	2-13
DN	DOWNLOAD NETWORK	DN <-C> <-E> <-S> <-I> <-O OFFSET> <FILENAME>	2-14
GO	EXECUTE	GO <ADDR>	2-15
GT	Go TILL BREAKPOINT	GT <ADDR>	2-16
HELP	HELP	HELP <COMMAND>	2-17
IRD	INTERNAL REGISTER DISPLAY	IRD <MODULE.REGISTER>	2-18
IRM	INTERNAL REGISTER MODIFY	IRM <MODULE.REGISTER> <DATA>	2-19
MD	MEMORY DISPLAY	MD <WIDTH> <BEGIN> <END>	2-20
MM	MEMORY MODIFY	MM <WIDTH> ADDR <DATA>	2-21
RD	REGISTER DISPLAY	RD <REG>	2-22
RM	REGISTER MODIFY	RM REG DATA	2-23
RESET	RESET	RESET	2-24
SET	SET CONFIGURATIONS	SET OPTION <VALUE>	2-25
SHOW	SHOW CONFIGURATIONS	SHOW OPTION	2-27
STEP	STEP (OVER)	STEP	2-28
SYMBOL	SYMBOL MANAGEMENT	SYMBOL <SYMB> <-A SYMB VALUE> <-R SYMB> <-C   L   S>	2-29
TRACE	TRACE(INTO)	TRACE <NUM>	2-30
UPDEBUG	UPDATE DBUG	UPDEBUG	2-31
UPUSER	UPDATE USER FLASH	UPUSER	2-32
VERSION	SHOW VERSION	VERSION	2-33

## 2.4.1 BF - Block of Memory Fill

**BF**

Usage: BF<width> begin end data

The BF command fills a contiguous block of memory starting at address begin, stopping at address end, with the value data. Width modifies the size of the data that is written.

The value for addresses begin and end may be an absolute address specified as a hexadecimal value, or a symbol name. The value for data may be a symbol name, or a number converted according to the user defined radix, normally hexadecimal.

This command first aligns the starting address for the data access size, and then increments the address accordingly during the operation. Thus, for the duration of the operation, this command performs properly aligned memory accesses.

Examples:

To fill a memory block starting at 0x00010000 and ending at 0x00040000 with the value 0x1234, the command is:

```
bf      10000 40000 1234
```

To fill a block of memory starting at 0x00010000 and ending at 0x00040000 with a byte value of 0xAB, the command is:

```
bf.b    10000 40000 AB
```

To zero out the BSS section of the target code (defined by the symbols bss\_start and bss\_end), the command is:

```
bf      bss_start bss_end 0
```

## 2.4.2 BM - Block Move

## BM

Usage: BM begin end dest

The BM command moves a contiguous block of memory starting at address begin, stopping at address end, to the new address dest. The BM command copies memory as a series of bytes, and does not alter the original block.

The value for addresses begin, end, and dest may be an absolute address specified as a hexadecimal value, or a symbol name. If the destination address overlaps the block defined by begin and end, an error message is produced and the command exits.

Examples:

To copy a block of memory starting at 0x00040000 and ending at 0x00080000 to the location 0x00200000, the command is:

```
bm 40000 80000 200000
```

To copy the target code's data section (defined by the symbols data\_start and data\_end) to 0x00200000, the command is:

```
bm data_start data_end 200000
```



### 2.4.3 BR - Breakpoint

### BR

Usage: BR addr <-r> <-c count> <-t trigger>

The BR command inserts or removes breakpoints at address addr. The value for addr may be an absolute address specified as a hexadecimal value, or a symbol name. Count and trigger are numbers converted according to the user defined radix, normally hexadecimal.

If no argument is provided to the BR command, a listing of all defined breakpoints is displayed.

The -r option to the BR command removes a breakpoint defined at address addr. If no address is specified in conjunction with the -r option, then all breakpoints are removed.

Each time a breakpoint is encountered during the execution of target code, its count value is incremented by one. By default, the initial count value for a breakpoint is zero, but the -c option allows setting the initial count for the breakpoint.

Each time a breakpoint is encountered during the execution of target code, the count value is compared against the trigger value. If the count value is equal to or greater than the trigger value, a breakpoint is encountered and control returned to dBUG. By default, the initial trigger value for a breakpoint is one, but the -t option allows setting the initial trigger for the breakpoint.

If no address is specified in conjunction with the -c or -t options, then all breakpoints are initialized to the values specified by the -c or -t option.

Examples:

To set a breakpoint at the C function main(), the command is:

```
br    _main
```

When the target code is executed and the processor reaches main(), control will be returned to dBUG.

To set a breakpoint at the C function bench() and set its trigger value to 3, the command is:

```
br    _bench -t 3
```

When the target code is executed, the processor must attempt to execute the function bench() a third time before returning control back to dBUG.

To remove all breakpoints, the command is:

```
br    -r
```

## 2.4.4 BS - Block Search

## BS

Usage: BS<width> begin end data

The BS command searches a contiguous block of memory starting at address begin, stopping at address end, for the value data. Width modifies the size of the data that is compared during the search.

The value for addresses begin and end may be an absolute address specified as a hexadecimal value, or a symbol name. The value for data may be a symbol name, or a number converted according to the user defined radix, normally hexadecimal.

This command first aligns the starting address for the data access size, and then increments the address accordingly during the operation. Thus, for the duration of the operation, this command performs properly aligned memory accesses.

Examples:

To search for the 16-bit value 0x1234 in the memory block starting at 0x00040000 and ending at 0x00080000 the command is:

```
bs      40000 80000 1234
```

This reads the 16-bit word located at 0x00040000 and compares it against the 16-bit value 0x1234. If no match is found, then the address is incremented to 0x00040002 and the next 16-bit value is read and compared.

To search for the 32-bit value 0xABCD in the memory block starting at 0x00040000 and ending at 0x00080000, the command is:

```
bs.l    40000 80000 ABCD
```

This reads the 32-bit word located at 0x00040000 and compares it against the 32-bit value 0x0000ABCD. If no match is found, then the address is incremented to 0x00040004 and the next 32-bit value is read and compared.

To search the BSS section (defined by the symbols bss\_start and bss\_end) for the byte value 0xAA, the command is:

```
bs.b    bss_start bss_end AA
```

## 2.4.5 DATA - Data Conversion

## DATA

Usage: DATA data

The DATA command displays data in both decimal and hexadecimal notation.

The value for data may be a symbol name or an absolute value. If an absolute value passed into the DATA command is prefixed by '0x', then data is interpreted as a hexadecimal value. Otherwise data is interpreted as a decimal value.

All values are treated as 32-bit quantities.

Examples:

To display the decimal equivalent of 0x1234, the command is:

```
data    0x1234
```

To display the hexadecimal equivalent of 1234, the command is:

```
data    1234
```

## 2.4.6 DI - Disassemble

## DI

Usage:        DI <addr>

The DI command disassembles target code pointed to by addr. The value for addr may be an absolute address specified as a hexadecimal value, or a symbol name.

Wherever possible, the disassembler will use information from the symbol table to produce a more meaningful disassembly. This is especially useful for branch target addresses and subroutine calls.

The DI command attempts to track the address of the last disassembled opcode. If no address is provided to the DI command, then the DI command uses the address of the last opcode that was disassembled.

Examples:

To disassemble code that starts at 0x00040000, the command is:

```
di      40000
```

To disassemble code of the C function main(), the command is:

```
di      _main
```

## 2.5.7 DL - Download Serial

## DL

Usage: DL <offset>

The DL command performs an S-record download of data obtained from the serial port. The value for offset is converted according to the user defined radix, normally hexadecimal.

If offset is provided, then the destination address of each S-record is adjusted by offset.

The DL command checks the destination address for validity. If the destination is an address below the defined user space (0x00000000-0x00010000), then an error message is displayed and downloading aborted.

If the S-record file contains the entry point address, then the program counter is set to reflect this address.

Examples:

To download an S-record file through the serial port, the command is:

```
dl
```

To download an S-record file through the serial port, and adjust the destination address by 0x40, the command is:

```
dl    0x40
```

## 2.4.8 DN - Download Network

## DN

Usage:        DN <-c> <-e> <-i> <-s> <-o offset> <filename>

The DN command downloads code from the network. The DN command handle files which are either S-record, COFF or ELF formats. The DN command uses Trivial File Transfer Protocol, TFTP, to transfer files from a network host. This command only works with 100% NE2000 compatible boards.

In general, the type of file to be downloaded and the name of the file must be specified to the DN command. The -c option indicates a COFF download, the -e option indicates an ELF download, -I option indicates an image fownload, and the -s indicates an S-record download. The -o option works only in conjunction with the -s option to indicate and optional offset for S-record download. The filename is passed directly to the TFTP server and, therefore, must be a valid filename on the server.

If neither of the -c, -e, -i, -s or filename options are specified, then a default filename and filetype will be used. Default filename and filetype parameters are manipulated using the set and show commands.

The DN command checks the destination address for validity. If the destination is an address below the defined user space, then an error message is displayed and downloading aborted.

For ELF and COFF files which contain symbolic debug information, the symbol tables are extracted from the file during download and used by dBUG. Only global symbols are kept in dBUG. The dBUG symbol table is not cleared prior to downloading, so it is the user's responsibility to clear the symbol table as necessary prior to downloading.

If an entry point address is specified in the S-record, COFF or ELF file, the program counter is set accordingly.

Examples:

To download an S-record file with the name "srec.out", the command is:

```
dn -s srec.out
```

To download a COFF file with the name "coff.out", the command is:

```
dn -c coff.out
```

To download a file using the default filetype with the name "bench.out", the command is:

```
dn bench.out
```

To download a file using the default filename and filetype, the command is:

```
dn
```

**This command requires proper Network address and parameter setup. Refer to Appendix A for this procedure. Also refer to "SET" command to setup the base address and the IRQ for the card.**

## 2.4.9 Go - Execute

## GO

Usage:       GO <addr>

The GO command executes target code starting at address addr. The value for addr may be an absolute address specified as a hexadecimal value, or a symbol name.

If no argument is provided, the GO command begins executing instructions at the current program counter.

When the GO command is executed, all user-defined breakpoints are inserted into the target code, and the context is switched to the target program. Control is only regained when the target code encounters a breakpoint, illegal instruction, or other exception which causes control to be handed back to dBUG.

Examples:

To execute code at the current program counter, the command is:

```
go
```

To execute code at the C function main(), the command is:

```
go _main
```

To execute code at the address 0x00040000, the command is:

```
go 40000
```

## 2.4.10 GT - Execute Till a Temporary Breakpoint

**GT**

Usage:           GT <addr>

The GT command executes the target code starting at address in PC (whatever the PC has) until a temporary breakpoint as given in the command line is reached.

Example:

To execute code at the current program counter and stop at breakpoint address 0x10000, the command is:

GT 10000



## 2.4.11 HELP - Help

HE

Usage:       HELP <command>

The HELP command displays a brief syntax of the commands available within dBUG. In addition, the address of where user code may start is given. If command is provided, then a brief listing of the syntax of the specified command is displayed.

Examples:

To obtain a listing of all the commands available within dBUG, the command is:

help

The help list is longer than one page. The help command displays one screen full and ask for an input to display the rest of the list.

To obtain help on the breakpoint command, the command is:

help br

## 2.4.12 IRD - Internal Registers Display

## IRD

Usage:           IRD <module.register>

This command displays the internal registers of different modules inside the MCF5204. In the command line, the module refers to the module name where the register is located and the register refers to the specific register needed.

The registers are organized according to the module to which they belong. The available modules on the MCF5204 are SIM, UART, and TIMER. Refer to MCF5204 User's Manual.

Example:

```
ird       sim.sypcr               ;display the SYPCR register in the SIM module.
```

### 2.4.13 IRM - Internal Registers MODIFY

### IRM

Usage:            IRM module.register data

This command modifies the contents of the internal registers of different modules inside the MCF5204. In the command line, the module refers to the module name where the register is located, register refers to the specific register needed, and data is the new value to be written into that register.

The registers are organized according to the module to which they belong. The available modules on the MCF5204 are SIM, UART, and TIMER. Refer to MCF5204 User's Manual

Example:

```
irm    timer.tmr1 0021           ;write 0021 into TMR1 register in the TIMER module.
```

## 2.4.14 MD - Memory Display

## MD

Usage: MD<width> <begin> <end>

The MD command displays a contiguous block of memory starting at address begin and stopping at address end. The value for addresses begin and end may be an absolute address specified as a hexadecimal value, or a symbol name. Width modifies the size of the data that is displayed.

Memory display starts at the address begin. If no beginning address is provided, the MD command uses the last address that was displayed. If no ending address is provided, then MD will display memory up to an address that is 128 beyond the starting address.

This command first aligns the starting address for the data access size, and then increments the address accordingly during the operation. Thus, for the duration of the operation, this command performs properly aligned memory accesses.

Examples:

To display memory at address 0x00400000, the command is:

```
md 400000
```

To display memory in the data section (defined by the symbols data\_start and data\_end), the command is:

```
md data_start
```

To display a range of bytes from 0x00040000 to 0x00050000, the command is:

```
md.b 40000 50000
```

To display a range of 32-bit values starting at 0x00040000 and ending at 0x00050000, the command is:

```
md.l 40000 50000
```

**This command may be repeated by simply pressing the carriage-return (Enter) key.** It will continue with the address after the last display address.

## 2.2.15 MM - Memory Modify

## MM

Usage: MM<width> addr <data>

The MM command modifies memory at the address addr. The value for address addr may be an absolute address specified as a hexadecimal value, or a symbol name. Width modifies the size of the data that is modified. The value for data may be a symbol name, or a number converted according to the user defined radix, normally hexadecimal.

If a value for data is provided, then the MM command immediately sets the contents of addr to data. If no value for data is provided, then the MM command enters into a loop. The loop obtains a value for data, sets the contents of the current address to data, increments the address according to the data size, and repeats. The loop terminates when an invalid entry for the data value is entered, i.e., a period.

This command first aligns the starting address for the data access size, and then increments the address accordingly during the operation. Thus, for the duration of the operation, this command performs properly aligned memory accesses.

Examples:

To set the byte at location 0x00010000 to be 0xFF, the command is:

```
mm.b 10000 FF
```

To interactively modify memory beginning at 0x00010000, the command is:

```
mm 10000
```

## 2.4.16 RD - Register Display

**RD**

Usage: MM<width> addr <data>

The MM command modifies memory at the address addr. The value for address addr may be an absolute address specified as a hexadecimal value, or a symbol name. Width modifies the size of the data that is modified. The value for data may be a symbol name, or a number converted according to the user defined radix, normally hexadecimal.

If a value for data is provided, then the MM command immediately sets the contents of addr to data. If no value for data is provided, then the MM command enters into a loop. The loop obtains a value for data, sets the contents of the current address to data, increments the address according to the data size, and repeats. The loop terminates when an invalid entry for the data value is entered, i.e., a period.

This command first aligns the starting address for the data access size, and then increments the address accordingly during the operation. Thus, for the duration of the operation, this command performs properly aligned memory accesses.

Examples:

To set the byte at location 0x00010000 to be 0xFF, the command is:

```
mm.b 10000 FF
```

To interactively modify memory beginning at 0x00010000, the command is:

```
mm 10000
```

## 2.4.17 RM - Register Modify

**RM**

Usage:           RM reg data

The RM command modifies the contents of the register reg to data. The value for reg is the name of the register, and the value for data may be a symbol name, or it is converted according to the user defined radix, normally hexadecimal.

dBUG preserves the registers by storing a copy of the register set in a buffer. The RM command updates the copy of the register in the buffer. The actual value will not be written to the register until target code is executed.

Examples:

To change register D0 to contain the value 0x1234, the command is:

```
rm      D0 1234
```

## **2.4.18 RESET - Reset the board and dBUG**

### **RESET**

Usage:           RESET

The RESET command attempts to reset the board and dBUG to their initial power-on states.

The RESET command executes the same sequence of code that occurs at power-on. This code attempts to initialize the devices on the board and dBUG data structures. If the RESET command fails to reset the board to your satisfaction, cycle power or press the reset button.

Examples:

To reset the board and clear the dBUG data structures, the command is:

```
reset
```



## 2.4.19 SET - Set Configuration

## SET

Usage:       SET option <value>  
              SET

The SET command allows the setting of user configurable options within dBUG. The options are listed below. If the SET command is issued without option, it will show the available options and values.

The board needs a RESET after this command in order for the new option(s) to take effect.

baud - This is the baud rate for the first serial port on the board. All communications between dBUG and the user occur using either 9600 or 19200 bps, eight data bits, no parity, and one stop bit, 8N1. Do not choose 38400 baud.

base - This is the default radix for use in converting number from their ASCII text representation to the internal quantity used by dBUG. The default is hexadecimal (base 16), and other choices are binary (base 2), octal (base 8), and decimal (base 10).

client - This is the network Internet Protocol, IP, address of the board. For network communications, the client IP is required to be set to a unique value, usually assigned by your local network administrator.

server - This is the network IP address of the machine which contains files accessible via TFTP. Your local network administrator will have this information and can assist in properly configuring a TFTP server if one does not exist.

gateway - This is the network IP address of the gateway for your local subnetwork. If the client IP address and server IP address are not on the same subnetwork, then this option must be properly set. Your local network administrator will have this information.

netmask - This is the network address mask to determine if use of a gateway is required. This field must be properly set. Your local network administrator will have this information.

filename - This is the default filename to be used for network download if no name is provided to the DN command.

filetype - This is the default file type to be used for network download if no type is provided to the DN command. Valid values are: "srecord", "coff", "image", and "elf".

autoboot - This option allows for the automatic downloading and execution of a file from the network. This option can be used to automatically boot an operating system from the network. Valid values are: "on" and "off". This option is not implemented on the current revision of dBUG.

nicbase - this is base address of the network interface card. When using network card, the base address of that card is needed by the dBUG in order to communicate with it. This command is used to inform the dBUG of the address of the card. dBUG does not set or configure the interface card. It only uses this address to access the card. The user should provide this information to dBUG.

nicirq - this is the IRQ used in the network interface card. When using network card, the IRQ used by that card is needed by the dBUG in order to communicate with it. This command is used to inform the dBUG of the IRQ of the card. dBUG does not set or configure the interface card. It only uses this IRQ to access the card. The user should provide this information to dBUG.

flashws - This command is used to adjust the number of wait state for the Flash ROM.

sramws - This command is used to adjust the number of wait state for the SRAM.

Examples:

To see all the available options and supported choices, the command is:

```
set
```

To set the baud rate of the board to be 19200, the command is:

```
set      baud 19200
```

Now press the RESET button (RED) or RESET command for the new baud to take effect. This baud will be programmed in Flash ROM and will be used during the power-up.

In order to use the KNE2000TLC ethernet ISA card in the system, the debugger need to know its IRQ and its base address. The Kingston Technology Corporation ethernet card KNE2000TLC has a default base address of \$300 and uses IRQ3. To set up the debugger for ethernet communication, the following commands should be issued first.

```
set      nicbase 300
set      nicirq  3
```

## 2.4.20 SHOW - Show Configuration

## SHOW

Usage:       SHOW option  
              SHOW

The SHOW command displays the settings of the user configurable options within dBUG. Most options configurable via the SET command can be displayed with the SHOW command. If the SHOW command is issued without any option, it will show all options.

Examples:

To display all the current options, the command is:

```
show
```

To display the current baud rate of the board, the command is:

```
show           baud
```

To display the TFTP server IP address, the command is:

```
show           server
```

## 2.4.21 STEP - Step Over

ST

Usage: STEP

The ST command can be used to “step over” a subroutine call, rather than tracing every instruction in the subroutine. The ST command sets a breakpoint one instruction beyond the current program counter and then executes the target code.

The ST command can be used for BSR and JSR instructions. The ST command will work for other instructions as well, but note that if the ST command is used with an instruction that will not return, i.e. BRA, then the temporary breakpoint may never be encountered and thus dBUG may not regain control.

Examples:

To pass over a subroutine call, the command is:

step

## 2.4.22 SYMBOL - Symbol Name Management

## SYMBOL

Usage:           SYMBOL <symb> <-a symb value> <-r symb> <-c|l|s>

The SYMBOL command adds or removes symbol names from the symbol table. If only a symbol name is provided to the SYMBOL command, then the symbol table is searched for a match on the symbol name and its information displayed.

The -a option adds a symbol name and its value into the symbol table. The -r option removes a symbol name from the table.

The -c option clears the entire symbol table, the -l option lists the contents of the symbol table, and the -s option displays usage information for the symbol table.

Symbol names contained in the symbol table are truncated to 31 characters. Any symbol table lookups, either by the SYMBOL command or by the disassembler, will only use the first 31 characters. Symbol names are case sensitive.

Examples:

To define the symbol “main” to have the value 0x00040000, the command is:

```
symbol           -a main 40000
```

To remove the symbol “junk” from the table, the command is:

```
symbol           -r junk
```

To see how full the symbol table is, the command is:

```
symbol           -s
```

To display the symbol table, the command is:

```
symbol           -l
```

### 2.4.23 TRACE - Trace Into

**TR**

Usage:           TRACE <num>

The TRACE command allows single instruction execution. If num is provided, then num instructions are executed before control is handed back to dBUG. The value for num is a decimal number.

The TRACE command sets bits in the processors' supervisor registers to achieve single instruction execution, and the target code executed. Control returns to dBUG after a single instruction execution of the target code.

Examples:

To trace one instruction at the program counter, the command is:

```
tr
```

To trace 20 instructions from the program counter, the command is:

```
tr      20
```

## 2.4.24 UPDEBUG - Update the dBUG Image

## UPDEBUG

Usage:           UPDEBUG

The UPDEBUG command is used for updating the dBUG image in Flash. When updates to the MCF5204 EVS dBUG are available, the updated image is downloaded to address 0x00010000. The new image is placed into Flash using the UPDEBUG command. The user is prompted for verification before performing the operation. Use this command with extreme caution, as any error can render dBUG, and thus the board, useless!

### **2.4.25 UPUSER - Update User Code In Flash**

### **UPUSER**

Usage:           UPUSER

The UPUSER command places user code and data into space allocated for the user in Flash, the last 128K of Flash ROM. To place code and data in user Flash, the image is downloaded to address 0x00010000, and the UPUSER command issued. This commands programs the entire upper 128K of Flash. Users access this space starting at address 0xFFE20000.



## 2.4.26 VERSION - Display dBUG Version

## VERSION

Usage:           VERSION

The VERSION command display the version information for dBUG. The dBUG version number and build date are both given.

The version number is separated by a decimal, for example, “v1.1”. The first number indicates the version of the CPU specific code, and the second number indicates the version of the board specific code.

The version date is the day and time at which the entire dBUG monitor was compiled and built.

Examples:

To display the version of the dBUG monitor, the command is:

version

## 2.5 TRAP #15 Functions

An additional utility within the dBUG firmware is a function called the TRAP 15 handler. This function can be called by the user program to utilize various routines within the dBUG, to perform a special task, and to return control to the dBUG. This section describes the TRAP 15 handler and how it is used.

There are four TRAP #15 functions. These are: OUT\_CHAR, IN\_CHAR, CHAR\_PRESENT, and EXIT\_TO\_dBUG.

### 2.5.1 OUT\_CHAR

This function ( function code 0x0013) sends a character, which is in lower 8 bits of D1, to terminal.

Assembly example:

```
/* assume d1 contains the character */
move.l    #$0013,d0    Selects the function
TRAP      #15          The character in d1 is sent to terminal
```

C example:

```
void board_out_char (int ch)
{
    /* If your C compiler produces a LINK/UNLK pair for this routine,
     * then use the following code which takes this into account
     */
    #if 1
        /* LINK a6,#0 -- produced by C compiler */
        asm (" move.l    8(a6),d1");    /* put 'ch' into d1 */
        asm (" move.l    #0x0013,d0"); /* select the function */
        asm (" trap      #15");         /* make the call */
        /* UNLK a6 -- produced by C compiler */
    #else
        /* If C compiler does not produce a LINK/UNLK pair, the use
         * the following code.
         */
        asm (" move.l    4(sp),d1");    /* put 'ch' into d1 */
        asm (" move.l    #0x0013,d0"); /* select the function */
        asm (" trap      #15");         /* make the call */
    #endif
}
```

### 2.5.2 IN\_CHAR

This function (function code 0x0010) returns an input character (from terminal) to the caller . The returned character is in D1.

Assembly example:

```
move.l    #$0010,d0    Select the function
trap      #15          Make the call, the input character is in d1.
```

C example:

```
int board_in_char (void)
{
    asm (“ move.l  #0x0010,d0”);    /* select the function */
    asm (“ trap    #15”);           /* make the call */
    asm (“ move.l  d1,d0”);         /* put the character in d0 */
}
```

### 2.5.3 CHAR\_PRESENT

This function (function code 0x0014) checks if an input character is present to receive. A value of zero is returned in D0 when no character is present. A non-zero value in D0 means a character is present.

Assembly example:

```
move.l  #$0014,d0    Select the function
trap    #15          Make the call, d0 contains the response (yes/no).
```

C example:

```
int board_char_present (void)
{
    asm (“ move.l  #0x0014,d0”);    /* select the function */
    asm (“ trap    #15”);           /* make the call */
}
```

### 2.5.4 EXIT\_TO\_dBUG

This function (function code 0x0000) transfers the control back to the dBUG, by terminating the user code. The register context are preserved.

Assembly example:

```
move.l  #$0000,d0    Select the function
trap    #15          Make the call, exit to dBUG.
```

C example:

```
void board_exit_to_dbug (void)
{
    asm (“ move.l  #0x0000,d0”);    /* select the function */
    asm (“ trap    #15”);           /* exit and transfer to dBUG */
}
```

## CHAPTER 3

### HARDWARE DESCRIPTION AND RECONFIGURATION

This chapter provides a functional description of the SBC5204 board hardware. With the description given here and the schematic diagram provided at the end of this manual, the user can gain a good understanding of the board's design. In this manual, an active low signal is indicated by a "-" preceding the signal name.

#### 3.1 THE PROCESSOR AND SUPPORT LOGIC

This part of the Chapter discusses the CPU and general supporting logic on the SBC5204 board.

##### 3.1.1 The Processor

The microprocessor used in the SBC5204 is the highly integrated MCF5204, 32-bit processor. The MCF5204 uses a ColdFire processor as the core with 512 bytes of instruction cache, a UART, two Timers, 512 bytes of SRAM, one-byte wide parallel I/O port, and the supporting integrated system logic. All the registers of the core processor are 32 bits wide except for the Status Register (SR) which is 16 bits wide. This processor communicates with external devices over a 16-bit wide data bus, D0-D15. This chip can address the entire 4 G Bytes of memory space using internal chip-select logic. However, it provides only 22 address lines, A0-A21. All the processor's signals are available at J8 and J9 for off the board expansion. Refer to section 3.7 for pin assignment.

The MCF5204 has an IEEE JTAG-compatible port and BDM port. These signals are available at J7 and J9. The processor also has the logic to generate six (6) chip selects, -CS0 to -CS5.

##### 3.1.2 The Reset Logic

The reset logic provides system initialization under two modes. Under system power-up and when the RESET switch, S2 (red switch), is activated. The power-on and the RESET switch assert the processor's -RESET line to reset the processor.

U4 is used to produce both active high and low RESET. The -RESET signal is for on board devices and RESET is for the ISA Bus.

dBUG performs the following configurations of internal resources during the initialization. The instruction cache is invalidated and disabled. The Vector Base Register, VBR, points to the Flash. However, a copy of the exception table is made at address \$00000000 in SRAM. To take over an exception vector, the user places the address of the exception handler in the appropriate vector in the vector table located at \$00000000, and then points the VBR to \$00000000.

The Software Watchdog Timer is disabled, Bus Monitor enabled, and internal timers are placed in a stop condition. Interrupt controller registers initialized with unique interrupt level/priority pairs. The Port A general purpose I/O pins are configured for dedicated peripheral functions, i.e. the UART.

### **3.1.2.1 The ATS/BUSW Line**

The ATS/BUSW line can be configured to function as -ATS or BUSW after reset. If the -IRQ0 is kept low during Reset, the pin is -ATS otherwise, it is BUSW. The SBC5204 leaves the -IRQ0 high during the reset which chooses the BUSW function. If the -ATS function is needed, the user may press the ABORT button (BLACK) while pressing the RESET button (RED) which will cause the -IRQ0 to remain low when resetting the board and the -ATS function will be selected.

### **3.1.3 The Clock Circuitry**

The SBC5204 uses a 25MHZ oscillator (U3) to provide the clock to CLK pin of the processor. This clock also feeds to LSI2032 for its internal use and to produce clock for the ISA timings and MC68HC901 (1/4 system clock).

### **3.1.4 Watchdog Timer (BUS MONITOR)**

A bus cycle is initiated by the processor providing the necessary information for the bus cycle (e.g. address, data, control signals, etc.) and asserting the -CS low. Then, the processor waits for an acknowledgment (-DTACK signal) from the addressed device before it can complete the bus cycle. It is possible (due to incorrect programming) that the processor attempts to access part of the address space which physically does not exist. In this case, the bus cycle will go on for ever, since there is no memory or I/O device to provide an acknowledgment signal, and the processor will be in an infinite wait state. The MCF5204 has the necessary logic built into the chip to watch the duration of the bus cycle. If the cycle is not terminated within the preprogrammed duration the logic will internally assert Transfer Error signal. In response, the processor will terminate the bus cycle and an access fault exception (trap) will take place.

The duration of the Watchdog is selected by BMT0-1 bits in System Protection Register. The dBUG initializes this register with the value 00 which provides for 1024 system clock time-out.

### **3.1.5 Interrupt Sources**

The ColdFire family of processors can receive interrupts for seven levels of interrupt priorities. When the processor receives an interrupt which has higher priority than the current interrupt mask (in status register), it will perform an interrupt acknowledge cycle at the end of the current instruction cycle. This interrupt acknowledge cycle indicates to the source of the interrupt that the request is being acknowledged and the device should provide the proper vector number to indicate where the service routine for this interrupt level is located. If the source of interrupt is not capable of providing a vector, its interrupt should be set up as autovector interrupt which directs the processor to a predefined entry into the exception table (refer to the MCF5204 User's Manual).

The processor goes to different service routine via the exception table. This table is in the Flash and the VBR points to it. However, a copy of this table is made in the RAM starting at \$00000000. To take over an exception vector, the user places the address of the exception handler in the appropriate vector in the vector table located at \$00000000, and then points the VBR to \$00000000.

The MCF5204 has four external interrupt request lines (-IRQ0, -IRQ1, -IRQ2, -IRQ3) and four internal requests from Timer1, Timer2, Software watchdog timer, and UART. Each interrupt source, external and internal, can be programmed for any priority level. In case of similar priority level, a second relative priority between 1 to 3 will be assigned.

On SBC5204, the internal Timers, Software Watchdog Timer, and UART are disabled and not used. However, the software watchdog is programmed for Level 7, priority 2 and uninitialized vector. The UART is programmed for Level 3, priority 2 and autovector. The Timers are at Level 5 with Timer 1 with priority 3 and Timer 2 with priority 2 and both for autovector.

The SBC5204 uses -IRQ0 to support the ABORT function using the ABORT switch S1 (black switch). This switch is used to force a non-maskable interrupt (level 7, priority 3) if the user's program execution should be aborted without issuing a RESET (refer to Chapter 2 for more information on ABORT). Since the ABORT switch is not capable of generating a vector in response to level seven interrupt acknowledge from the processor, the debugger programs this request for autovector mode.

The MC68HC901 reports its interrupt request on -IRQ1 line which is set for Level 1, priority 3. It uses the vectored mode for acknowledgment. The chip-select -CS3 is used to generate the -IACK signal for MC68HC901. The MC68HC901 is programmed to generate vectors \$F0 to \$FF. This should not be changed.

The -IRQ2 and -IRQ3 lines of the MCF5204 are not used on this board. However, the -IRQ2 is programmed for Level 1 with priority 1 and the -IRQ3 is programmed for Level 1 with priority 2. The user may use these lines for external interrupt request. Refer to MCF5204 User's Manual for more information about the interrupt controller.

### **3.1.6 Internal SRAM**

The MCF5204 has 512 bytes of internal memory. This memory is mapped to \$02000000 and is not used by the dBUG. It is available to the user.

### **3.1.7 The MCF5204 Registers and Memory Map**

The memory and I/O resources of the SBC5204 are divided into three groups, MCF5204 Internal, External resources, and the ISA Bus address. All the I/O registers are memory mapped.

The MCF5204 has built in logic and six Chip-select pins (-CS0, -CS1, -CS2, -CS3, -CS4, -CS5) which are used to enable external memory and I/O devices. There are eighteen (18) 32-bit registers to specify the address range, type of access, and the method of DTACK generation for each chip-select pin. These registers are programmed by dBUG to map the external memory and I/O devices.

The SBC5204 uses chip-select zero (-CS0) to enable the EPROM/Flash ROM (refer to Section 3.3.) The SBC5204 also uses -CS1 to enable the SRAM (refer to Section 3.2), -CS2 for enabling the MC68HC901, -CS3 for Interrupt acknowledge of MC68HC901, and -CS4 for ISA Bus I/O space. The SBC5204 does not use the -CS5.

The chip select mechanism of the MCF5204 allows the memory mapping to be defined based on the memory space desired (User/Supervisor, Program/Data spaces).

All the MCF5204 internal registers, configuration registers, parallel I/O port registers, DUART registers and system control registers are mapped by MBAR register at 1K-byte boundary. It is mapped to \$01000000 by dBUG. For complete map of these registers refer to the MCF5204 User's Manual.

The SBC5204 board can have up to 1M bytes of SRAM installed. The first 1M bytes are reserved for this memory. Refer to Section 3.2 for a discussion of RAM. The dBUG is programmed in two 29F010 Flash

ROM's which only occupies 256K bytes of the address space. The first 128K bytes are used by dBUG and the second half is left for user. Refer to section 3.3.

The MC68HC901 is used as dBUG serial communication, baud rate generator, and ISA Bus interrupt request. Refer to section 3.4.1.

The ISA Bus interface maps all the I/O space of the ISA bus to the MCF5204 memory at address \$04000000. Refer to section 3.6.

**TABLE 3.1. The SBC5204 memory map.**

ADDRESS RANGE	SIGNAL and DEVICE
\$00000000-\$000FFFFF <sup>1</sup>	-CS1, Up to 1M bytes of SRAM's.
\$01000000-\$010003FF	Internal Module registers
\$02000000-\$020001FF	Internal SRAM
\$03000000-\$030FFFFF	-CS2, 1M space for MC68HC901. -CS3 is used for IACK
\$04000000-\$040FFFFF	-CS4, 1M ISA Bus area
\$FFE00000-\$FFE3FFFF	-CS0, 256K bytes of Flash ROM.

<sup>1</sup> Refer to the text for more detail.

All the unused area of the memory map is available to the user.

### 3.1.8 Reset Vector Mapping

After reset, the processor attempts to get the initial stack pointer and initial program counter values from locations \$000000-\$000007 (the first eight bytes of memory space). This requires the board to have a nonvolatile memory device in this range with proper information. However, in some systems, it is preferred to have RAM starting at address \$00000000. In MCF5204, the -CS0 responds to any accesses after reset until the V-bit is set for CS0. This includes the reset vector range. Since -CS0 is connected to Flash ROM's, the Flash ROM's appear to be at address \$00000000 which provides the initial stack pointer and program counter (the first 8 bytes of the EPROM). The initialization routine, however, programs the chip-select logic and locates the Flash ROM to start at \$FFE00000 and the SRAM's to start at \$00000000.

### 3.1.9 DTACK Generation

The processor starts a bus cycle by providing the necessary information (address A1-A23, R/-W, etc.) and asserting the -CS. The processor then waits for an acknowledgment (-DTACK) by the addressed device before it can complete the bus cycle. This -DTACK is used not only to indicate the presence of a device, it also allows devices with different access time to communicate with the processor properly. The MCF5204, as part of the chip-select logic, has a built in mechanism to generate the -DTACK for all external devices which do not have the capability to generate the -DTACK on their own. The Flash ROM's and SRAM's can not generate the -DTACK. Their chip-select logic's are programmed by dBUG to generate the -DTACK internally after a preprogrammed number of wait states. In order to support the future expansion of the board, the -DTACK input of the processor is also connected to the Processor Expansion Bus, J9. This allows the expansion boards to assert this line to indicate their -DTACK to the processor. On the expansion boards, however, this signal should be generated through an open collector buffer with no pull-up resistor, a pull-up resistor is included on the board. All the -DTACK's from the expansion boards should be connected to this line.

### 3.1.10 Wait State Generator

The Flash ROM and SRAM chips on the board may require some adjustments on the cycle time of the processor to make them compatible with processor speed. To extend the CPU bus cycles for the slower devices, the chip-select logic of the MCF5204 can be programmed to generate the -DTACK after a given number of wait states. Refer to Sections 3.2 and 3.3 information about wait state requirements of SRAM's and Flash ROM's respectively.

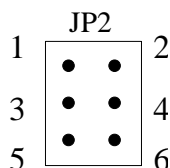
## 3.2 THE EXTERNAL SRAM

The SBC5204 has two 32-pin sockets (U11 and U12) for static RAM's. These sockets support both the 128Kx8 (such as KM681000BLP) and 512Kx8 (such as HM628512). The board may be configured for 256K and 1M bytes of SRAM's. The dBUG will detect the total memory installed on power-up.

There are two memory configuration choices:

- a. **256K bytes** - For 256K bytes, install two 128Kx8 SRAM chips in U11 and U12. The memory address range will be \$00000000-\$0003FFFF. The jumper JP2 pins 2 and 4 should be connected (default).
- b. **1M bytes** - For 1M bytes, install two 512x8 SRAM chips in U11 and U12. The memory address range will be \$00000000-\$000FFFFFFF. The jumper JP2 pins 4 and 6 should be connected.

The debugger programs the chip-select to generate one wait state for the SRAM.



## 3.3 THE EPROM/ FLASH ROM

There are two sockets for EPROM's/Flash ROM's on the SBC5204, U13 (high, even byte) and U14 (low, odd byte). These sockets support 32K, 64K, 128K, 256K, 512K, and 1M-byte EPROM's such as 27C256, 27C512, 27C010, 27C020, 27C040, and 27C080 chips for a total of up to 2M bytes. The sockets also support the Flash ROM's such as 29F010 and 29F040 which are 5-volt only devices.

If the user wishes to modify the size or the type of the memory chips, the jumpers JP2, JP3, and JP4 should be modified to accommodate different size and type of memory chips. Refer to Figure 3.1 for jumper selection.

The board is shipped with two 29F010, 128K-byte, FLASH ROM's for a total of 256K bytes. The first 128K of the Flash contains dBUG firmware. The second half (last 128K) is available to the user. The high byte (even address) chip is installed in U13 socket and the low byte (odd address) chip is installed in U14 socket. The chip-select signal generated by the MCF5204 (-CS0) enables both chips.

The MCF5204 chip-select logic can be programmed to generate the -DTACK for -CS0 signal after a certain number of wait states. The dBUG programs this parameter to three wait-states.

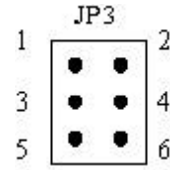
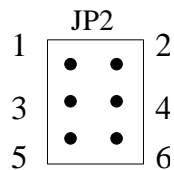


#### JP3 Configuration

MEMORY TYPE	JUMPER SETUP
FLASH ROM	Connect 3 to 5 and 4 to 6 (default)
EPROM	Connect 1 to 3 and 2 to 4

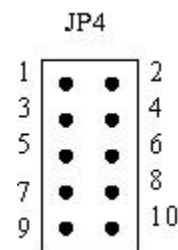
#### JP2 Configuration

MEMORY TYPE	JUMPER SETUP
FLASH ROM	Connect 3 to 5 (default)
EPROM	Connect 1 to 3



#### JP4 Configuration for EPROM

MEMORY SIZE	JUMPER SETUP
27C256 (256K EPROM)	5 to 7 and 6 to 8
27C512 (512K EPROM)	7 to 9 and 6 to 8
27C010 (1M EPROM)	3 to 5 and 7 to 9 4 to 6 and 8 to 10
27C020 (2M EPROM)	3 to 5 and 7 to 9 4 to 6 and 8 to 10
27C040 (4M EPROM)	3 to 5 and 7 to 9 2 to 4 and 8 to 10
27C080 (8M EPROM)	1 to 3 and 7 to 9 2 to 4 and 8 to 10



#### JP4 Configuration for FLASH ROM

MEMORY SIZE	JUMPER SETUP
29F010 (1M, Flash) and 29F040 (4M Flash)	7 to 9 and 8 to 10

Note: Only connect the pins specified. Leave the rest open.

**Figure 3.1. Jumper setup for the Flash/EPROM sockets.**

### **3.4 THE UART LOGIC**

The MCF5204 has a built in UART, This serial channel with software programmable baud rate generator is not used by the SBC5204 or dBUG and it is available to the user. The dBUG, however, programs the interrupt level for UART to Level 3, priority 2 and autovector mode of operation. The signals of this channel are available on J9 and are passed through the RS-232 driver/receiver and are available on DB-9 connector J6. Refer to the MCF5204 User's Manual for programming and the register map.

#### **3.4.1 MC68HC901**

To provide the board with one independent serial communication channel for dBUG communication with terminal or PC, an MC68HC901 is used. This device provides four timer channels (A, B, C, and D), one serial communication channel, and 8 input lines. Channel D timer is used as the baud rate generator for the serial communication channel.

The clock source for the timers is the 2.4576MHZ crystal. The clock signal to drive the MC68HC901 logic is one-fourth of the processor's clock.

The TXD (SO) signal and the RXD (SI) signal are passed through RS-232 driver/receiver and are available on J1. The eight input lines are used to report the ISA Bus interrupts (IRQ3, IRQ4, IRQ5, IRQ6, IRQ7, IRQ9, IRQ10, and IRQ11). The interrupt from MC68HC901 is reported to MCF5204 on -IRQ1 of the MCF5204. The interrupt level for the MC68HC901 is set for Level 1 with priority 3. The vectors used for MC68HC901 are \$F0 to \$FF. It generates 16 vectors. This should not be changed.

The -CS2 is used to access the MC68HC901 internal registers, it is mapped to \$03000000. The -CS3 is programmed to generate an Interrupt Acknowledge signal to drive the -IACK of the MC68HC901. Refer to MC68HC901 User's Manual for functional description and the programming model.

### **3.5 THE PARALLEL I/O Port**

The MCF5204 has one 8-bit parallel port. All the pins have dual functions. They can be configured as I/O or their alternate function via the Pin Assignment register. PA0/A20 and PA1/A21 are available on J8 and the rest are available on J9. User may use them based on the application. However, A20 will be used by 8M EPROM's if they are installed. Otherwise A20 and A21 can be changed to I/O pin. For more information on this refer to MCF5204 User's Manual from Motorola. The dBUG programs these pins for their dedicated peripheral functions.

### **3.6 THE ISA BUS LOGIC**

The SBC5204 includes the necessary logic, drivers, and the connector (P1) to allow the use of off-the-shelf ISA Bus I/O cards. The slot can be used with 8- or 16-bit ISA cards. Due to architectural differences between ISA and ColdFire buses, all accesses to the ISA bus must be 16-bits. In addition, for byte accessing, even ISA-space addresses are located starting at \$04000000, and odd ISA-space addresses are located starting at \$04010000. For example, consider 4 sequential registers starting at ISA-space address \$320. Their ColdFire addresses become, in order, \$04000320, \$04010320, \$04000322, and \$04010322.

The main purpose for this setup is to allow the use of Ethernet card (NE2000 compatible) to facilitate network down load, refer to chapter 2 for network download command (DN). The dBUG driver only accepts 100% NE2000 compatible cards.

The ISA Bus interrupt request lines IRQ3, IRQ4, IRQ5, IRQ6, IRQ7, IRQ9, IRQ10, and IRQ11 are connected to I0 to I7 of the MC68HC901. The requested interrupt is then routed to -IRQ1 of the MCF5204.

### 3.7 THE CONNECTORS AND THE EXPANSION BUS

There are ten connectors on the SBC5204 which are used to connect the board to external I/O devices and or expansion boards. This section provides a brief discussion and the pin assignments of the connectors.

#### 3.7.1 The Terminal Connector J1

The SBC5204 uses a 9-pin D-sub female connector J1 for connecting the board to a terminal or a PC with terminal emulation software. The available signals are a working subset of the RS-232C standard. Table 3.2 shows the pin assignment.

**TABLE 3.2. The J1 (TERMINAL) Connector pin assignment.**

PIN NO.	DIRECTION	SIGNAL NAME
1	Output	Data Carrier Detect (shorted to 4 & 6)
2	Output	Receive data
3	Input	Transmit data
4	Input	Data Terminal Ready (shorted to 1 & 6)
5		Signal Ground
6	Output	Data Set Ready (shorted to 1 & 4)
7	Input	Request to Send (shorted to 8)
8	Output	Clear to Send (shorted to 7)
9		Not Used

#### 3.7.2 The ISA Bus Auxiliary Power Connector J2

The ISA Bus requires +/-12 and -5 as well as +5 volts supply. Since they are not always needed the connector used for these is a simple burg connector. Table 3.3 shows the Pin assignment for J2.

**TABLE 3.3. The J2 Connector pin assignment.**

PIN NUMBER	SIGNAL NAME
1	+12 Volts
2	Ground
3	-12 Volts
4	-5 Volts

### 3.7.3 The Power Supply Connectors J3 and J4

The SBC5204 needs +5 volts supply (less than an Amp.). The power can be +5 Volts regulated *or* +7.5 to +12 Volts DC (regulated or unregulated) which utilizes the on board regulator U9. Jumper JP1 (Table 3.6) makes the selection between +5 Volts regulated and the +7.5-12 Volts supply. If pins 1 and 2 are connected, the board needs external +5 Volts regulated supply. If pins 2 and 3 are connected, then a DC supply of +7.5 to +12 volts may be used. In either case, the power may be connected to the board through J3 (2.1mm power jack) or the J4 two-contact lever actuated terminal block. On J3 the center pin (pin 1) is the plus supply and the body (pin 3) is the ground. On J4 the Red handle (pin 1) is the plus supply and the black handle (pin 2) is the ground. Tables 3.4 and 3.5 show the Pin assignment for J3 and J4.

**TABLE 3.4. The J3 Connector pin assignment.**

PIN NUMBER	SIGNAL NAME
1 (center pin)	Plus Supply
2 (body)	Ground

**TABLE 3.5. The J4 Connector pin assignment.**

PIN NUMBER	SIGNAL NAME
1	Plus Supply
2	Ground

**TABLE 3.6. The Jumper JP1.**

Jumper Pins	Selection
1 to 2	regulated +5 Volts
2 to 3	+7.5 to +12 regulated or unregulated (default)

### 3.7.4 The Programming Connector J5

The J5 connector is used to program the ispLSI2032. This Connector is not a user connector.

**TABLE 3.7. The J5 Connector Pin Assignment.**

PIN NO.	SIGNAL NAME
1	+5 Volts
2	-SDO
3	-SDI
4	-ISPEN
5	No Connect (key)
6	-MODE
7	GND
8	SCLK

### 3.7.5 The Auxiliary Serial Communication Connector J6

The MCF5204 has a built-in UART. This channel is not used by the SBC5204 dBUG and it is available to the user. The signals of this channel are available on J9 and they are also run through RS-232 driver/receivers and are available on J6. The available signals form a working subset of the RS-232C standard. Table 3.8 shows the pin assignment for J6.

**TABLE 3.8. The J6 Connector pin assignment.**

PIN NO.	DIRECTION	SIGNAL NAME
1	Output	Connected to pin 6 and 8
2	Output	Receive Data
3	Input	Transmit Data
4		No connect
5		Signal Ground
6	Output	Connected to 1 and 8
7	Input	Clear to Send
8	Output	Request to Send (connected to 1 & 6)
9		Not Used

### 3.7.6 The Debug Connector J7

The MCF5204 does have background Debug Port, Real-Time Trace Support, and Real-Time Debug Support. The necessary signals are available at connector J7. Table 3.9 shows the pin assignment.

### 3.7.7 The Processor Expansion Bus J8 and J9

All the processors signals are available on two bus headers J8 and J9 for future expansion. Although these signals are not buffered, they can drive at least one TTL load with some having more than one TTL load capability. User may refer to the data sheets for the major parts and the schematic at the end of this manual to obtain an accurate loading capability. All the primary signals to/from the processor needed for expansion are available on J8. Secondary signals (less likely to be used) and I/O signals are available on J9. Therefore, a single 50-wire flat ribbon cable with the IDC connectors may be used for most of future expansions. Tables 3.10 and 3.11 show the pin assignment for J8 and J9 respectively.

**TABLE 3.9. The J7 Connector pin assignment.**

PIN NO.	SIGNAL NAME
1	No Connect
2	-BKPT
3	Ground
4	DSCLK
5	Ground
6	No Connect
7	-RESET
8	DSI
9	+5 Volts
10	DSO
11	Ground
12	MTMOD2/PST3
13	MTMOD1/PST2
14	MTMOD0/PST1
15	-HIZ/PST0
16	DDAT3
17	DDAT2
18	DDAT1
19	DDAT0
20	Ground
21	MTMOD3
22	No Connect
23	Ground
24	CLK
25	+5 Volts
26	No Connect

**TABLE 3.10. The J8 Connector pin assignment.**

PIN NO.	SIGNAL NAME
1	A0
2	D0
3	A1
4	D1
5	A2
6	D2
7	A3
8	D3
9	A4
10	D4
11	A5
12	D5
13	A6
14	D6
15	A7
16	D7
17	A8
18	D8
19	A9
20	D9
21	A10
22	D10
23	A11
24	D11
25	A12
26	D12
27	A13
28	D13
29	A14
30	D14
31	A15
32	D15
33	A16
34	+5 Volts
35	A17
36	Ground
37	A18
38	-CS2
39	A19
40	-CS3
41	A20
42	-CS4
43	A21
44	-CS5
45	+5 Volts
46	-RE
47	-UDS
48	-WE
49	Ground
50	-LDS

**Table 3.11. The J9 Connector pin assignment.**

PIN NO.	SIGNAL NAME
1	TCLK
2	TIN
3	DSCLK
4	TOUT
5	DSI
6	TXD
7	DSO
8	RXD
9	-BKPT
10	-RTS
11	+5 Volts
12	-CTS
13	Ground
14	+5 Volts
15	DDATA0
16	Ground
17	DDATA1
18	-IRQ0
19	DDATA2
20	-IRQ1
21	DDATA3
22	-IRQ2
23	+5 Volts
24	-IRQ3
25	Ground
26	Ground
27	MTMOD0/PST1
28	-CS0
29	MTMOD1/PST2
30	-HIZ/PST0
31	MTMOD2/PST3
32	BUSW
33	MTMOD3
34	-DTACK
35	-RESET
36	+5 Volts
37	Ground
38	-CS1
39	CLK
40	No Connect

### **3.7.8 The ISA Bus Connector P1**

The SBC5204 can utilize the ISA Bus 16-bit I/O cards. The P1 connector is ISA Bus compatible connector. Table 3.12 shows the pin assignment.



**TABLE 3.12. The P1 Connector pin assignment.**

PIN NO.	SIGNAL NAME	PIN NO.	SIGNAL NAME
1	GND	2	IOCHK*
3	RESET	4	SD7
5	+5V	6	SD6
7	IRQ9	8	SD5
9	-5V	10	SD4
11	DRQ2	12	SD3
13	-12V	14	SD2
15	ZWS*	16	SD1
17	+12V	18	SD0
19	GND	20	IOCHRDY
21	SMFMW*	22	AEN
23	SMFMR*	24	SA19
25	IOW*	26	SA18
27	IOR*	28	SA17
29	DACK3*	30	SA16
31	DRQ3	32	SA15
33	DACK1*	34	SA14
35	DRQ1	36	SA13
37	REFSH	38	SA12
39	SYSCLK	40	SA11
41	IRQ7	42	SA10
43	IRQ6	44	SA9
45	IRQ5	46	SA8
47	IRQ4	48	SA7
49	IRQ3	50	SA6
51	DACK2*	52	SA5
53	TC	54	SA4
55	BALE	56	SA3
57	+5V	58	SA2
59	OSC	60	SA1
61	GND	62	SA0
63	MEMCS16*	64	SBHE*
65	IOCS16	66	LA23
67	IRQ10	68	LA22
69	IRQ11	70	LA21
71	IRQ12	72	LA20
73	IRQ15	74	LA19
75	IRQ14	76	LA18
77	DACK0*	78	LA17
79	DRQ0	80	MEMB*
81	DACK5*	82	MEMW*
83	DRQ5	84	SD8
85	DACK6*	86	SD9
87	DRQ6	88	SD10
89	DACK7*	90	SD11
91	DRQ7	92	SD12
93	+5V	94	SD13
95	MASTER*	96	SD14
97	GND	98	SD15

### 3.8 THE SBC5204 JUMPERS

There are a total of four jumpers on the SBC5204 board to configure the board for different setup. Table 3.13 shows what these jumpers are for and the section where more information can be found.

**TABLE 3.13. The SBC5204 Jumpers.**

Jumper No.	Function (section)
JP1	Power Supply Selection, (section 3.7.3)
JP2	RAM and EPROM size selection (section 3.2 and 3.3)
JP3	Flash/ EPROM selection (section 3.3)
JP4	Flash/EPROM size selection (section 3.3)

## Appendix A

### A.1 Configuring dBUG for Network Downloads

dBUG has the ability to perform downloads over an Ethernet network using the Trivial File Transfer Protocol, TFTP. Prior to using this feature, several parameters are required for network downloads to occur. The information that is required and the steps for configuring dBUG are described below.

#### A1.1 Required Network Parameters

For performing network downloads, dBUG needs six parameters; four are network-related, and two are download-related. The parameters are listed below, with the dBUG designation following in parenthesis.

All computers connected to an Ethernet network running the IP protocol need three network-specific parameters. These parameters are:

- Internet Protocol, IP, address for the computer (client IP),
- IP address of the Gateway for non-local traffic (gateway IP), and
- Network netmask for flagging traffic as local or non-local (netmask).

In addition, the dBUG network download command requires the following three parameters:

- IP address of the TFTP server (server IP),
- Name of the file to download (filename),
- Type of the file to download (filetype of S-record, COFF, Elf, or Image).

Your local system administrator can assign a unique IP address for the board, and also provide you the IP addresses of the gateway, netmask, and TFTP server. Fill out the lines below with this information.

Client IP:	____.____.____.____	(IP address of the board)
Server IP:	____.____.____.____	(IP address of the TFTP server)
Gateway:	____.____.____.____	(IP address of the gateway)
Netmask:	____.____.____.____	(Network netmask)

#### A.1.2 Configuring dBUG Network Parameters

Once the network parameters have been obtained, dBUG must be configured. The following commands are used to configure the network parameters.

```
set client <client IP>
set server <server IP>
set gateway <gateway IP>
set netmask <netmask>
```

For example, the TFTP server is named 'santafe' and has IP address 123.45.67.1. The board is assigned the IP address of 123.45.68.15. The gateway IP address is 123.45.68.250, and the netmask is 255.255.255.0. The commands to dBUG are:

```
set client 123.45.68.15
set server 123.45.67.1
```

```
set gateway 123.45.68.250
set netmask 255.255.255.0
```

The last step is to inform dBUG of the name and type of the file to download. Prior to giving the name of the file, keep in mind the following.

Most, if not all, TFTP servers will only permit access to files starting at a particular sub-directory. (This is a security feature which prevents reading of arbitrary files by unknown persons.) For example, SunOS uses the directory /tftp\_boot as the default TFTP directory. When specifying a filename to a SunOS TFTP server, all filenames are relative to /tftp\_boot. As a result, you normally will be required to copy the file to download into the directory used by the TFTP server.

A default filename for network downloads is maintained by dBUG. To change the default filename, use the command:

```
set filename <filename>
```

When using the Ethernet network for download, either S-record, COFF, Elf, or Image files may be downloaded. A default filetype for network downloads is maintained by dBUG as well. To change the default filetype, use the command:

```
set filetype <srecord|coff|elf|image>
```

Continuing with the above example, the compiler produces an executable COFF file, 'a.out'. This file is copied to the /tftp\_boot directory on the server with the command:

```
rcp a.out santafe:/tftp_boot/a.out
```

Change the default filename and filetype with the commands:

```
set filename a.out
set filetype coff
```

Finally, perform the network download with the 'dn' command. The network download process uses the configured IP addresses and the default filename and filetype for initiating a TFTP download from the TFTP server.

### **A.1.3 Troubleshooting Network Problems**

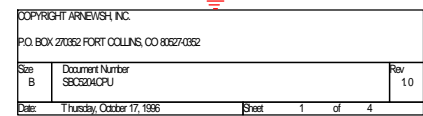
Most problems related to network downloads are a direct result of improper configuration. Verify that all IP addresses configured into dBUG are correct. This is accomplished via the 'show' command.

Using an IP address already assigned to another machine will cause dBUG network download to fail, and probably other severe network problems. Make certain the client IP address is unique for the board.

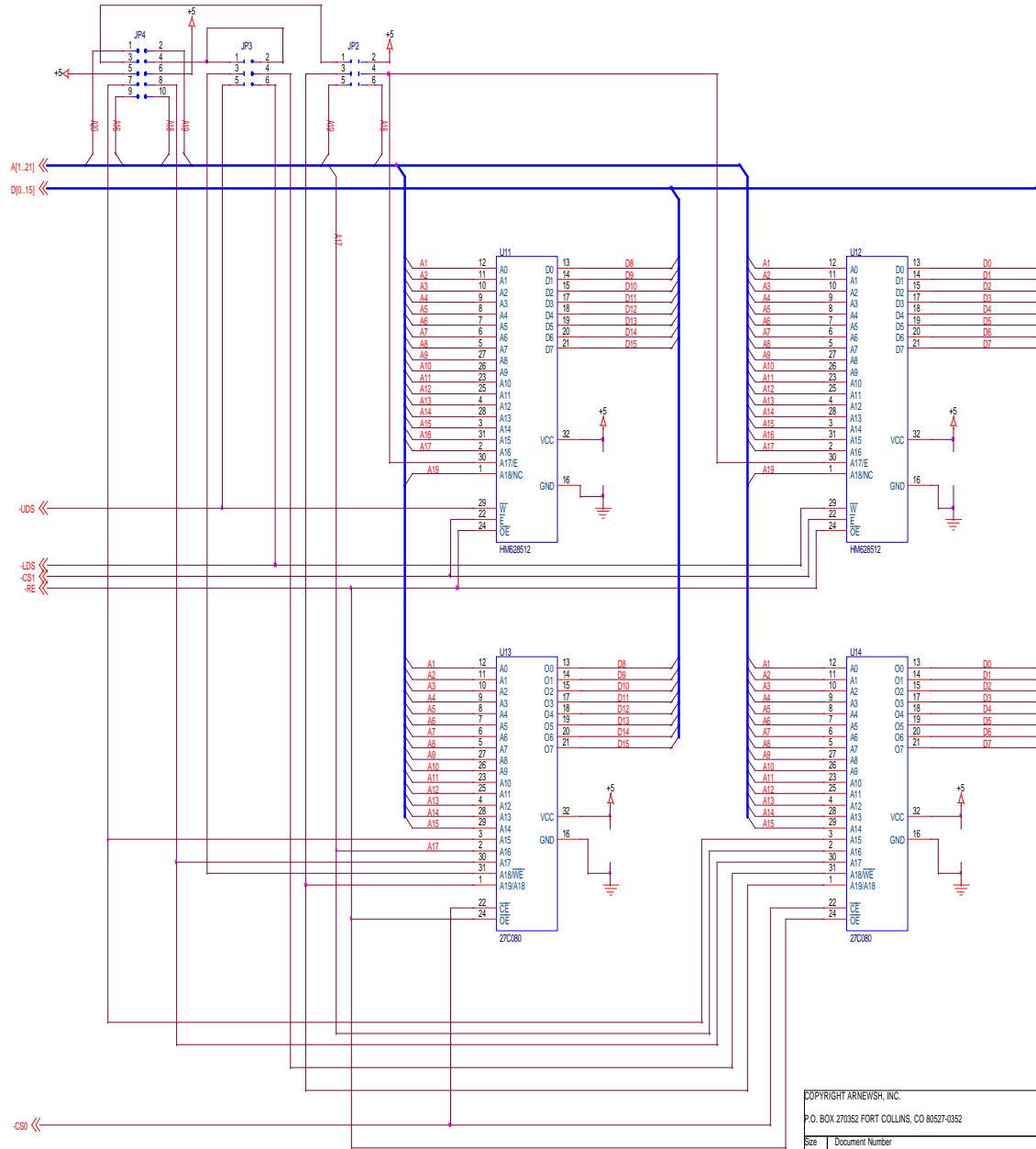
Check for proper insertion or connection of the network cable. Are status LEDs lit indicating that network traffic is present?

Check for proper configuration and operation of the TFTP server. Most Unix workstations can execute a command named 'tftp' which can be used to connect to the TFTP server as well. Is the default TFTP root directory present and readable?

If 'ICMP\_DESTINATION\_UNREACHABLE' or similar ICMP message appears, then a serious error has occurred. Reset the board, and wait one minute for the TFTP server to time out and terminate any open connections. Verify that the IP addresses for the server and gateway are correct.



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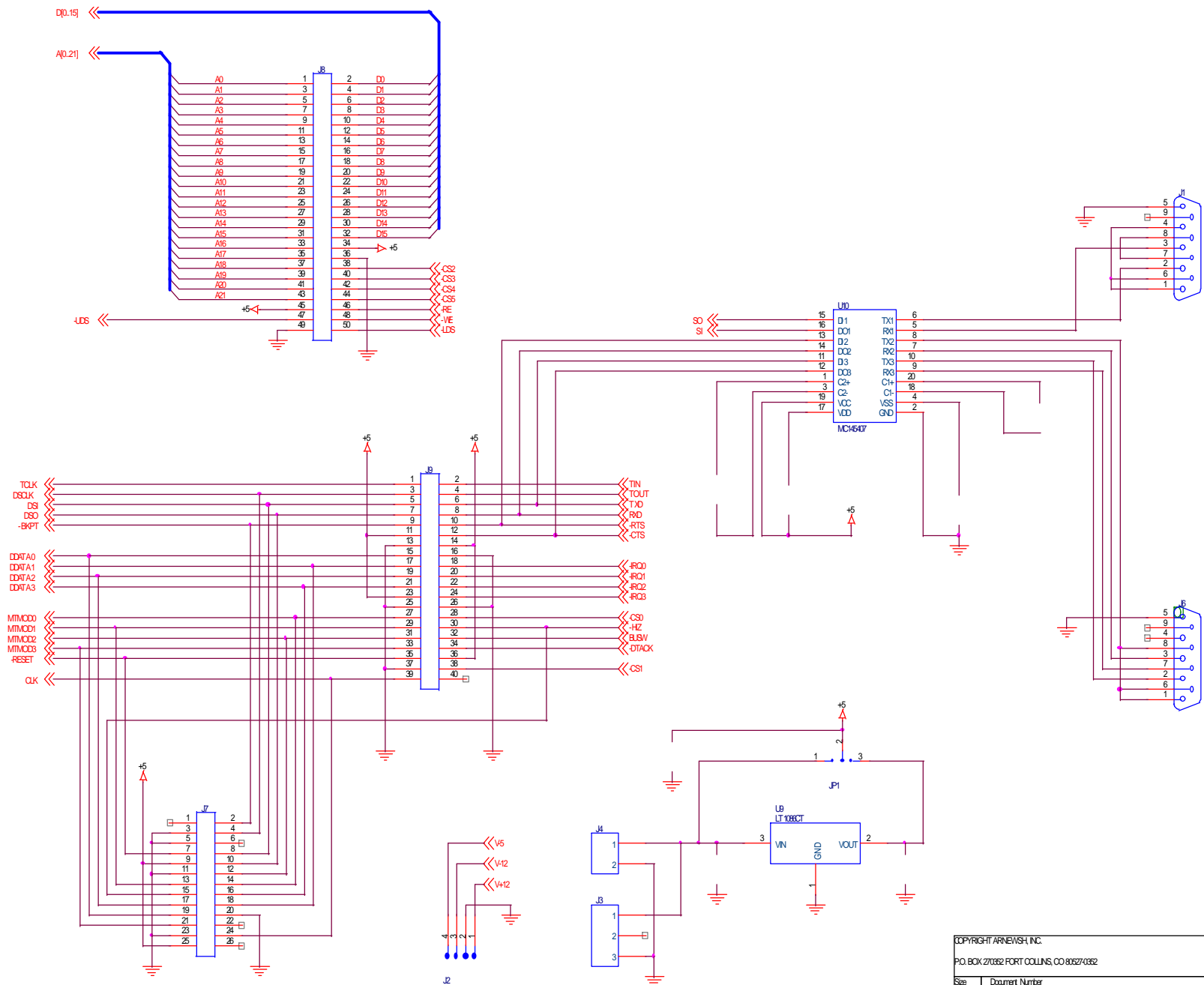


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